



**CCSDS**

The Consultative Committee for Space Data Systems

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## Recommendation for Space Data System Standards

# ORBIT DATA MESSAGES

PROPOSED STANDARD

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## FOREWORD

This document is a Recommended Standard for Orbit Data Messages (ODMs) and has been prepared by the Consultative Committee for Space Data Systems (CCSDS). The set of orbit data messages described in this Recommended Standard is the baseline concept for trajectory representation in data interchange applications that are cross-supported between Agencies of the CCSDS.

This Recommended Standard establishes a common framework and provides a common basis for the interchange of orbit and orbit-relevant data. It allows implementing organizations within each Agency to proceed coherently with the development of compatible derived standards for the flight and ground systems that are within their cognizance. Derived Agency standards may implement only a subset of the optional features allowed by the Recommended Standard and may incorporate features not addressed by this Recommended Standard.

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- Space and Upper Atmosphere Research Commission (SUPARCO)/Pakistan.
- Swedish Space Corporation (SSC)/Sweden.
- United States Geological Survey (USGS)/USA.

## DOCUMENT CONTROL

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CCSDS 502.0-B-1	Orbit Data Messages, Issue 1	September 2004	Original issue, superseded
CCSDS <del>502.0-P-</del> <del>2.38-P2.39</del>	ORBIT DATA MESSAGES, Proposed Standard, Issue <del>3P2.39</del>	<del>24</del> <del>November</del> <del>2018</del> <del>DRAFT</del> <del>December</del> <del>2019</del>	Current issue: – changes from the original issue are documented in ANNEX K
EC 1	Editorial Change 1		Corrects erroneous cross references and table of contents entries; corrects typographical anomaly in annex D; updates informative references to current issues in ANNEX K, Section K2
CCSDS 502.0.R-2, Cor. 1	Technical Corrigendum 1		Corrects/clarifies text; updates references [1] and [4] to current issues in 0.
CCSDS <del>502.0-P-</del> <del>2.38-P2.39</del>	Orbit Comprehensive Message SANA Registry for ODM Keyword values		Added Orbit Comprehensive Message (OCM) and transitioned ODM keyword values to SANA registry

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# 1 INTRODUCTION

## 1.1 PURPOSE AND SCOPE

This Orbit Data [MessageMessages](#) (ODM) Recommended Standard specifies four standard message formats for use in transferring spacecraft orbit information between space agencies and commercial or governmental spacecraft operators: the Orbit Parameter Message (OPM), the Orbit Mean-Elements Message (OMM), the Orbit Ephemeris Message (OEM) and the Orbit Comprehensive Message (OCM). Such exchanges are used for:

- a) pre-flight planning for tracking or navigation support;
- b) scheduling tracking support;
- c) carrying out tracking operations (sometimes called metric predicts);
- d) performing orbit comparisons;
- e) carrying out navigation operations such as orbit propagation and orbit reconstruction;
- f) assessing mutual physical and electromagnetic interference among satellites orbiting the same celestial body (currently primarily Earth, Moon, and Mars);
- g) performing orbit conjunction (collision avoidance) studies; and
- h) developing and executing collaborative maneuvers to mitigate interference or enhance mutual operations.

This Recommended Standard includes sets of requirements and criteria that the message formats have been designed to meet. For exchanges where these requirements do not capture the needs of the participating agencies and satellite operators, another mechanism may be selected.

The Orbit Data [MessageMessages](#) (ODM) [standard](#) is an international standard published under the auspices of CCSDS and International Standards Organization (ISO) Technical Committee 20, Subcommittee 13, developed jointly and in concert with the ISO TC20/SC14. As such, this CCSDS standard is also properly labeled as ISO 26900.

The recommended Orbit Data Message format is ASCII (reference [3]).

This ODM document describes both ‘Keyword = Value Notation’ (or KVN) as well as Extensible Markup Language (XML, reference [4]) formatted messages. Selection of KVN or XML format should be specified in an ICD.

NOTE – As currently specified, an OPM, OMM, or OEM file is to represent orbit data for a single spacecraft and the OCM is to represent orbit data for either a single spacecraft or single parent spacecraft of a parent/child spacecraft deployment scenario. It is possible that the architecture may support multiple spacecraft per file; this could be considered in the future.

## 1.2 APPLICABILITY

The rationale behind the design of each orbit data message is described in ANNEX I and may help the application engineer to select a suitable message. Definition of the orbit accuracy underlying a particular orbit message is outside of the scope of this Recommended Standard and should be specified via Interface Control Document (ICD) between data exchange participants (or specified via COMMENT sections in the message itself). Applicability information specific to each orbit data message format appears in sections 3, 4, and 5, as well as in I2.4.

This Recommended Standard is applicable only to the message format and content, but not to its transmission. The transmission of the message between agencies and operators is outside the scope of this document and should be specified in the ICD.

Description of the message formats based on the use of Extensible Markup Language (XML) is detailed in ~~an integrated XML schema document for all Navigation Data Message Recommended Standards. (See reference [4].)~~Section 8.

## 1.3 RATIONALE

This update to version 2 of the Orbit Data Messages adds a fourth message type (OCM) based on collaboration of the CCSDS Navigation Working Group and the ISO Technical Committee 20, Subcommittee 14, Working Group 3 (ISO TC20/SC14/WG3). A full list of the changes in this document is located in ANNEX K.

## 1.4 DOCUMENT STRUCTURE

Section 0 provides a brief overview of the CCSDS-recommended Orbit Data Message types, the Orbit Parameter Message (OPM), Orbit Mean-Elements Message (OMM), Orbit Ephemeris Message (OEM) and the Orbit Comprehensive Message (OCM).

Section 3 provides details about the structure and content of the OPM.

Section 4 provides details about the structure and content of the OMM.

Section 5 provides details about the structure and content of the OEM.

Section 6 provides details about the structure and content of the OCM.

Section 7 discusses the syntax considerations of the set of Orbit Data Messages (OPM, OMM, OEM and OCM).

[Section 8 provides details on the XML instantiations of the OPM, OMM, OEM and OCM.](#)

Following the principal content of the document, there are a number of annexes, both normative and informative, to guide the ODM user.

## 1.5 DEFINITIONS

For the purposes of this document, the following definitions apply:

- a) the word ‘agencies’ may also be construed as meaning ‘satellite operators’ or ‘satellite service providers’;
- b) the word ‘participant’ denotes an entity that has the ability to acquire or broadcast navigation messages and/or radio frequencies, for example, a spacecraft, a tracking station, a tracking instrument, or an agency/operator;
- c) the notation ‘n/a’ signifies ‘not applicable’;
- d) depending on context, the term ‘ODM’ may be used to refer to this document, or may be used to refer collectively to the OPM, OMM, OEM and OCM messages.
- e) An 'observation' is a unique measurement set of a satellite’s state from a single sensor configuration at a single time (e.g. azimuth from a single sensor at a single time).
- f) A 'sensor track' is a set of observations within **MINUTES** a specified number of minutes for the same object, observed by the same sensor configuration, where each observation is within a specified number of minutes (which is dependent on the orbit regime of the object) of the other observations in the track (e.g. a set of 10 two-way transponder range measurements from the same sensor using the same transponder on the satellite), where the number of minutes could alternately be defined as the time between start and stop of the measurement “session” or signal modulation that enables metric tracking.

## 1.6 NOMENCLATURE

The following conventions apply for the normative specifications in this Manual:

- a) the words ‘shall’ and ‘must’ imply a binding and verifiable specification;
- b) the word ‘should’ implies an optional, but desirable, specification;
- c) the word ‘may’ implies an optional specification;
- d) the words ‘is’, ‘are’, and ‘will’ imply statements of fact.

NOTE – These conventions do not imply constraints on diction in text that is clearly informative in nature.

## 1.7 REFERENCES

The following documents contain provisions which, through reference in this text, constitute provisions of this Recommended Standard. At the time of publication, the editions indicated were valid. All documents are subject to revision, and users of this Recommended Standard are encouraged to investigate the possibility of applying the most recent editions of the

documents indicated below. The CCSDS Secretariat maintains a register of currently valid CCSDS Recommended Standards.

- [1] *Time Code Formats*. Recommendation for Space Data System Standards, CCSDS 301.0-B-4. Blue Book. Issue 4. Washington, D.C.: CCSDS, November 2010.
- [2] *United Nations Office of Outer Space Affairs satellite designator/index, searchable at* <<http://www.unoosa.org/oosa/osoindex> >
- [3] *Information Technology—8-Bit Single-Byte Coded Graphic Character Sets—Part 1: Latin Alphabet No. 1*. International Standard, ISO/IEC 8859-1:1998. Geneva: ISO, 1998.
- [4] *XML Specification for Navigation Data Messages*. Recommendation for Space Data System Standards, CCSDS 505.0-B-1. Blue Book. Issue 1. Washington, D.C.: CCSDS, December 2010.
- [5] Paul V. Biron and Ashok Malhotra, eds. *XML Schema Part 2: Datatypes*. 2nd Edition. W3C Recommendation. N.p.: W3C, October 2004. <<http://www.w3.org/TR/2001/REC-xmlschema-2-20010502/>>
- [6] *IEEE Standard for Binary Floating-Point Arithmetic*. IEEE Std 754-1985. New York: IEEE, 1985.
- [7] Henry S. Thompson, et al. eds. *XML Schema Part 1: Structures*. 2nd ed. W3C Recommendation. N.p.: W3C, October 2004.
- [8] CCSDS 503.0-PB-1.0-4, Tracking Data Message, ~~January 2011~~ November 2007.
- [9] CCSDS 504.0-PB-1.5, Attitude Data Message, ~~October 2011~~ May 2008.
- [10] SANA Navigation Working Group Registry:  
[https://sanaregistry.org/r/navigation\\_standard\\_normative\\_annexes](https://sanaregistry.org/r/navigation_standard_normative_annexes)
- [11] SANA Registry of Organizations: <https://sanaregistry.org/r/organizations>
- [12] SANA Registry of Orbit Centers: [https://sanaregistry.org/r/orbit\\_centers](https://sanaregistry.org/r/orbit_centers)
- [13] SANA Registry of Time Systems: [https://sanaregistry.org/r/time\\_systems](https://sanaregistry.org/r/time_systems)
- [14] SANA Registry of Celestial Body Reference Frames:  
[https://sanaregistry.org/r/celestial\\_body\\_reference\\_frames](https://sanaregistry.org/r/celestial_body_reference_frames)
- [15] SANA Registry of Orbit-Relative Reference Frames:  
[https://sanaregistry.org/r/orbit\\_relative\\_reference\\_frames](https://sanaregistry.org/r/orbit_relative_reference_frames)

- [16] SANA Registry of Spacecraft and Attitude Control Reference Frames:  
[https://sanaregistry.org/r/spacecraft\\_reference\\_frames](https://sanaregistry.org/r/spacecraft_reference_frames)
- [17] SANA Registry of Orbital Elements: [https://sanaregistry.org/r/orbital\\_elements](https://sanaregistry.org/r/orbital_elements)
- [18] SANA Registry of Covariance Representations:  
[https://sanaregistry.org/r/orbital\\_covariance\\_matrix\\_types](https://sanaregistry.org/r/orbital_covariance_matrix_types)
- [19] SANA Registry of Atmosphere Models: [https://sanaregistry.org/r/atmosphere\\_models](https://sanaregistry.org/r/atmosphere_models)
- [20] SANA Registry of Gravity Models: [https://sanaregistry.org/r/gravity\\_models](https://sanaregistry.org/r/gravity_models)
- [21] SANA Registry of Object Types: [https://sanaregistry.org/r/orbital\\_covariance\\_matrix\\_types](https://sanaregistry.org/r/orbital_covariance_matrix_types)
- [22] SANA Registry of Operational Status of Space Object:  
[https://sanaregistry.org/r/operational\\_status](https://sanaregistry.org/r/operational_status)
- [23] SANA Registry of Orbit Averaging Techniques: [https://sanaregistry.org/r/orbit\\_averaging](https://sanaregistry.org/r/orbit_averaging)
- [24] SANA Registry of Orbit Types: [https://sanaregistry.org/r/orbit\\_types](https://sanaregistry.org/r/orbit_types)

## 2 OVERVIEW

### 2.1 ORBIT DATA MESSAGE TYPES

#### 2.2 ORBIT PARAMETER MESSAGE (OPM)

An OPM specifies the position and velocity of a single object at a specified epoch. Optionally, osculating Keplerian elements may be provided. This message is suited to exchanges that (1) involve automated interaction and/or human interaction, and (2) do not require high-fidelity dynamic modeling.

The OPM requires the use of a propagation technique to determine the position and velocity at times different from the specified epoch, leading to a higher level of effort for software implementation than for the OEM. A 6x6 position/velocity covariance matrix that may be used in the propagation process is optional.

The OPM allows for modeling of any number of maneuvers (as both finite and instantaneous events) and simple modeling of solar radiation pressure and atmospheric drag.

The OPM also contains an optional covariance matrix which reflects the uncertainty of the orbit state.

Though primarily intended for use by computers, the attributes of the OPM also make it suitable for applications such as exchanges by email, FAX or voice, or applications where the message is to be frequently interpreted by humans.

#### 2.3 ORBIT MEAN-ELEMENTS MESSAGE (OMM)

An OMM specifies the orbital characteristics of a single object at a specified epoch, expressed in mean Keplerian elements. This message is suited to exchanges that (1) involve automated interaction and/or human interaction, and (2) do not require high-fidelity dynamic modeling. Such exchanges may be inter-agency exchanges, or ad hoc exchanges among satellite operators when interface control documents have not been negotiated. Ad hoc interactions usually involve more than one satellite, each satellite controlled and operated by a different operating authority.

The OMM includes keywords and values that can be used to generate canonical NORAD Two Line Element Sets (TLEs) to accommodate the needs of heritage users (see reference [M-43]).

The OMM also contains an optional covariance matrix which reflects the uncertainty of the mean Keplerian elements. This information may be used to determine contact parameters that encompass uncertainties in predicted future states of orbiting objects of interest.

This message is suited for directing antennas and planning contacts with satellites. It is not recommended for assessing mutual physical or electromagnetic interference among Earth-orbiting spacecraft, developing collaborative maneuvers, or propagating precisely the orbits of

active satellites, inactive man-made objects, and near-Earth debris fragments. It is not suitable for numerical integration of the governing equations.

Though primarily intended for use by computers, the attributes of the OMM also make it suitable for applications such as exchanges by email, FAX or voice, or applications where the message is to be frequently interpreted by humans.

## 2.4 ORBIT EPHEMERIS MESSAGE (OEM)

An OEM specifies the position and velocity of a single object at multiple epochs contained within a specified time range. The OEM is suited to exchanges that (1) involve automated interaction (e.g., computer-to-computer communication where frequent, fast automated time interpretation and processing is required), and (2) require higher fidelity or higher precision dynamic modeling than is possible with the OPM.

The OEM allows for dynamic modeling of any number of gravitational and non-gravitational accelerations. The OEM requires the use of an interpolation technique to interpret the position and velocity at times different from the tabular epochs.

The OEM also contains an optional covariance matrix which reflects the uncertainty of the orbit solution used to generate states in the ephemeris.

## 2.5 ORBIT COMPREHENSIVE MESSAGE (OCM)

An OCM specifies position and velocity of either a single object or an en masse parent/child deployment scenario stemming from a single object. The OCM aggregates and extends OPM, OEM and OMM content in a single comprehensive hybrid message (file) and offers the following additional capabilities:

- Optional Earth Orientation (UT1 and UTC) at a nearby (relevant) reference epoch;
- Optional Leap second specification
- Optional area cross-sections for drag, SRP perturbations modeling.
- Optional spacecraft dimensions and orientation information for collision probability estimation
- Optional perturbations model specification;
- Optional maneuver specification (impulsive or finite burn);
- Optional orbit states (specified using one or more of Cartesian and orbit elements and reference frames) for a single or parent object at either a single epoch or as a time history (ephemeris);
- Optional orbit determination data and metrics;
- Optional covariance matrix of selectable/arbitrary order for a single or parent object at either a single epoch or as a time history (ephemeris) which reflects the uncertainty of the orbit solution or ~~Monte Carlo~~ simulation used to obtain the nominal states in the orbit state(s);
- Optional covariance content options (e.g. Cartesian 3x3, 6x6, 7x7, or any combination of order, reference frame and orbit elements)

- Optional State Transition Matrix specification;
- ~~Optional Ephemeris Compression (EC) specification via polynomials;~~

The OCM simultaneously emphasizes flexibility and message conciseness by offering extensive optional content while minimizing mandatory content. The OCM is well-suited for exchanges that (1) involve automated interaction (e.g., computer-to-computer communication where frequent, fast automated time interpretation and processing is required), and (2) involve regular orbit data transfer for numerous objects (e.g. 200,000) using minimal network bandwidth, disk storage and quantity of files. The OCM allows the user, in a single message/file, to either embed high-fidelity orbit propagation into an ephemeris time history (akin to the OEM ephemeris), or specify orbital states which can be propagated with supplied perturbations model parameters (akin to OPM content), or both.

## 2.6 EXCHANGE OF MULTIPLE MESSAGES

For a given object, multiple OPM, OMM, or OEM messages may be provided in a message exchange session to achieve ephemeris fidelity requirements, whereas a single, self-contained OCM ~~is typically~~may be sufficient. If ephemeris information for multiple objects is to be exchanged, then multiple OPM, OMM, OEM or OCM files must be used, with the exception that the OCM supports parent/child deployment scenario specifications in a single message.

## 2.7 DEFINITIONS

Definitions of time systems, reference frames, planetary models, maneuvers and other fundamental topics related to the interpretation and processing of state vectors and spacecraft ephemerides are provided in reference [M-1].

### 3 ORBIT PARAMETER MESSAGE (OPM)

#### 3.1 GENERAL

**3.1.1** Orbit information may be exchanged between two participants by sending a state vector (see reference [M-1]) for a specified epoch using an Orbit Parameter Message (OPM). The message recipient must have an orbit propagator available that is able to propagate the OPM state vector to compute the orbit at other desired epochs. For this propagation, additional ancillary information (spacecraft properties such as mass, area, and maneuver planning data, if applicable) may be included with the message.

**3.1.2** Osculating Keplerian elements and Gravitational Coefficient may be included in the OPM in addition to the Cartesian state to aid the message recipient in performing consistency checks. If any Keplerian element is included, the entire set of elements must be provided.

**3.1.3** If participants wish to exchange mean element information, then the Orbit Mean-Elements Message (OMM) or Orbit Comprehensive Message (OCM) should be the selected message type. (See sections 4 and 6.)

**3.1.4** The use of the OPM is best applicable under the following conditions:

- a) an orbit propagator consistent with the models used to develop the orbit data should be available at the receiver's site;
- b) the receiver's modeling of gravitational forces, solar radiation pressure, atmospheric drag, and thrust phases (see reference [M-1]) should fulfill accuracy requirements established between the exchange partners.

**3.1.5** The OPM shall be a plain text file consisting of orbit data for a single object.

**3.1.6** The OPM file-naming scheme should be agreed to on a case-by-case basis between the exchange partners, and should be documented in an ICD. The method of exchanging OPMs should be decided on a case-by-case basis by the exchange partners and documented in an ICD.

NOTE – Detailed syntax rules for the OPM are specified in section 7.

#### 3.2 OPM CONTENT/STRUCTURE

##### 3.2.1 GENERAL

The OPM shall be represented as a combination of the following:

- a) a header;
- b) metadata (data about data);
- c) data; and
- d) optional comments (explanatory information).

### 3.2.2 OPM HEADER

3.2.2.1 Table 3-1 specifies for each header item:

- a) the keyword to be used;
- b) a short description of the item;
- c) examples of allowed values; and
- d) whether the item is mandatory or optional.

3.2.2.2 Only those keywords shown in table 3-1 shall be used in an OPM header.

**Table 3-1: OPM Header**

Keyword	Description	Examples of Values	Mandatory
CCSDS_OPM_VERS	Format version in the form of 'x.y', where 'y' is incremented for corrections and minor changes, and 'x' is incremented for major changes.	2.0	Yes
COMMENT	Comments (allowed in the OPM Header only immediately after the OPM version number). (See 7.7 for formatting rules.)	<del>COMMENT</del> —This is a comment	No
CREATION_DATE	File creation date/time in UTC. (For format specification, see 7.5.10)	2001-11-06T11:17:33 2002-204T15:56:23Z	Yes
ORIGINATOR	Creating agency or operator. Select from the accepted set of values indicated in ANNEX B, Section B1 <del>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del>	CNES, ESOC, GSFC, GSOC, JPL, JAXA, INTELSAT, USAF, INMARSAT	Yes

### 3.2.3 OPM METADATA

Table 3-2 specifies for each metadata item:

- a) the keyword to be used;
- b) a short description of the item;
- c) examples of allowed values; and
- d) whether the item is mandatory or optional.

3.2.3.1 Only those keywords shown in table 3-2 shall be used in OPM metadata.

NOTE – For some keywords (OBJECT\_NAME, OBJECT\_ID) there are no definitive lists of authorized values maintained by a control authority; the references listed in 1.7 are the best known sources for authorized values to date. For the TIME\_SYSTEM and REF\_FRAME keywords, see ANNEX B, Section B3 and Section B4 respectively, for guidance and a link to the approved set of values.

**Table 3-2: OPM Metadata**

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Examples of Values	Mandatory
COMMENT	Comments (allowed at the beginning of the OPM Metadata). (See 7.7 for formatting rules.)	<del>COMMENT</del> —This is a comment	No
MESSAGE_ID	ID that uniquely identifies a message from a given originator. -The format and content of the message identifier value are at the discretion of the originator.	OPM 201113719185 ABC-12_34	No
<del>MESSAGE_CLASSIF</del>	<del>User defined free text classification of this OCM</del>	<del>FOUO</del>	<del>No</del>
OBJECT_NAME	Spacecraft name for which the orbit state is provided. While there is no CCSDS-based restriction on the value for this keyword, it is recommended to use names from the UN Office of Outer Space Affairs designator index (reference <del>Error! Reference source not found.;</del> [2], which include Object name and international designator of the participant.	EUTELSAT W1 MARS PATHFINDER STS 106 NEAR	Yes
OBJECT_ID	Object identifier of the object for which the orbit state is provided. There is no CCSDS-based restriction on the value for this keyword, but <del>it is recommended that</del> values <u>should</u> be the international spacecraft designator as published in the UN Office of Outer Space Affairs designator index (reference <del>Error! Reference source not found.;</del> [2]). Recommended values have the format YYYY-NNNP {PP}, where: YYYY = Year of launch. NNN = Three digit serial number of launch in year YYYY (with leading zeros). P{PP} = At least one letter for the identification of the part brought into space by the launch.  In cases where the asset is not listed in the UN Office of Outer Space Affairs designator index or that index format is not used, OBJECT_ID terminology should be mutually agreed in an ICD.	2000-052A 1996-068A 2000-053A 1996-008A	Yes

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

<p>CENTER_NAME</p>	<p><b>Origin of <u>the orbit</u> reference frame</b>, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, or another <u>reference frame center (such as a spacecraft. <del>Select, ground station, formation flying reference "chief" spacecraft, etc.</del></u></p> <p><u>Natural bodies shall be selected</u> from the accepted set of values indicated in <del>ANNEX B</del> ANNEX B, Section <del>B2 (and note B2.</del></p> <p><u>For spacecraft, it is recommended to use either the procedure to propose a new value, if Object name or international designator of the participant as catalogued in the UN Office of Outer Space Affairs designator index (reference [2]). Alternately, the OBJECT DESIGNATOR may be used.</u></p> <p><u>For other reference frame origins, this set of existing ANNEX B values does not accommodate your particular use case).</u> field is a free text descriptor which can draw upon ground station name, etc.</p>	<p>EARTH EARTH BARYCENTER MOON SOLAR SYSTEM BARYCENTER SUN <u>ISS</u> JUPITER BARYCENTER EROS</p>	<p>Yes</p>
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Keyword	Description	Examples of Values	Mandatory
REF_FRAME	Reference frame in which the state vector and optional Keplerian element data are given. Select from the accepted set of values indicated in ANNEX B, Section B4 ( <del>and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del>	ICRF1 ITRF2000 J2000 <u>TEMEOFDATE</u>	Yes
REF_FRAME_EPOCH	Epoch of reference frame, if not intrinsic to the definition of the reference frame. (See 7.5.10 for formatting rules.)	2001-11-06T11:17:33 2002-204T15:56:23Z	No

TIME_SYSTEM	Time system used for state vector, maneuver, and covariance data (also see table 3-3). Select from the accepted set of values indicated in ANNEX B, Section B3 <del>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del>	UTC, TAI, TT, GPS, TDB, TCB	Yes
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### 3.2.4 OPM DATA

**3.2.4.1** Table 3-3 provides an overview of the six logical blocks in the OPM Data section (State Vector, Osculating Keplerian Elements, Spacecraft Parameters, Position/Velocity Covariance Matrix, Maneuver Parameters, and User Defined Parameters), and specifies for each data item:

- a) the keyword to be used;
- b) a short description of the item;
- c) the units to be used;
- d) whether the item is mandatory or optional.

**3.2.4.2** Only those keywords shown in table 3-3 shall be used in OPM data.

NOTE – Requirements relating to the keywords in table 3-3 appear after the table.

**Table 3-3: OPM Data**

Keyword	Description	Units	Mandatory
<b>State Vector Components in the Specified Coordinate System</b>			
COMMENT	(See 7.7 for formatting rules.)	n/a	No
EPOCH	Epoch of state vector & optional Keplerian elements. (See 7.5.10 for formatting rules.)	n/a	Yes
X	Position vector X-component	km	Yes
Y	Position vector Y-component	km	Yes
Z	Position vector Z-component	km	Yes
X_DOT	Velocity vector X-component	km/s	Yes
Y_DOT	Velocity vector Y-component	km/s	Yes
Z_DOT	Velocity vector Z-component	km/s	Yes
<b>Osculating Keplerian Elements in the Specified Reference Frame (none or all parameters of this block must be given.)</b>			
COMMENT	(See 7.7 for formatting rules.)	n/a	No
SEMI_MAJOR_AXIS	Semi-major axis	km	No
ECCENTRICITY	Eccentricity	n/a	No
INCLINATION	Inclination	deg	No
RA_OF_ASC_NODE	Right ascension of ascending node	deg	No
ARG_OF_PERICENTER	Argument of pericenter	deg	No
TRUE_ANOMALY or MEAN_ANOMALY	True anomaly or mean anomaly	deg	No
GM	Gravitational Coefficient (Gravitational Constant x Central Mass)	km**3/s**2	No
<b>Spacecraft Parameters</b>			
COMMENT	(See 7.7 for formatting rules.)	n/a	No
MASS	<del>S/C Mass</del> Spacecraft mass	kg	No
SOLAR_RAD_AREA	Solar Radiation Pressure Area (A <sub>R</sub> )	m**2	No
SOLAR_RAD_COEFF	Solar Radiation Pressure Coefficient (C <sub>R</sub> )	n/a	No
DRAG_AREA	Drag Area (A <sub>D</sub> )	m**2	No
DRAG_COEFF	Drag Coefficient (C <sub>D</sub> )	n/a	No
<b>Position/Velocity Covariance Matrix (6x6 Lower Triangular Form. None or all parameters of the matrix must be given. COV_REF_FRAME may be omitted if it is the same as REF_FRAME.)</b>			
COMMENT	(See 7.7 for formatting rules.)	n/a	No
COV_REF_FRAME	Reference frame in which the covariance data are given. Select from the accepted set of values indicated in ANNEX B, Sections B4 and B5 <del>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del>	<del>ICRF3</del> <del>ITRF2000</del> TOD_n/a EARTH	No
CX_X	Covariance matrix [1,1]	km**2	No
CY_X	Covariance matrix [2,1]	km**2	No
CY_Y	Covariance matrix [2,2]	km**2	No
CZ_X	Covariance matrix [3,1]	km**2	No
CZ_Y	Covariance matrix [3,2]	km**2	No
CZ_Z	Covariance matrix [3,3]	km**2	No
CX_DOT_X	Covariance matrix [4,1]	km**2/s	No
CX_DOT_Y	Covariance matrix [4,2]	km**2/s	No
CX_DOT_Z	Covariance matrix [4,3]	km**2/s	No
CX_DOT_X_DOT	Covariance matrix [4,4]	km**2/s**2	No

Keyword	Description	Units	Mandatory
CY_DOT_X	Covariance matrix [5,1]	km**2/s	No
CY_DOT_Y	Covariance matrix [5,2]	km**2/s	No
CY_DOT_Z	Covariance matrix [5,3]	km**2/s	No
CY_DOT_X_DOT	Covariance matrix [5,4]	km**2/s**2	No
CY_DOT_Y_DOT	Covariance matrix [5,5]	km**2/s**2	No
CZ_DOT_X	Covariance matrix [6,1]	km**2/s	No
CZ_DOT_Y	Covariance matrix [6,2]	km**2/s	No
CZ_DOT_Z	Covariance matrix [6,3]	km**2/s	No
CZ_DOT_X_DOT	Covariance matrix [6,4]	km**2/s**2	No
CZ_DOT_Y_DOT	Covariance matrix [6,5]	km**2/s**2	No
CZ_DOT_Z_DOT	Covariance matrix [6,6]	km**2/s**2	No
<b>Maneuver Parameters (Repeat for each maneuver. <del>None or all parameters of this block must be given.</del>)</b>			
COMMENT	(See 7.7 for formatting rules.)	n/a	No
MAN_EPOCH_IGNITION	Epoch of ignition. (See 7.5.10 for formatting rules.)	n/a	No
MAN_DURATION	Maneuver duration (If = 0, impulsive maneuver)	s	No
MAN_DELTA_MASS	Mass change during maneuver (value is < 0)	kg	No
MAN_REF_FRAME	Reference frame in which the velocity increment vector data are given. Select from the accepted set of values indicated in ANNEX B, Sections B4 and B5 <del>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del>	n/a	No
MAN_DV_1	1 <sup>st</sup> component of the velocity increment	<del>m</del> km/s	No
MAN_DV_2	2 <sup>nd</sup> component of the velocity increment	<del>m</del> km/s	No
MAN_DV_3	3 <sup>rd</sup> component of the velocity increment	<del>m</del> km/s	No
<b>User Defined Parameters (all parameters in this section must be described in an ICD).</b>			
USER_DEFINED_x	User defined parameter, where 'x' is replaced by a variable length user specified character string. Any number of user defined parameters may be included, if necessary to provide essential information that cannot be conveyed in COMMENT statements. Example: USER_DEFINED_EARTH_MODEL = WGS-84	n/a	No

**3.2.4.3** All values except Maneuver Parameters in the OPM data are ‘at epoch’, i.e., the value of the parameter at the time specified in the EPOCH keyword.

**3.2.4.4** Table 3-3 is broken into six logical blocks, each of which has a descriptive heading. These descriptive headings shall not be included in an OPM, unless they appear in a properly formatted COMMENT statement.

**3.2.4.5** If the solar radiation coefficient,  $C_R$ , is set to zero, no solar radiation pressure shall be ~~taken into account~~considered.

**3.2.4.6** If the atmospheric drag coefficient,  $C_D$ , is set to zero, no atmospheric drag shall be ~~taken into account~~considered.

**3.2.4.7** Parameters for thrust phases may be optionally given for the computation of the trajectory during or after maneuver execution (see reference [M-1] for the simplified modeling of such maneuvers). For impulsive maneuvers, MAN\_DURATION must be set to zero.

MAN\_DELTA\_MASS may be used for both finite and impulsive maneuvers; the value must be a negative number.

**3.2.4.8** Multiple sets of maneuver parameters may appear. For each maneuver, all the maneuver parameters shall be repeated in the order shown in table 3-3.

**3.2.4.9** If the OPM contains a maneuver definition, the Spacecraft Parameters section must be included.

**3.2.4.10** Values in the covariance matrix shall be expressed in the applicable reference frame (COV\_REF\_FRAME keyword), and shall be presented sequentially from upper left [1,1] to lower right [6,6], lower triangular form, row by row left to right. Variance and covariance values shall be expressed in standard double precision as related in 7.5. This logical block of the OPM may be useful for risk assessment and establishing maneuver and mission margins. The intent is to provide causal connections between output orbit data and both physical hypotheses and measurement uncertainties. These causal relationships guide operators' corrective actions and mitigations.

**3.2.4.11** A section of User Defined Parameters may be provided if necessary. In principle, this provides flexibility, but also introduces complexity, non-standardization, potential ambiguity, and potential processing errors. Accordingly, if used, the keywords and their meanings must be described in an ICD. User Defined Parameters, if included in an OPM, should be used as sparingly as possible; their use is not encouraged.

### **3.3 OPM EXAMPLES AND SUPPLEMENTARY INFORMATION**

Example OPMs and associated supplementary (non-normative) information are provided in Annex [ED](#).

## 4 ORBIT MEAN-ELEMENTS MESSAGE (OMM)

### 4.1 GENERAL

**4.1.1** Orbit information may be exchanged between two participants by sending an orbital state based on mean Keplerian elements (see reference [M-1]) for a specified epoch using an Orbit Mean-Elements Message (OMM). The message recipient must use appropriate orbit propagator algorithms in order to correctly propagate the OMM state to compute the orbit at other desired epochs.

**4.1.2** The OMM is intended to allow replication of the data content of an existing TLE in a CCSDS standard format, but the message can also accommodate other implementations of mean elements. All essential fields of the ‘de facto standard’ TLE are included in the OMM in a style that is consistent with that of the other ODMs (i.e., the OPM and OEM). From the fields in the OMM, it is possible to generate a TLE (see reference [M-32]). Programs that convert OMMs to TLEs must be aware of the structural requirements of the TLE, including the checksum algorithm and the formatting requirements for the values in the TLE. The checksum and formatting requirements of the TLE do not apply to the values in an OMM.

**4.1.3** If participants wish to exchange osculating element information, then the Orbit Parameter Message (OPM) or the Orbit Comprehensive Message (OCM) should be the selected message type. (See sections 3 and 6.)

**4.1.4** The use of the OMM is best applicable under the following conditions:

- a) an orbit propagator consistent with the models used to develop the orbit data should be run at the receiver’s site;
- b) the receiver’s modeling of gravitational forces, solar radiation pressure, atmospheric drag, etc. (see reference [M-1]), should fulfill accuracy requirements established between the exchange partners.

**4.1.5** The OMM shall be a plain text file consisting of orbit data for a single object.

**4.1.6** The OMM file-naming scheme should be agreed to on a case-by-case basis between the exchange partners, and should be documented in an ICD. The method of exchanging OMMs should be decided on a case-by-case basis by the exchange partners and documented in an ICD.

NOTE – Detailed syntax rules for the OMM are specified in section 7.

### 4.2 OMM CONTENT/STRUCTURE

#### 4.2.1 GENERAL

The OMM shall be represented as a combination of the following:

- a) a header;

- b) metadata (data about data);
- c) data; and
- d) optional comments (explanatory information).

**4.2.2 OMM HEADER**

4.2.2.1 Table 4-1 specifies for each header item:

- a) the keyword to be used;
- b) a short description of the item;
- c) examples of allowed values; and
- d) whether the item is mandatory or optional.

4.2.2.2 Only those keywords shown in table 4-1 shall be used in an OMM header.

**Table 4-1: OMM Header**

Keyword	Description	Examples of Values	Mandatory
CCSDS_OMM_VERS	Format version in the form of 'x.y', where 'y' is incremented for corrections and minor changes, and 'x' is incremented for major changes.	3.0	Yes
COMMENT	Comments (allowed in the OMM Header only immediately after the OMM version number). (See 7.7 for formatting rules.)	<del>COMMENT</del> This is a comment	No
CREATION_DATE	File creation date/time in UTC. ( For format specification, see 7.5.10.)	2001-11-06T11:17:33 2002-204T15:56:23Z	Yes
ORIGINATOR	Creating agency or operator. Select from the accepted set of values indicated in ANNEX B, Section B1 <del>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del>	CNES, ESOC, GSFC, GSOC, JPL, JAXA, INTELSAT, USAF, INMARSAT	Yes
<u>MESSAGE_ID</u>	<u>ID that uniquely identifies a message from a given originator. The format and content of the message identifier value are at the discretion of the originator.</u>	<u>OMM 201113719185</u> <u>ABC-12 34</u>	<u>No</u>

**4.2.3 OMM METADATA**

4.2.3.1 Table 4-2 specifies for each metadata item:

- a) the keyword to be used;
- b) a short description of the item;

- c) examples of allowed values; and
- d) whether the item is mandatory or optional.

**4.2.3.2** Only those keywords shown in table 4-2 shall be used in OMM metadata.

NOTE – For some keywords (OBJECT\_NAME and OBJECT\_ID there are no definitive lists of authorized values maintained by a control authority; the references listed in 1.7 are the best known sources for authorized values to date.

**Table 4-2: OMM Metadata**

Keyword	Description	Examples of Values	Mandatory
COMMENT	Comments (allowed at the beginning of the OMM Metadata). (See 7.7 for formatting rules.)	<del>COMMENT</del> —This is a comment	No
<del>MESSAGE_ID</del>	<del>ID that uniquely identifies a message from a given originator. The format and content of the message identifier value are at the discretion of the originator.</del>	<del>OMM-201113719185 ABC-12_34</del>	<del>No</del>
<del>MESSAGE_CLASSIF</del>	<del>User-defined free-text classification of this OCM</del>	<del>FOUO</del>	<del>No</del>
OBJECT_NAME	Spacecraft name for which the orbit state is provided. There is no CCSDS-based restriction on the value for this keyword, but it is recommended to use names from the UN Office of Outer Space Affairs designator index (reference [2]), which include Object name and international designator of the participant.	TelKom 2 Spaceway 2 INMARSAT 4-F2	Yes
OBJECT_ID	Object identifier of the object for which the orbit state is provided. There is no CCSDS-based restriction on the value for this keyword, but <del>it is recommended that</del> values <u>should</u> be the international spacecraft designator as published in the UN Office of Outer Space Affairs designator index (reference [2]). Recommended values have the format YYYY-NNNP{PP}, where: YYYY = Year of launch. NNN = Three digit serial number of launch in year YYYY (with leading zeros). P{PP} = At least one capital letter for the identification of the part brought into space by the launch.  In cases where the asset is not listed in the bulletin, or the UN Office of Outer Space Affairs designator index format is not used, the value should be provided in an ICD.	2005-046A 2005-046B 2003-022A	Yes

Keyword	Description	Examples of Values	Mandatory
CENTER_NAME	Origin of the <b>STM</b> reference frame, which <del>may</del> be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, <del>or another spacecraft.</del> <u>Select. Natural bodies shall be selected</u> from the accepted set of values indicated in ANNEX B, Section B2 (and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case). B2.	EARTH MARS MOON	Yes
REF_FRAME	Name of the reference frame in which the Keplerian element data are given. Select from the accepted set of values indicated in ANNEX B, Section B4 (and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).  Note: NORAD Two Line Element Sets and corresponding SGP orbit propagator ephemeris output are explicitly defined to be in the True Equator Mean Equinox of Date (TEME of Date) reference frame. Therefore, TEME of date shall be used for OMMs based on NORAD Two Line Element sets, rather than the almost imperceptibly different TEME of Epoch (see reference [M-32] or [M-43] for further details).	TEME J2000	Yes
REF_FRAME_EPOCH	Epoch of reference frame, if not intrinsic to the definition of the reference frame. (See 7.5.10 for formatting rules.)	2001-11-06T11:17:33 2002-204T15:56:23Z	No
TIME_SYSTEM	Time system used for the orbit state and covariance matrix. Select from the accepted set of values indicated in ANNEX B, Section B3 (and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).	UTC	Yes
MEAN_ELEMENT_THEORY	Description of the Mean Element Theory. Indicates the proper method to employ to propagate the state.	SGP4 DSST USM	Yes

#### 4.2.4 OMM DATA

4.2.4.1 Table 4-3 provides an overview of the five logical blocks in the OMM Data section (Mean Keplerian Elements, Spacecraft Parameters, TLE Related Parameters, Position/Velocity Covariance Matrix, and User Defined Parameters), and specifies for each data item:

- a) the keyword to be used;

- b) a short description of the item;
- c) the units to be used;
- d) whether the item is mandatory or optional.

**4.2.4.2** Only those keywords shown in table 4-3 shall be used in OMM data.

NOTE – Requirements relating to the keywords in table 4-3 appear after the table.

**Table 4-3: OMM Data**

Keyword	Description	Units	Mandatory
<b>Mean Keplerian Elements in the Specified Reference Frame</b>			
COMMENT	(See 7.7 for formatting rules.)	n/a	No
EPOCH	Epoch of Mean Keplerian elements. (See 7.5.10 for formatting rules.)	n/a	Yes
SEMI_MAJOR_AXIS or MEAN_MOTION	Semi-major axis in kilometers (preferred), or, if MEAN_ELEMENT_THEORY = SGP/SGP4, the Keplerian Mean motion in revolutions per day	km rev/day	Yes
ECCENTRICITY	Eccentricity	n/a	Yes
INCLINATION	Inclination	deg	Yes
RA_OF_ASC_NODE	Right ascension of ascending node	deg	Yes
ARG_OF_PERICENTER	Argument of pericenter	deg	Yes
MEAN_ANOMALY	Mean anomaly	deg	Yes
GM	Gravitational Coefficient (Gravitational Constant x Central Mass)	km**3/s**2	No
<b>Spacecraft Parameters</b>			
COMMENT	(See 7.7 for formatting rules.)	n/a	No
MASS	S/CSpacecraft Mass	kg	No
SOLAR_RAD_AREA	Solar Radiation Pressure Area (A <sub>R</sub> )	m**2	No
SOLAR_RAD_COEFF	Solar Radiation Pressure Coefficient (C <sub>R</sub> )	n/a	No
DRAG_AREA	Drag Area (A <sub>D</sub> )	m**2	No
DRAG_COEFF	Drag Coefficient (C <sub>D</sub> )	n/a	No
<b>TLE Related Parameters (This section is only required if MEAN_ELEMENT_THEORY=SGP/SGP4)</b>			
COMMENT	(See 7.7 for formatting rules.)	n/a	No
EPHEMERIS_TYPE	Default value = 0. (See 4.2.4.7.)	n/a	No
CLASSIFICATION_TYPE	Default value = U. (See 4.2.4.7.)	n/a	No
NORAD_CAT_ID	NORAD Catalog Number ('Satellite Number') an integer of up to nine digits. This keyword is only required if MEAN_ELEMENT_THEORY=SGP/SGP4.	n/a	No
ELEMENT_SET_NO	Element set number for this satellite. Normally incremented sequentially, but may be out of sync if it is generated from a backup source. Used to distinguish different TLEs, and therefore only meaningful if TLE-based data is being exchanged (i.e., MEAN_ELEMENT_THEORY = SGP/SGP4).	n/a	No
REV_AT_EPOCH	Revolution Number	n/a	No
BSTAR	SGP/SGP4 drag-like coefficient (in units 1/[Earth radii]). Only required if MEAN_ELEMENT_THEORY=SGP/SGP4	1/ER	No

Keyword	Description	Units	Mandatory
MEAN_MOTION_DOT	First Time Derivative of the Mean Motion (only required if MEAN_ELEMENT_THEORY = SGP)	rev/day**2	No
MEAN_MOTION_DDOT	Second Time Derivative of Mean Motion (only required if MEAN_ELEMENT_THEORY = SGP)	rev/day**3	No
Position/Velocity Covariance Matrix (6x6 Lower Triangular Form. None or all parameters of the matrix must be given. COV_REF_FRAME may be omitted if it is the same as the REF_FRAME.)			
COMMENT	(See 7.7 for formatting rules.)	n/a	No
COV_REF_FRAME	Reference frame in which the covariance data are given. Select from the accepted set of values indicated in ANNEX B, Sections B4 and B5 <del>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del>	n/a	No
CX_X	Covariance matrix [1,1]	km**2	No
CY_X	Covariance matrix [2,1]	km**2	No
CY_Y	Covariance matrix [2,2]	km**2	No
CZ_X	Covariance matrix [3,1]	km**2	No
CZ_Y	Covariance matrix [3,2]	km**2	No
CZ_Z	Covariance matrix [3,3]	km**2	No
CX_DOT_X	Covariance matrix [4,1]	km**2/s	No
CX_DOT_Y	Covariance matrix [4,2]	km**2/s	No
CX_DOT_Z	Covariance matrix [4,3]	km**2/s	No
CX_DOT_X_DOT	Covariance matrix [4,4]	km**2/s**2	No
CY_DOT_X	Covariance matrix [5,1]	km**2/s	No
CY_DOT_Y	Covariance matrix [5,2]	km**2/s	No
CY_DOT_Z	Covariance matrix [5,3]	km**2/s	No
CY_DOT_X_DOT	Covariance matrix [5,4]	km**2/s**2	No
CY_DOT_Y_DOT	Covariance matrix [5,5]	km**2/s**2	No
CZ_DOT_X	Covariance matrix [6,1]	km**2/s	No
CZ_DOT_Y	Covariance matrix [6,2]	km**2/s	No
CZ_DOT_Z	Covariance matrix [6,3]	km**2/s	No
CZ_DOT_X_DOT	Covariance matrix [6,4]	km**2/s**2	No
CZ_DOT_Y_DOT	Covariance matrix [6,5]	km**2/s**2	No
CZ_DOT_Z_DOT	Covariance matrix [6,6]	km**2/s**2	No
User Defined Parameters (all parameters in this section must be described in an ICD).			
USER_DEFINED_x	User defined parameter, where 'x' is replaced by a variable length user specified character string. Any number of user defined parameters may be included, if necessary to provide essential information that cannot be conveyed in COMMENT statements. Example: USER_DEFINED_EARTH_MODEL = WGS-84	n/a	No

**4.2.4.3** All values in the OMM are 'at epoch', i.e., the value of the parameter at the time specified in the EPOCH keyword.

**4.2.4.4** Table 4-3 is broken into five logical blocks, each of which has a descriptive heading. These descriptive headings shall not be included in an OMM, unless they appear in a properly formatted COMMENT statement.

**4.2.4.5** Values in the covariance matrix shall be expressed in the applicable reference frame (COV\_REF\_FRAME keyword if used, or REF\_FRAME keyword if not), and shall be presented sequentially from upper left [1,1] to lower right [6,6], lower triangular form, row by row left to right. Variance and covariance values shall be expressed in standard double precision as related in 7.5. This logical block of the OMM may be useful for risk assessment and establishing maneuver and mission margins.

**4.2.4.6** For operations in Earth orbit with a TLE-based OMM, some special conventions must be observed, as follows:

- The value associated with the CENTER\_NAME keyword shall be ‘EARTH’.
- The value associated with the REF\_FRAME keyword shall be ‘TEMEOFDATE’ (see ANNEX B, Section B4).
- The value associated with the TIME\_SYSTEM keyword shall be ‘UTC’.
- The format of the OBJECT\_NAME and OBJECT\_ID keywords shall be that of the UN Office of Outer Space Affairs designator index (reference [2]).
- The MEAN\_MOTION keyword must be used instead of SEMI\_MAJOR\_AXIS.

**4.2.4.7** For those who wish to use the OMM to represent a TLE, there are a number of considerations that apply with respect to precision of angle representation, use of certain fields by the propagator, reference frame, etc. Some sources suggest the coding for the EPHEMERIS\_TYPE keyword: 1=SGP, 2=SGP4, 3=SDP4, 4=SGP8, 5=SDP8. Some sources suggest the following coding for the CLASSIFICATION\_TYPE keyword: U=unclassified, S=secret. (For further information see references [M-32] and [M-43])

**4.2.4.8** Maneuvers are not accommodated in the OMM. Users of the OMM who wish to model maneuvers may use several OMM files to describe the orbit at applicable epochs.

**4.2.4.9** A section of User Defined Parameters is allowed. In principle, this provides flexibility, but also introduces complexity, non-standardization, potential ambiguity, and potential processing errors. Accordingly, if used, the keywords and their meanings must be described in an ICD. User Defined Parameters, if included in an OMM, should be used as sparingly as possible; their use is not encouraged.

### **4.3 OMM EXAMPLES AND SUPPLEMENTARY INFORMATION**

Example OMMs and associated supplementary (non-normative) information are provided in Annex FE.

## 5 ORBIT EPHEMERIS MESSAGE (OEM)

### 5.1 GENERAL

**5.1.1** Orbit information may be exchanged between two participants by sending an ephemeris in the form of a series of state vectors (Cartesian vectors providing position and velocity, and optionally accelerations) using an Orbit Ephemeris Message (OEM). The message recipient must have a means of interpolating across these state vectors to obtain the state at an arbitrary time contained within the span of the ephemeris.

**5.1.2** The OEM may be used for assessing mutual physical or electromagnetic interference among Earth-orbiting spacecraft, developing collaborative maneuvers, and representing the orbits of active satellites, inactive man-made objects, near-Earth debris fragments, etc. The OEM reflects the dynamic modeling of any users' approach to conservative and non-conservative phenomena.

**5.1.3** The OEM shall be a plain text file consisting of orbit data for a single object.

**5.1.4** The OEM file-naming scheme should be agreed to on a case-by-case basis between the participants, typically using an ICD. The method of exchanging OEMs should be decided on a case-by-case basis by the participants and documented in an ICD.

NOTE – Detailed syntax rules for the OEM are specified in section 7.

### 5.2 OEM CONTENT/STRUCTURE

#### 5.2.1 GENERAL

**5.2.1.1** The OEM shall be represented as a combination of the following:

- a) a header;
- b) metadata (data about data);
- c) ephemeris data;
- d) optional covariance matrix data; and
- e) optional comments (explanatory information).

**5.2.1.2** OEM files must have a set of minimum required sections; some may be repeated. Table 5-1 outlines the contents of an OEM.

**Table 5-1: OEM File Layout Specifications**

<b>Required Sections</b>	Header Metadata Ephemeris Data (Appropriate comments should also be included, although they are not required.)
<b>Allowable Repetitions of Sections</b>	Covariance Matrix (optional) Metadata Ephemeris Data Covariance Matrix (optional) Metadata Ephemeris Data Covariance Matrix (optional) Metadata Ephemeris Data Covariance Matrix (optional) ...etc. (Appropriate comments should also be included.)

**5.2.2 OEM HEADER**

**5.2.2.1** The OEM header assignments are shown in table 5-2, which specifies for each item:

- a) the keyword to be used;
- b) a short description of the item;
- c) examples of allowed values; and
- d) whether the item is mandatory or optional.

**5.2.2.2** Only those keywords shown in table 5-2 shall be used in an OEM header.

**Table 5-2: OEM Header**

Keyword	Description	Examples of Values	Mandatory
CCSDS_OEM_VERS	Format version in the form of 'x.y', where 'y' is incremented for corrections and minor changes, and 'x' is incremented for major changes.	3.0	Yes
COMMENT	Comments (allowed in the OEM Header only immediately after the OEM version number). (See 7.7 for formatting rules.)	COMMENT This is a comment	No
CREATION_DATE	File creation date and time in UTC. (For format specification, see 7.5.10.)	2001-11-06T11:17:33 2002-204T15:56:23	Yes
ORIGINATOR	Creating agency or operator. Select from the accepted set of values indicated in ANNEX B, Section B1 <del>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del>	CNES, ESOC, GSFC, GSOC, JPL, JAXA, INTELSAT, USAF, INMARSAT	Yes
MESSAGE_ID	<u>ID that uniquely identifies a message from a given originator. The format and content of the message identifier value are at the discretion of the originator.</u>	<u>OEM 201113719185</u> <u>ABC-12 34</u>	<u>No</u>

### 5.2.3 OEM METADATA

5.2.3.1 The OEM metadata assignments are shown in table 5-3, which specifies for each item:

- a) the keyword to be used;
- b) a short description of the item;
- c) examples of allowed values; and
- d) whether the item is mandatory or optional.

5.2.3.2 Only those keywords shown in table 5-3 shall be used in OEM metadata.

NOTE – For some keywords (OBJECT\_NAME and OBJECT\_ID) there are no definitive lists of authorized values maintained by a control authority; the references listed in 1.7 are the best known sources for authorized values to date. For the TIME\_SYSTEM and REF\_FRAME keywords, see ANNEX B, Section B3 and Section B4 respectively, for guidance and a link to the approved set of values.

5.2.3.3 A single metadata group shall precede each ephemeris data block. Multiple occurrences of a metadata group followed by an ephemeris data block may be used. Before each metadata group the string 'META\_START' shall appear on a separate line and after each metadata group (and before the associated ephemeris data block) the string 'META\_STOP' shall appear on a separate line.

**Table 5-3: OEM Metadata**

Keyword	Description	Examples of Values	Mandatory
META_START	The OEM message contains metadata, ephemeris data, and covariance data; this keyword is used to delineate the start of a metadata block within the message (metadata are provided in a block, surrounded by 'META_START' and 'META_STOP' markers to facilitate file parsing). This keyword must appear on a line by itself.	n/a	Yes
COMMENT	Comments allowed only immediately after the META_START keyword. (See 7.7 for formatting rules.)	COMMENT This is a comment.	No
<del>MESSAGE_ID</del>	<del>ID that uniquely identifies a message from a given originator. The format and content of the message identifier value are at the discretion of the originator.</del>	<del>OEM-201113719185 ABC-12_34</del>	<del>No</del>
<del>MESSAGE_CLASSIF</del>	<del>User-defined free-text classification of this OCM</del>	<del>FOUO</del>	<del>No</del>
OBJECT_NAME	The name of the object for which the ephemeris is provided. There is no CCSDS-based restriction on the value for this keyword, but it is recommended to use names from the UN Office of Outer Space Affairs designator index (reference [2]), which include Object name and international designator of the participant.	EUTELSAT W1 MARS PATHFINDER STS 106 NEAR	Yes
OBJECT_ID	Object identifier of the object for which the ephemeris is provided. There is no CCSDS-based restriction on the value for this keyword, but <del>it is recommended that</del> values <u>should</u> be the international spacecraft designator as published in the UN Office of Outer Space Affairs designator index (reference [2]). Recommended values have the format YYYY-NNNP{PP}, where: YYYY = Year of launch. NNN = Three-digit serial number of launch in year YYYY (with leading zeros). P{PP} = At least one capital letter for the identification of the part brought into space by the launch.  In cases where the asset is not listed in reference [2], or the UN Office of Outer Space Affairs designator index format is not used, the value should be provided in an ICD.	2000-052A 1996-068A 2000-053A 1996-008A	Yes

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Examples of Values	Mandatory
CENTER_NAME	<p><b>Origin of the STM reference frame</b>, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, or another <b>reference frame center (such as a spacecraft. <del>Select, ground station, formation flying reference “chief” spacecraft, etc.</del></b>)</p> <p><b>Natural bodies shall be selected</b> from the accepted set of values indicated in <b>ANNEX BANEX B, Section B2 <del>(and note B2,</del></b></p> <p><b>For spacecraft, it is recommended to use either the procedure to propose a new value, if Object name or international designator of the participant as catalogued in the UN Office of Outer Space Affairs designator index (reference [2]). Alternately, the OBJECT DESIGNATOR may be used.</b></p> <p><b>For other reference frame origins, this set of existing ANNEX B values does not accommodate your particular use case). field is a free text descriptor which can draw upon ground station name, etc.</b></p>	<p>EARTH EARTH BARYCENTER MOON SOLAR SYSTEM BARYCENTER SUN JUPITER BARYCENTER STS 106 EROS</p>	Yes
REF_FRAME	<p>Reference frame in which the ephemeris data are given. Select from the accepted set of values indicated in ANNEX B, Section B4 <b>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</b></p>	<p>ICRF3 ITRF1993 ITRF1997 ITRF2000 ITRFyyyy (template for future versions) TOD (True Equator and Equinox of Date) J2000 (Earth Mean Equator and Equinox of J2000) TDR (true of date rotating) GRC (Greenwich rotating coordinate frame, another name for TDR)</p>	Yes
REF_FRAME_EPOCH	<p>Epoch of reference frame, if not intrinsic to the definition of the reference frame. (See 7.5.10 for formatting rules.)</p>	<p>2001-11-06T11:17:33 2002-204T15:56:23Z</p>	No
TIME_SYSTEM	<p>Time system used for metadata, ephemeris and covariance data (also see table 3-3). Select from the accepted set of values indicated in ANNEX B, Section B3 <b>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</b></p>	<p>UTC, TAI, TT, GPS, TDB, TCB</p>	Yes

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Examples of Values	Mandatory
START_TIME	Start of TOTAL time span covered by ephemeris data and covariance data immediately following this metadata block. (For format specification, see 7.5.10.)	1996-12- 18T14:28:15.1172 1996-277T07:22:54	Yes
USEABLE_START_TIME USEABLE_STOP_TIME	Optional start and end of USEABLE time span covered by ephemeris data immediately following this metadata block. To allow for proper interpolation near the ends of the ephemeris data block it may be necessary, depending upon the interpolation method to be used, to utilize these keywords with values within the time span covered by the ephemeris data records as delimited by the START/STOP_TIME time tags. (For format specification, see 7.5.10.) These keywords are optional items, and thus may not be necessary, depending on the recommended interpolation method. However, it is recommended to use the USEABLE_START_TIME and USEABLE_STOP_TIME capability in all cases. The USEABLE_START_TIME time tag at a new block of ephemeris data must be greater than or equal to the USEABLE_STOP_TIME time tag of the previous block.	1996-12- 18T14:28:15.1172 1996-277T07:22:54	No
STOP_TIME	End of TOTAL time span covered by ephemeris data and covariance data immediately following this metadata block. (For format specification, see 7.5.10.)	1996-12- 18T14:28:15.1172 1996-277T07:22:54	Yes
INTERPOLATION	This keyword may be used to specify the recommended interpolation method for ephemeris data in the immediately following set of ephemeris lines. <u>PROPAGATE indicates that orbit propagation is the preferred method to obtain states at intermediate times, via either a midpoint-switching or endpoint switching approach.</u>	HERMITE LINEAR LAGRANGE PROPAGATE	No
INTERPOLATION_DEGREE	Recommended interpolation degree for ephemeris data in the immediately following set of ephemeris lines. Must be an integer value. This keyword must be used if the 'INTERPOLATION' keyword is used and set to anything other than PROPAGATE.	5 1	No
META_STOP	The OEM message contains metadata, ephemeris data, and covariance data; this keyword is used to delineate the end of a metadata block within the message (metadata are provided in a block, surrounded by 'META_START' and 'META_STOP' markers to facilitate file parsing). This keyword must appear on a line by itself.	n/a	Yes

## 5.2.4 OEM DATA: EPHEMERIS DATA LINES

**5.2.4.1** Each set of ephemeris data, including the time tag, must be provided on a single line. The order in which data items are given shall be fixed: **Epoch, X, Y, Z, X\_DOT, Y\_DOT, Z\_DOT, X\_DDOT, Y\_DDOT, Z\_DDOT**.

**5.2.4.2** The position and velocity terms shall be mandatory; acceleration terms may be provided.

**5.2.4.3** At least one space character must be used to separate the items in each ephemeris data line.

**5.2.4.4** Repeated time tags may occur in consecutive ephemeris data blocks if the STOP\_TIME of the first ephemeris data block is greater than the START\_TIME of the second ephemeris data block. Although the USEABLE\_STOP\_TIME and USEABLE\_START\_TIME of the consecutive ephemeris data blocks must not overlap (except for a possibly shared endpoint), the STOP\_TIME of the first ephemeris data block may be greater than the START\_TIME of the second ephemeris data block if the extra data is required for interpolation purposes.

**5.2.4.5** The TIME\_SYSTEM value must remain fixed within an OEM.

**5.2.4.6** The occurrence of a second (or greater) metadata block after some ephemeris data indicates that interpolation using succeeding ephemeris data with ephemeris data occurring prior to that metadata block shall not be done. This method may be used for proper modeling of propulsive maneuvers or any other source of a discontinuity such as eclipse entry or exit.

**5.2.4.7** Details about interpolation method should be specified using the INTERPOLATION and INTERPOLATION\_DEGREE keywords within the OEM. All data blocks must contain a sufficient number of ephemeris data records to allow the recommended interpolation method to be carried out consistently throughout the OEM.

## 5.2.5 OEM DATA: COVARIANCE MATRIX LINES

**5.2.5.1** A single covariance matrix data section may optionally follow each ephemeris data block.

**5.2.5.2** If present, the covariance matrix data lines in the OEM are separated from the ephemeris data by means of two new keywords: COV\_START and COVARIANCE\_STOP. The '~~COV~~COVARIANCE\_START' keyword must appear before the first line of the covariance matrix data. The 'COVARIANCE\_STOP' keyword must appear after the last line of covariance data. Each of these keywords shall appear on a line by itself with no time tags or values.

**5.2.5.3** The epoch of the navigation solution related to the covariance matrix must be provided via the 'EPOCH' keyword. The reference frame of the covariance matrix, if different from that of the states in the ephemeris, must be provided via the 'COV\_REF\_FRAME'

keyword. **NOTE: COV REF FRAME must be specified for each covariance matrix block if it is not in the same frame as the ephemeris.**

**5.2.5.4** Each row of the 6x6 lower triangular covariance matrix must be provided on a single line. The order in which data items are given shall be fixed. The elements in each row of covariates shall be defined by the order in the ephemeris data line (i.e., **X, Y, Z, X\_DOT, Y\_DOT, Z\_DOT**). The six rows of the covariance matrix contain from one to six numbers depending on what row of the matrix is being represented (first row has one element, second row has two, continuing in this fashion until the sixth row has six elements).

**5.2.5.5** At least one space character must be used to separate the items in each covariance matrix data line.

**5.2.5.6** Multiple covariance matrices may appear in the covariance matrix section; they may appear with any desired frequency (one for each navigation solution that makes up the overall ephemeris is recommended). The OEM may also contain propagated covariances, not just individual covariances associated with navigation solutions.

**5.2.5.7** If there are multiple covariance matrices in the data section, they must be ordered by increasing time tag.

### **5.3 OEM EXAMPLES AND SUPPLEMENTARY INFORMATION**

Example OEMs and associated supplementary (non-normative) information are provided in Annex **GF**.

## 6 ORBIT COMPREHENSIVE MESSAGE (OCM)

### 6.1 GENERAL DESCRIPTION

**6.1.1** Comprehensive orbit information may be exchanged between two participants by sending orbit data/content for one or more epochs using an Orbit Comprehensive Message (OCM). The OCM aggregates and extends OMM, OPM and OEM content in a single hybrid message. The OCM simultaneously emphasizes flexibility and message conciseness by offering extensive optional standardized content while minimizing mandatory content.

**6.1.2** The OCM shall be a plain text file consisting of orbit data for a single space object, or in the case of a parent/child satellite deployment scenario, a single parent object.

~~**6.1.3** The units universally used throughout the OCM are kilometers (for orbit state and covariance time histories) and m/s and  $m/s^2$  (for maneuvers), mass in kilograms and time in seconds.~~

~~**6.1.46.1.3** The OCM file-naming scheme should be agreed to on a case-by-case basis between the exchange partners, and should be documented in an ICD. The method of exchanging OCMs should be decided on a case-by-case basis by the exchange partners and documented in an ICD.~~

~~**6.1.56.1.4** Orbit information may be exchanged between two or more participants by sending an ephemeris in the form of one or more time series of orbital states (selectable as orbital elements and/or Cartesian vectors providing position and optionally velocity and accelerations) using an Orbit Comprehensive Message (OCM). If orbital states are desired at arbitrary time(s) contained within the span of the ephemeris, the message recipient **is encouraged to must** use a suitable interpolation method. For times outside of supplied orbit state time spans or if the step size between orbit states is too large to support interpolation [M-86], optional perturbations parameters can and should be included in this message and the recipient must **haveuse** a suitably-compatible orbit propagator.~~

~~**6.1.66.1.5** The OCM may be used for assessing mutual physical or electromagnetic interference among Earth-orbiting spacecraft, developing collaborative maneuvers, and representing the orbits of active satellites, inactive man-made objects, near-Earth debris fragments, etc. The OCM reflects the dynamic modeling of any users' approach to conservative and non-conservative phenomena.~~

NOTE – Detailed syntax rules for the OCM are specified in section 7.

### 6.2 OCM ~~CONTENT/STRUCTURE~~ AND OVERARCHING REQUIREMENTS

#### 6.2.1 GENERAL STRUCTURE

The OCM shall be represented as athe combination of the following elements, ordered as shownlisted in Table 6-1. ~~The ordering~~Note that while many of these~~the~~ sections ~~is mandatory.~~The order of occurrence of the OCM sections shall be fixed as shown in table 6-1.

- ~~1) one mandatory header;~~
- ~~2) one mandatory metadata section (data about data);~~
- ~~3) are optional data section(s), comprised of one or more data constituent types:~~
  - ~~a. one or more, at least one of the optional orbit state time histories data sections must be provided.~~
  - ~~b. one optional space object physical characteristics section~~
  - ~~c. one or more optional covariance time histories~~
  - ~~d. one or more optional State Transition Matrix (STM) time histories~~
  - ~~e. one or more optional maneuver data section(s)~~
  - ~~f. one optional perturbations section~~
  - ~~g. one optional orbit determination data section~~
  - ~~h. one optional user defined section containing data and supplemental comments (explanatory information).~~

**Table 6-1: OCM File Layout and Ordering Specification**

<b>Section</b>	<b>Content</b>	<b><u>Mandatory?</u></b>
<del>Mandatory</del> Header	<del>Header</del> <u>A single header of the message.</u>	<u>Yes</u>
<del>Mandatory</del> Metadata	<del>Metadata</del> ( <del>Informational comments recommended but not required.</del> ) <u>A single metadata section (data about data).</u>	<u>Yes</u>
<del>Optional</del> Orbit Data <del>Section(s)</del>	<del>Optional:</del> One or more orbit state time histories ( <del>each</del> consisting of one or more orbit states)).	<u>No</u>
<del>Optional</del> Space Object Physical Description	<del>Optional:</del> <u>A single space object physical characteristics section.</u>	<u>No</u>
<del>Optional</del> Covariance Data <del>Section(s)</del>	<del>Optional:</del> One or more covariance time histories (each consisting of one or more covariance matrices)).	<u>No</u>
<del>Optional</del> State Transition Matrix Data <del>Section(s)</del>	<del>Optional:</del> One or more state transition matrix time histories (each consisting of one or more state transition matrices)).	<u>No</u>
<del>Optional</del> Maneuver <del>Section(s)</del> Data	<del>Optional:</del> <u>One or more</u> maneuver specifications for either impulsive or finite burns or acceleration profiles.	<u>No</u>
<del>Optional</del> Perturbations <del>Section</del> Parameters	<del>Optional:</del> <u>A single perturbations parameters section.</u>	<u>No</u>
<del>Optional</del> Orbit Determination <del>Section</del> Data	<del>Optional:</del> <u>A single orbit determination data section.</u>	<u>No</u>
<del>Optional</del> user-defined parameters	<del>Optional:</del> <u>One or more user-defined parameters sections containing data and supplemental comments (explanatory information).</u>	<u>No</u>

**6.2.1 GENERAL REQUIREMENTS**

The following requirements apply to all OCM sections and content:

**6.2.1.1** The order of occurrence of OCM keywords shall be fixed as listed in the keyword value tables in the OCM section descriptions.

**6.2.1.2** Within each section, note that keywords labeled as “mandatory” in the corresponding tables denotes those keywords that must be included in this section if that particular section is included. If a keyword is labeled as mandatory and is not provided, the default value specified in the corresponding table entry shall be used.

**6.2.1.3** All time-tags may be specified by either a relative time (e.g., 20157.26) measured in seconds with respect to the specified epoch time (e.g., the overarching default value EPOCH\_TZERO) or an absolute time (e.g., 2018-11-13T11:13:20.5Z as formatted in Section 7.5.10) epoch time.

**6.2.1.4** Within an OCM data block, all time-tags must adhere to either relative time, or absolute time, for the entirety of that data block. It is not permitted to mix relative and absolute time within the same data block.

**6.2.1.5** Time tags of information within ordered sequences of OCM sections may be separated by uniform or non-uniform step size(s).

**6.2.1.6** Time tags of one OCM section may or may not match those of another OCM section.

**6.2.2 OCM HEADER**

**6.2.2.1** Table 6-2 specifies the keywords for each header item.

**6.2.2.2** Only those keywords shown in table 6-2 shall be used in an OCM header.

**6.2.2.3** The order of occurrence of these OCM header keywords shall be fixed as shown in table 6-2.

**Table 6-2: OCM Header**

Keyword	Description	Examples of Values	Mandatory
CCSDS_OCM_VERS	Format version in the form of 'x.y', where 'y' is incremented for corrections and minor changes, and 'x' is incremented for major changes-	3.0	Yes
COMMENT	Comments (a contiguous set of one or more comment lines <del>are</del> allowed in the OCM Header only immediately after the OCM version number). (See 7.7 for formatting rules-))	<del>COMMENT</del> —This is a comment	No
CREATION_DATE	File creation date/time in UTC. (For format specification, see 7.5.10-))	2001-11-06T11:17:33 2002-204T15:56:23Z	Yes
ORIGINATOR	<u>Creating agency or operator. Select from the accepted set of values indicated in ANNEX B, Section B1</u>	<u>CNES, ESOC, GSFC, GSOC, JPL, JAXA, INTELSAT, USAF, INMARSAT</u>	Yes
MESSAGE_ID	<u>Free text field containing an ID that uniquely identifies a message from this message originator. The format and content of the message identifier value are at the discretion of the originator</u>	<u>OCM 201113719185</u> <u>ABC-12_34</u>	No
CLASSIFICATION	<u>User-defined free-text message classification/caveats of this OCM. It is recommended that selected values be pre-coordinated between exchanging entities by mutual agreement.</u>	<u>SBU</u> <u>“Operator-proprietary data; secondary distribution not permitted”</u>	No

**6.2.3 OCM METADATA**

**6.2.3.1** Table 6-3 specifies the metadata keywords. Only those keywords shown in table 6-3 shall be used in OCM metadata.

~~6.2.3.2 The “OCM Metadata” section is mandatory; “mandatory” in the context of Table 6-3 denotes those keywords which must be included in this section.~~

~~6.2.3.3~~ **6.2.3.2** Each metadata section must begin with keyword META\_START and end with keyword META\_STOP.

~~6.2.3.4 Each of these keywords shall appear on a line by itself.~~

~~6.2.3.5~~ **6.2.3.3** At most, only one metadata section shall appear in in the entire scope of an OCM.

6.2.3.4 The order of occurrence of these OCM metadata keywords shall be fixed as shown in table 6-3.

NOTE – For some keywords (OBJECT\_NAME, OBJECT\_IDDESIGNATOR) there are no definitive lists of authorized values maintained by a control authority; the references listed in Section 1.7 are the best known sources for authorized values to date.

NOTE 2 – While specification of OBJECT\_NAME, OBJECT\_IDDESIGNATOR and INTERNATIONAL\_DESIGNATOR are individually optional, **it is recommended that** one of these three keywords **should** be supplied.

NOTE 3 – Metadata fields which are relied upon by the subsequent optional OCM message subtypes (orbit state time histories, maneuver data, etc.) are designated as such in the right-hand column of **Table 6-3**.

Table 6-3.

~~6.2.3.61.1.1.1~~ The order of occurrence of these OCM metadata keywords shall be fixed as shown in table 6-3.

~~6.2.3.7~~ When selecting a value for the OBJECT\_TYPE keyword, note that per [M-17], objects in the space environment can be categorized in two broad categories: The ones which can be traced back to a launch event and for which the nature can be identified, and the ones for which this is not (yet) possible. With these two major categories in mind, when OBJECT\_TYPE is specified, it shall categorize objects into one of the following nine categories:

- ~~PL:~~ A payload, which is a space object that is designed to perform specific function in space excluding launch functionality. This includes operational satellites as well as calibration objects.
- ~~PM:~~ A payload mission-related object, which is a space object that is released as space debris, which served a purpose for the function of a payload. Common examples include covers for optical instruments or astronaut tools.
- ~~PF:~~ A payload fragmentation debris, which is a space object that is fragmented or unintentionally released from a payload as space debris for which their genesis can be traced back to a unique event. This class includes objects created when a payload explodes or when it collides with another object.
- ~~PD:~~ Payload debris, which is a space object that is fragmented or unintentionally released from a payload as space debris for which the genesis is unclear but orbital or physical properties enable a correlation with a source.
- ~~RB:~~ Rocket body, which is a space object that is designed to perform launch-related functionality. This includes the various orbital stages of launch vehicles, but not payloads that release smaller payloads themselves.
- ~~RM:~~ Rocket mission related object, which is a space object that is intentionally released as space debris that served a purpose for the function of a rocket body. Common examples include shrouds and engines.

- ~~RF~~: Rocket fragmentation debris, which is a space object that is fragmented or unintentionally released from a rocket body as space debris for which their genesis can be traced back to a unique event. This class includes objects created when a launch vehicle explodes.
- ~~RD~~: Rocket debris, which is a space object that is fragmented or unintentionally released from a rocket body as space debris for which the genesis is unclear but orbital or physical properties enable a correlation with a source.
- ~~UI~~: Unidentified, where a space object cannot be traced back to a launch, its nature cannot be determined, or it is intentionally unspecified by the message creator.

~~6.2.3.8~~ When selecting a value for the ORBIT\_TYPE keyword, [M-17], orbits shall be characterized as follows:

- ~~EGO~~: Extended Geostationary Orbit,  $37948 < a < 46380$  km,  $e < 0.25$ ,  $i < 25^\circ$
- ~~ESO~~: Escape Orbits
- ~~GHO~~: GEO-superGEO, Crossing Orbits  $31570 < hp < 40002$  km,  $40002$  km  $< ha$
- ~~GEO~~: Geosynchronous Earth Orbit, with  $i > 3^\circ$ ,  $35586 < hp < 35986$  km,  $35586 < ha < 35986$  km
- ~~GSO~~: GeoStationary Orbit, with  $3^\circ < i < 25^\circ$ ,  $35586 < hp < 35986$  km,  $35586 < ha < 35986$  km
- ~~GTO~~: Geosynchronous Transfer Orbit,  $i < 90^\circ$ ,  $hp < 2000$  km,  $31570 < ha < 40002$  km
- ~~HAO~~: High Altitude Earth Orbit,  $40002$  km  $< hp$ ,  $40002$  km  $< ha$
- ~~HEO~~: Highly Eccentric Earth Orbit,  $hp < 31570$  km,  $40002$  km  $< ha$
- ~~IGO~~: Inclined Geosynchronous Orbit,  $37948 < a < 46380$  km,  $e < 0.25$ ,  $25^\circ < i < 180^\circ$
- ~~LEO~~: Low Earth Orbit,  $hp < 2000$  km,  $ha < 2000$  km
- ~~LMO~~: LEO-MEO Crossing Orbits,  $hp < 2000$  km,  $2000 < ha < 31570$  km
- ~~MEO~~: Medium Earth Orbit,  $2000 < hp < 31570$  km,  $2000 < ha < 31570$  km
- ~~MGO~~: MEO-GEO Crossing Orbits,  $2000 < hp < 31570$  km,  $31570 < ha < 40002$  km
- ~~NSO~~: Navigation Satellites Orbit  $50^\circ < i < 70^\circ$ ,  $18100 < hp < 24300$  km,  $18100 < ha < 24300$  km
- ~~UFO~~: Undefined Orbit

**Table 6-3: OCM Metadata**

Keyword	Description	Default (if any)	Examples of Values	Mandatory	Any OCM sections relying upon this field ?
<del>META_START</del> <del>COMMENT</del>	<del>Comments (a contiguous set of one or more comment lines are allowed in the OCM Metadata section; see 7.7 for comment formatting rules). Start of the metadata section</del>	n/a	<del>COMMENT This is a comment</del>	<del>Yes</del> <u>n/a</u>	No
<del>COMMENT</del> <del>ORIGINATOR</del>	<del>Creating agency or operator. Select from the accepted set of values indicated in ANNEX B, Section B1 (and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case). Comments (a contiguous set of one or more comment lines is allowed in the OCM Metadata section; see 7.7 for comment formatting rules).</del>	<del>n/a</del>	<del>This is a comment</del> <del>CNES, ESOC, GSFC, GSOC, JPL, JAXA, INTELSAT, USAF, INMARSAT</del>	<del>Yes</del> <u>No</u>	No
ORIGINATOR-_POC	Free text field containing originator or programmatic Point-of-Contact (PoC) for OCM	<u>n/a</u>	Mr. Rodgers	No	No
ORIGINATOR-_POSITION	Free text field containing contact position of the originator PoC	<u>n/a</u>	Flight Dynamics Mission Design Lead	No	No
ORIGINATOR_PHONE	Free text field containing originator PoC phone number	<u>n/a</u>	+49615130312123456789 <u>01</u>	No	No
ORIGINATOR_ADDRESS	Free text field containing originator PoC address information for OCM creator (suggest email, website, or physical address, etc.)	<u>n/a</u>	JOHN.DOE@ SOMEWHERE. <del>NET</del> <u>ORG</u>	No	No
TECH _ORG	Creating agency or operator (value should be drawn from the abbreviated "Organizations" name column of the SANA registry at <a href="https://www.sanaregistry.org/r/organizations">https://www.sanaregistry.org/r/organizations</a> )		NASA	No	No
TECH _POC	Free text field containing technical Point-of-Contact (PoC) for OCM		Maxwell Smart	No	No
TECH _POSITION	Free text field containing contact position of the technical PoC		Flight Dynamics Mission Design Lead	No	No
TECH _PHONE	Free text field containing technical PoC phone number		+49615130312	No	No
TECH_ADDRESS	Free text field containing technical PoC address information for OCM creator (suggest email, website, or physical address, etc.)		JOHN.DOE@ SOMEWHERE. <del>NET</del> <u>ORG</u>	No	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Default (if any)	Examples of Values	Mandatory	Any OCM sections relying upon this field ?
<del>MESSAGE_ID</del>	<del>Free text field containing an ID that uniquely identifies a message from this message originator. The format and content of the message identifier value are at the discretion of the originator.</del>		<del>OCM 201113719185 ABC-12_34</del>	<del>No</del>	<del>No</del>
<del>PREVIOUS_MESSAGE_ID</del>	Free text field containing an ID that uniquely identifies the previous message from this message originator for this particular space object. The format and content of the message identifier value are at the discretion of the originator.  <u>NOTE: One can provide the previous message ID without supplying the PREVIOUS_MESSAGE_EPOCH, and vice versa</u>		OCM 201113719184 ABC-12_33	No	No
<del>NEXT_MESSAGE_ID</del>	Free text field containing an ID that uniquely identifies the next message from this message originator for this particular space object. The format and content of the message identifier value are at the discretion of the originator.  <u>NOTE: One can provide the next message ID without supplying the NEXT_MESSAGE_EPOCH, and vice versa</u>		OCM 201113719186 ABC-12_35	No	No
<del>PREVIOUS_MESSAGE_EPOCH</del>	<del>Creation epoch of the previous message from this originator for this particular space object. For format specification, see 7.5.9. The time scale of this epoch is controlled via the "DEF_TIME_SYSTEM" keyword.</del>		<del>2001-11-06T11:17:33</del>	<del>No</del>	<del>No</del>
<del>NEXT_MESSAGE_EPOCH</del>	<del>Creation epoch of the next message from this originator for this particular space object. The format and content of the message identifier value are at the discretion of the originator.</del>		<del>2001-11-06T11:17:33</del>	<del>No</del>	<del>No</del>
<del>MESSAGE_CLASSIF</del>	<del>User defined free text classification of this OCM</del>		<del>FOUO</del>	<del>No</del>	<del>No</del>
ATT_MSG_LINK	Free text field containing <del>comma-separated file name(s)</del> <u>a unique identifier</u> of Attitude Data Message(s) that are linked (relevant) to this Orbit Data Message		ADM_MSG_35132.txt <u>ATT ID 0572</u>	No	No
CDM_MSG_LINK	Free text field containing <del>comma-separated file name(s)</del> <u>a unique identifier</u> of Conjunction Data Message(s) that are linked (relevant) to this Orbit Data Message		CDM_MSG_35132.txt <u>CDM ID 8257</u>	No	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Default (if any)	Examples of Values	Mandatory	Any OCM sections relying upon this field ?
PRM_MSG_LINK	Free text field containing <del>comma-separated file name(s)</del> <u>a unique identifier</u> of Pointing Request Message(s) that are linked (relevant) to this Orbit Data Message		PRM_MSG_35132.txt <u>PRM_ID 6897</u>	No	No
RDM_MSG_LINK	Free text field containing <del>comma-separated file name(s)</del> <u>a unique identifier</u> of Reentry Data Message(s) that are linked (relevant) to this Orbit Data Message		RDM_MSG_35132.txt <u>RDM_ID 1839</u>	No	No
TDM_MSG_LINK	Free text field containing <del>comma-separated file name(s)</del> <u>a unique identifier</u> of Tracking Data Message(s) that are linked (relevant) to this Orbit Data Message		TDM_MSG_35132.txt <u>TDM_ID 8354</u>	No	No
OBJECT_NAME	Free text field containing the spacecraft name for the object. There is no CCSDS-based restriction on the value for this keyword, but it is recommended to use names from the UN Office of Outer Space Affairs designator index (reference [2]), which include Object name and international designator of the participant.		SPOT ENVISAT IRIDIUM INTELSAT UNKNOWN	No	No
INTERNATIONAL_DESIGNATOR	Free text field containing an international designator for the object as assigned by the UN Committee on Space Research (COSPAR) and the US National Space Science Data Center (NSSDC). Such designator values have the following COSPAR format: YYYY-NNNP{PP}, where: YYYY = Year of launch. NNN = Three digit serial number of launch in year YYYY (with leading zeros). P{PP} = At least one capital letter for the identification of the part brought into space by the launch.  In cases where the object has no international designator, the value UNKNOWN may be used.  <u>NOTE: The international designator is stored in OBJECT_ID in the OPM, OMM and OEM.</u>		2000-052A 1996-068A 2000-053A 1996-008A UNKNOWN	No	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Default (if any)	Examples of Values	Mandatory	Any OCM sections relying upon this field ?
CATALOG_NAME	Free-text field specification of the satellite catalog source (or source agency or operator, value to be drawn from the abbreviated "Organizations" name column of the SANA registry at <a href="https://www.sanaregistry.org/r/organizations">https://www.sanaregistry.org/r/organizations</a> ) from which the international designator and catalog ID were obtained).	CSPOC	CSPOC RFSA ESA COMSPOC N/A	No	No
OBJECT_IDDESIGNATOR	Free text field containing specification of the unique satellite identification designator for the object. It may be useful to provide the control authority/source of this ID as well (e.g., 18SPCS, ISON, independent key ID). If the ID is not known (uncorrelated object), "UNKNOWN" may be used.		22444 18SPCS 18571 2147483648_04ae[...]d84c UNKNOWN N/A	No	No
OPERATOR	Free text field containing the operator of the space object		INTELSAT	No	No
OWNER	Free text field containing the owner of the space object		SIRIUS	No	No
MISSION	Free text field containing the name of the space object's mission (which other space objects may also be a part of)		EOS	No	No
CONSTELLATION	Free text field containing the name of the constellation to which this space object belongs		SPIRE	No	No
LAUNCH_EPOCH	Epoch of initial launch, specified in the DEF_TIME_SYSTEM time system. See 7.5.10 for formatting rules.		2011-11-06T11:17:33	No	No
LAUNCH_COUNTRY	Free text field containing the name of the launch country.		FRANCE	No	No
LAUNCH_SITE	Free text field containing the name of the launch site.		USAF-EASTERN-TEST RANGE FRENCH-GUIANA	No	No
LAUNCH_PROVIDER	Free text field specifying the name of the launch provider		ULA	No	No
LAUNCH_INTEGRATOR	Free text field specifying the name of the launch integrator		NASA	No	No
LAUNCH_PAD	Free text field containing the name of the launch pad.		LC-41	No	No
LAUNCH_PLATFORM	Free text field containing the name of the launch platform or source.		AIRCRAFT GROUND SUBMARINE SHIP SATELLITE MOBILE-GROUND-TRANSPORT	No	No
RELEASE_EPOCH	Epoch of most recent deployment of this space object in the parent/child deployment sequence, specified in the DEF_TIME_SYSTEM time system. See 7.5.10 for formatting rules.		2051-11-06T11:17:33	No	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Default (if any)	Examples of Values	Mandatory	Any OCM sections relying upon this field ?
<del>MISSION_START_EPOCH</del>	<del>Epoch of the beginning of mission operations, specified in the DEF_TIME_SYSTEM time system. See 7.5.10 for formatting rules.</del>		<del>2051-11-06T11:17:33</del>	<del>No</del>	<del>No</del>
<del>MISSION_END_EPOCH</del>	<del>Epoch of the cessation of mission operations, specified in the DEF_TIME_SYSTEM time system. See 7.5.10 for formatting rules.</del>		<del>2051-11-06T11:17:33</del>	<del>No</del>	<del>No</del>
<del>REENTRY_EPOCH</del>	<del>Epoch of the actual (historical) or estimated (future) reentry of this space object, specified in the DEF_TIME_SYSTEM time system. See 7.5.10 for formatting rules.</del>		<del>2051-11-06T11:17:33</del>	<del>No</del>	<del>No</del>
LIFETIME	Estimated remaining orbit lifetime this space object measured in days from <del>DEF_EPOCH_TZERO</del> .		22.0	No	No
<del>CATALOG_NAME</del>	<del>Specification of the satellite catalog source (or source agency or operator, value to be drawn from the abbreviated "Organizations" name column of the SANA registry at <a href="https://www.sanaregistry.org/t/organizations">https://www.sanaregistry.org/t/organizations</a>) from which the international designator and catalog ID were obtained. This is a free text field.</del>	<del>CSPOC</del>	<del>CSPOC RISA ESA COMSPOC</del>	<del>No</del>	<del>No</del>
OBJECT_TYPE	Specification of the type of object, <del>confined to</del> . <u>Select from the accepted set of values listed above indicated in 6.2.3.5.ANEX B, Section B11.</u>		PL RB RD	No	No
OPS_STATUS	<del>Operational status of the space object:</del> <del>OPERATIONAL</del> <del>NONOPERATIONAL</del> <del>PARTIALLY_OPERATIONAL</del> <del>BACKUP</del> <del>STANDBY</del> <del>EXTENDED_MISSION</del> <del>REENTRY_MODE</del> <del>DECAYED</del> <del>UNKNOWN</del>  <del>"Active" space objects include OPERATIONAL, PARTIALLY_OPERATIONAL, BACKUP, STANDBY, and EXTENDED_MISSION. Specification of the operational status of the space object. Select from the accepted set of values indicated in ANNEX B, Section B12.</del>		OPERATIONAL	No	No
ORBIT_TYPE	Specification of the type of orbit, <del>confined to</del> . <u>Select from the accepted set of values listed above indicated in 6.2.3.6.ANEX B, Section B14.</u>		EGO LEO	No	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Default (if any)	Examples of Values	Mandatory	Any OCM sections relying upon this field ?
OCM_DATA_ELEMENTS	Free text field containing a comma-delimited list of elements of information data blocks included in this message.		<u>ORB, PHYSCHAR, MNVR, COV, OD, PERTSORBIT, PHYSICAL DESCRIPTION, COVARIANCE, STM, MANEUVER, PERTURBATIONS, OD, USER</u>	No	No
<u>TIME_SYSTEM</u>	Time system in which EPOCH_TZERO is specified. Select from the accepted set of values indicated in ANNEX B, Section B3.	<u>UTC</u>	<u>UTC</u>	<u>No</u>	<u>Yes (defaults to UTC)</u>
<u>DEF_EPOCH_TZERO</u>	Default epoch to which all relative times are referenced in data blocks, unless overridden by block-specific EPOCH_TZERO values (For format specification, see 7.5.9.10.). The time scale of DEF_EPOCH_TZERO is controlled via the "DEF_TIME_SYSTEM" keyword.		2001-11-06T11:17:33	Yes	Yes
<u>DEF_TIME_SYSTEM</u> <u>CLK_EPOCH</u>	Time system in which DEF_EPOCH_TZERO is specified. Select from the accepted set of values indicated in ANNEX B, Section B3 (and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case). Defines the epoch corresponding to t=0 for the spacecraft clock. This is only used if the spacecraft clock (SCLK) timescale is employed by the user.	<u>1.0</u>	<u>UTC-5000.0</u> <u>1980-01-06T00:00:00</u>	<u>YesNo</u>	<u>NoYes (defaults to UTC)</u>
<u>SCLK_SEC_CLK_PER_SI_SEC</u>	Defines the number of clock seconds occurring during one SI second. This is only used if the spacecraft clock (SCLK) timescale is employed by the user.	1.0	2.5 [s]	No	No
<u>SEC_PER_DAY</u> <u>PREVIOUS MESSAGE_EPOCH</u>	Creation epoch of the previous message from this originator for this particular space object. For format specification, see 7.5. Defines the number of SI seconds in the chosen central body's "day", representing the approximate spin period of rotation for the chosen central body.10. The time scale of this epoch is UTC.  NOTE: One can provide the previous message epoch without supplying the PREVIOUS_MESSAGE_ID, and vice versa	<u>86400.0</u>	<u>2001-11-06T11:17:33</u> <u>88740 [s]</u>	No	<u>Yes (defaults to 86400)No</u>

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Default (if any)	Examples of Values	Mandatory	Any OCM sections relying upon this field ?
<u>NEXT_MESSAGE_EPOCH</u>	Anticipated (or actual) epoch of the next message from this originator for this particular space object. For format specification, see 7.5.10. The time scale of this epoch is UTC.  <u>NOTE: One can provide the next message epoch without supplying the NEXT_MESSAGE_ID, and vice versa</u>		<u>2001-11-07T11:17:33</u>	No	No
<u>EARLIESTSTART_TIME</u>	Time of the earliest data contained in the OCM, specified as either a relative time (e.g., <u>DT=20157.26</u> ) measured in seconds with respect to the <u>DEF_EPOCH_TZERO</u> keyword value or as an absolute time (e.g., <u>T=2018-11-13T11:13:20.SZ</u> as formatted in Section 7.5.9) specified in the “ <u>DEF_TIME_SYSTEM</u> ” timing system tag.		<del>DT=0.0</del> <u>T=2001-11-06T00:00:00</u>	No	No
<u>LATESTEND_TIME</u>	Time of the latest data contained in the OCM, specified as either a relative time (e.g., <u>DT=20157.26</u> ) measured in seconds with respect to the <u>DEF_EPOCH_TZERO</u> keyword value or as an absolute time (e.g., <u>T=2018-11-13T11:13:20.SZ</u> as formatted in Section 7.5.9) specified in the “ <u>DEF_TIME_SYSTEM</u> ” timing system tag.		<del>DT=86400.0</del> <u>T=2001-11-08T00:00:00</u>	No	No
<u>TIME_SPAN</u>	Span of time that the OCM covers, measured in days. <u>TIME_SPAN</u> is defined as ( <u>LATESTEND_TIME</u> - <u>EARLIESTSTART_TIME</u> ), measured in days, irrespective of whether <u>EARLIESTSTART_TIME</u> or <u>LATESTEND_TIME</u> are actually provided by the message creator.		20.0	No	No
<u>TAIMUTC_AT_TZERO</u>	Difference (TAI – UTC) in seconds (i.e. total # leap seconds elapsed since 1958) as modeled by the message originator at epoch “ <u>DEF_EPOCH_TZERO</u> ”.		36 [s]	No	No
<u>UT1MUTC_AT_TZERO</u>	Difference (UT1 – UTC) in seconds, as modeled by the originator at epoch “ <u>DEF_EPOCH_TZERO</u> ”.		0.357 [s]	No	No
<u>EOP_SOURCE</u>	Free text field specifying the source and version of the message originator’s Earth Orientation Parameters (EOP) used in the creation of this message.		e.g., “ <u>CelesTrak EOP file downloaded from <a href="http://celestrak.com/SpaceData/EOP-Last5Years.txt">http://celestrak.com/SpaceData/EOP-Last5Years.txt</a> at 2001-11-08T00:00:00”<u>CELESTRAK</u></u>	No	No
<u>INTERP_METHOD_EOP</u>	Free text field specifying the method used to select or interpolate sequential EOP data	LINEAR	PRECEDING_VALUE NEAREST_NEIGHBOR LINEAR LAGRANGE_ORDER_5	No	No

Keyword	Description	Default (if any)	Examples of Values	Mandatory	Any OCM sections relying upon this field ?
<u>SW_SOURCE</u>	<u>Free text field specifying the source and version of the message originator's space weather data used in the creation of this message.</u>		<u>CELESTRAK</u>	<u>No</u>	<u>No</u>
<u>INTERP_METHOD_SW</u>	<u>Free text field specifying the method used to select or interpolate sequential space weather data</u>	<u>LINEAR</u>	<u>PRECEDING_VALUE</u> <u>NEAREST_NEIGHBOR</u> <u>LINEAR</u> <u>LAGRANGE_ORDER_5</u>	<u>No</u>	<u>No</u>
<u>CELESTIAL_SOURCE</u>	<u>Free text field specifying the source and version of the message originator's celestial body (e.g., Sun/Earth/Planetary) ephemeris data used in the creation of this message.</u>		<u>JPL_DE_FILES</u>	<u>No</u>	<u>No</u>
<u>T_COEFF_SOURCE</u>	<u>Free text field specifying the source and version of the message originator's timing coefficients data used in the creation of this message.</u>		<u>JPL</u>	<u>No</u>	<u>No</u>
<u>META_STOP</u>	<u>End of the metadata section</u>	<u>n/a</u>		<u>n/a</u>	<u>No</u>

**6.2.4 OCM DATA: ORBIT STATE TIME HISTORY**

6.2.4.1 Table 6-84 provides an overview of the OCM orbit state time history (“ephemeris”) section. Only those keywords shown in Table 6-84 shall be used in the OCM orbit state time history data specification.

~~6.2.4.2 Keyword values shall be provided in the units specified in the “Units” column of Table 6-8.~~

~~6.2.4.3 The order of occurrence of these orbit state time history keywords shall be fixed as shown in Table 6-8.~~

~~6.2.4.4 The orbit state time history section is optional; “mandatory” in the context of Table 6-8 denotes those keywords which must be included in this section if this section is included.~~

6.2.4.5 6.2.4.2 Each orbit state time history data block must begin with keyword ORB\_START and end with keyword ORB\_STOP.

~~6.2.4.6 Each of these keywords shall appear on a line by itself.~~

6.2.4.7 6.2.4.3 Multiple orbit state data blocks shall appear in an OCM only if they are delimited by separate ORB\_START and ORB\_STOP keywords

~~6.2.4.8 It is recommended that each data block be clearly differentiated from the others by a unique ORB\_BASIS value or by one or more preceding explanatory comment(s).~~

**6.2.4.96.2.4.4** ~~It is recommended that each~~**Each** orbit state data block **should** be unique from all others in at least one of the following respects:

- 1) the selected element set (ORB\_TYPE) is unique
- 2) the orbit basis (PREDICTED, DETERMINED\_OD, DETERMINED\_TLM, ~~HYPOTHETICAL~~)SIMULATION, OTHER) is unique
- 3) the orbit state time history is based upon a unique orbit determination, navigation solution, or ~~Monte Carlo~~ simulation
- 4) the reference frame is unique
- 5) the orbit center is unique
- 6) the data interval timespan is unique (i.e., has no overlap with any other data interval(s))

**6.2.4.5** ~~In the event that the only difference between multiple orbit state time history data blocks is the selected element set (ORB\_TYPE), reference frame (ORB\_REF\_FRAME) and/or orbit center (CENTER\_NAME), the top-most depiction (i.e., the time history occurring first in the OCM) shall be adopted as the true or master depiction, and those subsequent data blocks shall be treated as containing derivative depictions provided purely for informational purposes.~~

**6.2.4.6** ~~Each orbit state time history shall be time-ordered to be monotonically increasing, with the exception that the message creator may indicate.~~

**6.2.4.7** ~~Positionally-discontinuous orbit states (i.e., separated by a changegap in the orbit state overtime history data across which interpolation should not be performed by providing exactly two consecutive lines containing a duplicate timestamp (e.g. following application) shall be represented by separate orbit state time history data blocks.~~

**6.2.4.8** ~~Velocity-discontinuous orbit states (i.e., by introduction of an impulsive maneuver or spacecraft or orbit event). In the easemanuever) shall be represented by separate orbit state time history data blocks.~~

**6.2.4.106.2.4.9** ~~All orbit state time history blocks must contain a sufficient number of such a duplicate timestamp, data records to allow the recommended interpolation prior to the duplicate timestamp shall use the first of the two duplicate timestamp orbit states, and interpolation after the duplicate timestamp shall use the second of the two. method to be carried out consistently throughout the time span.~~

**6.2.4.11** ~~While discontinuous orbit state time history spans could be accommodated via duplicate time stamps as noted above, it is recommended that such discontinuous time spans be stored in separate covariance data blocks.~~

**6.2.4.126.2.4.10** ~~If the user includes orbit states at key mission events or times, it is recommended that they may be useful to provide times, names, and significance for such mission events are listed in the descriptive comment line(s) immediately following the ORB\_START keyword.~~

**6.2.4.13** ~~Time tags of consecutive orbit states within the ordered sequence may be separated by uniform or non-uniform step size(s).~~

~~6.2.4.14 Orbit state time tags may or may not match those of maneuver, covariance and/or state transition matrix time histories.~~

~~6.2.4.15 All orbit state time history values in the OCM data shall be time-tagged by either a relative time (e.g., DT=20157.26) measured in seconds with respect to the epoch time specified via the ORB\_EPOCH\_TZERO keyword (or default epoch in DEF\_EPOCH\_TZERO if ORB\_EPOCH\_TZERO is not specified), or an absolute time (e.g., T=2018-11-13T11:13:20.5Z as formatted in Section 7.5.9) epoch time.~~

~~6.2.4.16.2.4.11~~ Each line of orbit ephemeris data shall be provided in fixed order ~~as: DT= or T=~~, beginning with an absolute or relative time tag, followed by the corresponding orbit state elements (as defined by ORB\_TYPE; see SANA registry [17] and ANNEX B, Section B7). ~~Units are km, km/s and degrees.~~

~~6.2.4.17.2.4.12~~ At least one space character must be used to separate the items in each orbit ephemeris data line.

~~6.2.4.18.2.4.13~~ The digits of precision and time steps suitable for interpolation of an orbit ephemeris time history should be chosen according to best practice to avoid positional and interpolation loss of precision [M-86].

~~6.2.4.19.2.4.14~~ If an orbit state time history section is included in the message, ~~it is recommended that~~ a corresponding perturbations section should be included as well to specify the perturbations incorporated in these orbit states.

6.2.4.15 The CENTER\_NAME shall be used to specify the origin of the reference frame that the orbit time history is specified in. The specified center may either be a natural, gravitationally-attracting body such as is provided in ANNEX B Section B2, or it may be a non-gravitationally-attracting origin to allow relative positional time histories. If a non-gravitationally-attracting origin is selected, however, then the specified ORB\_TYPE shall be confined to Cartesian or spherical coordinates, where the reference frame may be rotating or inertially fixed.

**Table 6-4: OCM Data: Orbit State Time History**

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
ORB_START	Start of an orbit state vector or time history section	n/a		n/a	Yes
COMMENT	Comments (a contiguous set of one or more comment lines <del>are</del> <u>is</u> allowed in the Orbit State Time History section only immediately after the ORB_START key word; see 7.7 for comment formatting rules).	n/a		<del>COMMENT</del> This is a comment	No
ORB_ID	Optional alphanumeric free-text string containing the identification number for this orbit state time history block	n/a		ORB_201604 02_XYZ	No

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Keyword	Description	Units	Default (if any)	Examples of Values	Mandato ry
ORB_PREV_ID	Optional alphanumeric free-text string containing the identification number for the previous orbit time history. Note: if the message is not part of a sequence of orbit time histories or if this orbit time history is the first in a sequence of orbit time histories, then ORB_PREV_ID should be excluded from this message.	n/a		ORB2016030 5A	No
ORB_NEXT_ID	Optional alphanumeric free-text string containing the identification number for the next orbit time history. Note: if the message is not part of a sequence of orbit time histories or if this orbit time history is the last in a sequence of orbit time histories, then ORB_NEXT_ID should be excluded from this message.	n/a		ORB2016030 5C	No
ORB_BASIS	Basis of this Orbit State time history data, this is free text field with the following suggested values: <ol style="list-style-type: none"> <li>1. "PREDICTED"</li> <li>2. "DETERMINED_OD" when estimated from observation-based orbit determination reconstruction and/or calibration.</li> <li>3. "DETERMINED_TLM" when read directly from telemetry.</li> <li>4. "<u>HYPOTHETICAL-SIMULATED</u>" for <u>generic simulations</u>, future mission design and optimization studies</li> <li>5. "<u>OTHER</u>" for other bases of this data</li> </ol> <p>Note: For definitive OD performed onboard whose solutions have been telemetered to the ground for inclusion in an OCM, the ORB_BASIS <del>shall</del><u>will</u> be considered to be DETERMINED_OD.</p>	n/a		PREDICTED	No
ORB_BASIS_ID	Optional alphanumeric free-text string containing the identification number for the orbit determination, navigation <u>solution</u> , or <del>Monte Carlo</del> simulation upon which this orbit state time history block is based	n/a		OD_5910	No
<u>INTERPOLATION</u>	<u>This keyword may be used to specify the recommended interpolation method for ephemeris data in the immediately following set of ephemeris lines. PROPAGATE indicates that orbit propagation is the preferred method to obtain states at intermediate times, via either a midpoint-switching or endpoint switching approach.</u>	<u>n/a</u>	<u>HERMITE</u>	<u>HERMITE</u> <u>LINEAR</u> <u>LAGRANGE</u> <u>PROPAGATE</u>	<u>No</u>
<u>INTERPOLATION DEGREE</u>	<u>Recommended interpolation degree for ephemeris data in the immediately following set of ephemeris lines. Must be an integer value. This keyword must be used if the 'INTERPOLATION' keyword is used and set to anything other than PROPAGATE.</u>	<u>n/a</u>	<u>3</u>	<u>5</u> <u>1</u>	<u>No</u>

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Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
ORB_AVERAGING	<p><del>Free-text keyword specifying</del> Specifies whether the provided orbit state/elements are based upon either osculating or mean elements, and if so, which mean element definition is employed. The intent of this field is to allow the user to correctly interpret how to use the provided orbit elements and know how to use them operationally.</p> <p>Values should be selected from the accepted set indicated in ANNEX B, Section B12. If an alternate single- or double-averaging formulation is used other than “MEAN_BROUWER” or “MEAN_KOZAI,” provided, the user may name it or use “OTHER” to denote specification via ICD as mutually agreed by message exchange participants.</p>	n/a	OSCULATING	OSCULATING MEAN_BROUWER MEAN_KOZAI AI (other...)	No
CENTER_NAME	<p>Origin of the orbit reference frame, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, or another spacecraft. Select from the accepted set of values indicated in ANNEX B, Section B2 (and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case); reference frame center (such as a spacecraft, ground station, formation flying reference “chief” spacecraft, etc.).</p> <p><del>QUESTION: DO WE WANT THIS TO BE AN OPEN-ENDED LIST (FREE TEXT, EXTENSIBLE WITHOUT COORDINATION), *OR* USE AN ICD TO DEFINE NON-EXISTING NAMES??</del></p> <p><del>*** QUESTION #2: ***</del></p> <p>Could this center be a non-gravitational center (i.e., a slave/chief relative motion case)? Natural bodies shall be selected from the accepted set of values indicated in ANNEX B, Section B2.</p> <p>For spacecraft, it is recommended to use either the Object name or international designator of the participant as catalogued in the UN Office of Outer Space Affairs designator index (reference [2]). Alternately, the OBJECT_DESIGNATOR may be used.</p> <p>For other reference frame origins, this field is a free text descriptor which can draw upon ground station name, etc.</p>	n/a	EARTH	<p><del>EARTH</del> Earth <del>Moon</del> <del>Solar System Barycenter</del> <del>Sun</del></p> <p>MOON SOLAR SYSTEM BARYCENTER SUN ISS EROS EARTH SUN L2 ISS Earth_sun_L2 EGLIN</p>	No
ORB_EPOCH_TZERO	<p>Reference epoch for all relative times in the orbit state time history block. See 7.5.10 for formatting rules. The time system of ORB_EPOCH_TZERO may be set per Annex B, Section B3 via the “ORB_TIME_SYSTEM” keyword.</p>	§7.5.9	<DEF_EPOCH_TZERO>	2001-11-06T11:17:33	No

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
<del>ORB_TIME_SYSTEM</del>	<del>Timing system of ORB_EPOCH_TZERO, selected per Annex B, Section B3.</del>	<del>n/a</del>	<del>&lt;DEF_TIME_SYSTEM&gt;</del>	<del>UTC UT1</del>	<del>No</del>
ORB_REF_FRAME	Reference frame of the orbit state time history. Select from the accepted set of values indicated in ANNEX B, Section B4 (and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case). ANNEX B, Section B4.	n/a	If not intrinsic to selected orbit set, default is ITRF2000	J2000	No
ORB_FRAME_EPOCH	Epoch of the orbit data reference frame, if not intrinsic to the definition of the reference frame. See 7.5.10 for formatting rules.	<del>§7.5.9</del> n/a	<del>&lt;DEF_EPOCH_TZERO&gt;</del>	2001-11-06T11:17:33 2002-204T15:56:23Z	No
ORB_TYPE	Specifies the orbit element set type; selected per ANNEX B, section B7.  <del>If set to ORB_TYPE is set to ICD, then ORB_N and ORB_ELEMENTS are mandatory and shall define the orbit elements used. [DLO1]</del>	n/a	CARTPV	n/a	<del>Yes</del> No
<del>ORB_N</del>	<del>Number of elements (excluding time) contained in the element set if ORB_TYPE is set to ICD. If ORB_TYPE is not set to ICD, then ORB_N shall be ignored in deference to the number of elements corresponding to the selected ORB_TYPE.</del>	<del>n/a</del>	<del>6</del>	<del>8</del>	<del>No</del>
<del>ORB_ELEMENTS</del>	<del>Free text definition of each of the orbit elements, if ORB_TYPE is set to ICD. If ORB_TYPE is not set to ICD, then the number of elements coincides with the selected ORB_TYPE. If ORB_TYPE is not set to ICD, then ORB_ELEMENTS shall be ignored in deference to the element definitions corresponding to the selected ORB_TYPE.</del>	<del>n/a</del>	<del>6</del>	<del>8</del>	<del>No</del>
... < Insert orbit lines here >	<b>Orbit time history line(s) shall be formatted as described above. Units are as specified in 6.2.4.13 – 6.2.4.16 the SANA Orbital Elements registry.</b>	km, km/s, deg			Yes
ORB_STOP	End of an orbit state vector or time history section	n/a		n/a	Yes

## 6.2.5 OCM DATA: SPACE OBJECT PHYSICAL CHARACTERISTICS

6.2.5.1 Table 6-45 gives an overview of the OCM space object physical characteristics section. Only those keywords shown in table 6-45 shall be used in OCM space object physical characteristics data.

~~6.2.5.2 Keyword values shall be provided in the units specified in the “Units” column of Table 6-4.~~

~~6.2.5.3 The order of occurrence of these OCM Space Objects Physical Characteristics keywords shall be fixed as shown in Table 6-4.~~

~~6.2.5.4~~ The “OCM Data: Space Object Physical Characteristics” section is optional; “mandatory” in the context of Table 6-4 denotes those keywords which must be included in this section if this section is included.

~~6.2.5.5~~6.2.5.2 At most, only one space object physical characteristics section shall appear in an OCM.

~~6.2.5.6~~6.2.5.3 The space object physical characteristics data section in the OCM shall be indicated by two keywords: PHYS\_START and PHYS\_STOP.

~~6.2.5.7~~6.2.5.4 The Space Object Optimally-Encompassing ~~Shape (OESBox (OEB))~~ parameters are defined in further detail in ANNEX C.

**Table 6-5: OCM Data: Space Object Physical Characteristics**

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
PHYS_START	Start of a Space Object Physical Characteristics specification	n/a			Yes
COMMENT	Comments (a contiguous set of one or more comment lines <del>are</del> <u>is</u> allowed in the OCM Space Object Physical Characteristics only immediately after the PHYS_START key word; see 7.7 for comment formatting rules).	n/a		<del>COMMENT</del> This is a comment	No
MANUFACTURER	Free text field containing the satellite manufacturer name			BOEING	No
BUS_MODEL	Free text field containing the satellite manufacturer's spacecraft bus model name			702	No
<del>DESIGNED_LIFETIME</del>	<del>Designed lifetime of the spacecraft, in years</del>	<del>yr</del>		<del>4.85</del>	<del>No</del>
DOCKED_WITH	Free text field containing a comma-separated list of other space objects that this object is docked to			ISS	No
<del>INFORMATION_WITH</del>	<del>Free text field containing a comma-separated list of other space objects that this object is formation flying with</del>			<del>TERRA, AQUA</del>	<del>No</del>
DRAG_AREA	<del>Additional</del> Drag Area ( $A_0$ ) facing the relative wind vector, not already incorporated into the attitude-dependent “AREA_ALONG_OES/OEB” parameters	m**2		2.5	No
DRAG_COEFF	Drag Coefficient ( $C_D$ ). If the atmospheric drag coefficient, $C_D$ , is set to zero, no atmospheric drag shall be <del>taken into account</del> <u>considered</u> .	n/a		2.2	No
DRAG_SCALE	Drag scale factor (1.0 represents no scaling). This factor is intended to allow operators to supply the nominal ballistic coefficient components while accommodating ballistic coefficient uncertainties (i.e. 1.06 represents a +6 percent error)	n/a	1.0	1.0	No
<del>INITIAL_MASS_AT BOL</del>	<del>S/C</del> <u>Space object</u> total mass at beginning of life	kg		500	No
MASS	<del>S/C</del> <u>Space object</u> total mass (i.e., “wet mass”) at the <u>current</u> reference epoch “ <del>DEF</del> -EPOCH_TZERO”	kg		472.3	No
<del>DRY_MASS_AT EOL</del>	<del>S/C</del> <u>total</u> <u>Space object</u> <u>dry</u> mass <u>at end of life</u> ( <u>without propellant</u> )	kg		300	No
OES_TYPE	Type of <del>Optimally Encompassing Shape (OES)</del> to use, <del>confined to one of the following basic shapes:</del> <del>BOX</del> <del>ELLIPSOID</del> <del>ELLIPTICAL_CYLINDER</del>	n/a	<del>BOX</del>	ELLIPSOID	<del>No</del>

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	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
	<del>OES</del> OEB_PARENT_FRAME	Reference frame which maps to the <del>OES</del> Optimally Enclosing Box (OEB) frame via the Euler sequence <del>OES</del> OEB_ROLL and <del>OES</del> OEB_YAW. Select from the accepted set of values indicated in <del>ANNEX B</del> ANNEX B, Sections B4 and B5 <del>(and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del>	n/a	RIC	ITRF1997	No
	<del>OES</del> OEB_PARENT_FRAME_EPOCH	Epoch of the <del>OES</del> OEB reference frame, if not intrinsic to the definition of the reference frame. (See 7.5.10 for formatting rules.)	n/a	<del>DEF</del> _EP OCH_TZE RO	2001-11-06T11:17:33 2002-204T15:56:23Z	No
	<del>OES</del> OEB_Q1	$q_1 = e_1 * \sin(\theta/2)$ , where $\theta$ = Euler rotation angle and $e_1$ = 1st component of Euler rotation axis for the rotation that maps from the <del>OES</del> OEB_PARENT_FRAME (defined above) to the frame aligned with the Optimally-Encompassing <del>Shape</del> ( <del>OES</del> Box (OEB) (defined in <del>ANNEX C</del> ANNEX C, Section <del>C1</del> ).C1). A value of "-999" denotes a tumbling space object.	n/a		-0.575131822	No
	<del>OES</del> OEB_Q2	$q_2 = e_2 * \sin(\theta/2)$ , where $\theta$ = Euler rotation angle and $e_2$ = 2nd component of Euler rotation axis for the rotation that maps from the <del>OES</del> OEB_PARENT_FRAME (defined above) to the frame aligned with the Optimally-Encompassing <del>Shape</del> Box (defined in <del>ANNEX C</del> ANNEX C, Section <del>C1</del> ).C1). A value of "-999" denotes a tumbling space object.	n/a		-0.280510532	No
	<del>OES</del> OEB_Q3	$q_3 = e_3 * \sin(\theta/2)$ , where $\theta$ = Euler rotation angle and $e_3$ = 3rd component of Euler rotation axis for the rotation that maps from the <del>OES</del> OEB_PARENT_FRAME (defined above) to the frame aligned with the Optimally-Encompassing <del>Shape</del> Box (defined in <del>ANNEX C</del> ANNEX C, Section <del>C1</del> ).C1). A value of "-999" denotes a tumbling space object.	n/a		-0.195634856	No
	<del>OES</del> OEB_QC	$q_c = \cos(\theta/2)$ , where $\theta$ = Euler axis/angle rotation angle for the rotation that maps from the <del>OES</del> OEB_PARENT_FRAME (defined above) to the frame aligned with the Optimally-Encompassing <del>Shape</del> Box ( <del>ANNEX C</del> ANNEX C, Section <del>C1</del> ).C1). $q_c$ shall be made non-negative by convention. A value of "-999" denotes a tumbling space object.	n/a		0.743144825	No
	<del>OES</del> OEB_MAX	Maximum physical dimension (along $\hat{X}_{OEB}$ ) of the Optimally-Encompassing <del>Shape</del> ( <del>OES</del> Box (OEB) in meters,	m		1	No
	<del>OES</del> OEB_MED	Medium physical dimension -(along $\hat{Y}_{OEB}$ ) of Optimally-Encompassing <del>Shape</del> ( <del>OES</del> Box (OEB) normal to <del>OES</del> OEB_MAX direction	m		0.5	No
	<del>OES</del> OEB_MIN	Minimum physical dimension -(along $\hat{Z}_{OEB}$ ) of Optimally-Encompassing <del>Shape</del> ( <del>OES</del> Box (OEB) in direction normal to both <del>OES</del> OEB_MAX and <del>OES</del> OEB_MED directions	m		0.3	No
	AREA_ALONG_ <del>OES</del> OEB_MAX	Cross-sectional area of space object when viewed along max <del>OES</del> OEB ( $\hat{X}_{OEB}$ ) direction as defined in ANNEX C	m**2		0.15	No
	AREA_ALONG_ <del>OES</del> OEB_MED	Cross-sectional area of space object when viewed along medium <del>OES</del> OEB ( $\hat{Y}_{OEB}$ ) direction as defined in ANNEX C	m**2		0.3	No

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Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
AREA_ALONG_ <del>OE</del> SOEB_MIN	Cross-sectional area of space object when viewed along minimum <del>OE</del> SOEB ( $\hat{Z}_{OEB}$ ) direction as defined in ANNEX C	m**2		0.5	No
AREA_MIN_FOR_PC	Minimum cross-sectional area for collision probability estimation purposes	m**2		1.0	No
AREA_MAX_FOR_PC	Maximum cross-sectional area for collision probability estimation purposes	m**2		1.0	No
AREA_AVG_FOR_PC	Typical (50 <sup>th</sup> percentile) cross-sectional area sampled over all space object orientations for collision probability estimation purposes	m**2		1.0	No
RCS	Typical (50 <sup>th</sup> percentile) effective Radar Cross Section of the space object sampled over all possible viewing angles	m**2		1. <del>0</del> 25	No
RCS_MIN	<u>Minimum Radar Cross Section observed for this object</u>	<u>n/a</u>		<u>1.1</u>	<u>No</u>
RCS_MAX	<u>Maximum Radar Cross Section observed for this object</u>	<u>n/a</u>		<u>2.5</u>	<u>No</u>
SOLAR_RAD_AREA	<del>Additional total</del> Solar Radiation Pressure Area ( $A_R$ ) facing the Sun, not already incorporated into the attitude-dependent "AREA_ALONG_ <del>OE</del> SOEB" parameters (computed from  $\{ \text{AREA\_ALONG\_} \del{OE} \text{SOEB\_MAX} \cos(\theta_1) + \text{AREA\_ALONG\_} \del{OE} \text{SOEB\_MED} \cos(\theta_2) + \text{AREA\_ALONG\_} \del{OE} \text{SOEB\_MIN} \cos(\theta_3) \}$ Where $\theta_i$ represents the angle between the normal to each MAX/MED/MIN face and the direction to the Sun.	m**2		1.0	No
SOLAR_RAD_COEFF	Solar Radiation Pressure Coefficient ( $C_R$ ). Note that if the solar radiation coefficient, $C_R$ , is set to zero, no solar radiation pressure shall be <del>taken into account</del> . <u>considered</u> .	n/a		1.7	No
SOLAR_RAD_SCALE	Solar Radiation Pressure scale factor (1.0 represents no scaling). <u>This factor is intended to allow operators to supply the nominal ballistic coefficient components while accommodating ballistic coefficient uncertainties (i.e. 1.06 represents a +6 percent error)</u>	n/a		1.0	No
VM_ <del>ABS</del> ABSOLUTE	Typical (50 <sup>th</sup> percentile) absolute Visual Magnitude of the space object sampled over all possible viewing angles and "normalized" as discussed in Annex C, Section <del>C-4C-2</del> to a 1 AU Sun-to-target distance, a phase angle of 0° and a 40,000 km target-to-sensor distance (equivalent of GEO satellite tracked at 15.6° above local horizon)	n/a		15.0	No
VM_APPARENT_MIN	<u>Minimum apparent Visual Magnitude observed for this space object</u>	<u>n/a</u>		<u>19.0</u>	<u>No</u>
VM_APPARENT	<u>Typical (50<sup>th</sup> percentile) apparent Visual Magnitude observed for this space object</u>	<u>n/a</u>		<u>15.0</u>	<u>No</u>
VM_APPARENT_MAX	<u>Maximum apparent Visual Magnitude observed for this space object (NOTE: The "MAX" value represents the brightest observation, which associates with a lower Vmag)</u>	<u>n/a</u>		<u>16.0</u>	<u>No</u>
REFLECTIVITY	Typical (50 <sup>th</sup> percentile) coefficient of reflectivity of the space object <del>sampled</del> over all possible viewing angles, <u>ranging from -1.0 to +1.0</u>	n/a		<del>15.0</del> .7	No

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	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
	CONTROL_MODE	<del>Primary</del> Free-text specification of <del>primary</del> mode of attitude control for the space object. Suggested examples include: <ul style="list-style-type: none"> <li>- THREE_AXIS</li> <li>- SPIN</li> <li>- DUAL_SPIN</li> <li>- TUMBLING</li> <li><del>GRAVITY_GRADIENT</del></li> <li><del>PASSIVE_MAG_TORQUE</del></li> <li><del>ACTIVE_MAG_TORQUE</del></li> <li><del>CMGS</del></li> <li>- ATT_THRUSTERS</li> </ul>	n/a		CMGS	No
	<u>ACTUATOR_TYPE</u>	<u>Free-text specification of type of actuator for attitude control. Suggested examples include:</u> <ul style="list-style-type: none"> <li>- <u>ATT_THRUSTERS</u></li> <li>- <u>ACTIVE_MAG_TORQUE</u></li> <li>- <u>PASSIVE_MAG_TORQUE</u></li> <li>- <u>CMGS</u></li> <li>- <u>NONE</u></li> <li>- <u>OTHER</u></li> </ul>	<u>deg</u>		<u>0.3</u>	<u>No</u>
ATT	KNOWLEDGE	Accuracy of attitude knowledge	deg		0.3	No
ATT	CONTROL	Ability to control attitude <del>pointing</del>	deg		2.0	No
ATT	<u>POINTING</u>	<u>Combined ability to both knowledge and control attitude</u>	<u>deg</u>		<u>2.3</u>	<u>No</u>
AVG	MANEUVER_FREQ	Average maneuver frequency, measured in <u>the number of orbit- or attitude-adjust</u> maneuvers per year	per yr		20.0	No
MAX	THRUST	Maximum composite thrust the spacecraft can accomplish in any single body-fixed direction	N		1.0	No
DV	BOL	Total ΔV capability of the spacecraft at beginning of life	<del>mk</del> m/s		14000.0	No
DV	REMAINING	Total ΔV remaining <del>capability of</del> the spacecraft	<del>mk</del> m/s		5000.0	No
IXX		Moment of Inertia about the X-axis of the <del>spacecraft's</del> <u>space object's</u> primary body frame (e.g. SC_Body_1)	kg*m <sup>**2</sup>		1000.0	No
IYY		Moment of Inertia about the Y-axis	kg*m <sup>**2</sup>		800.0	No
IZZ		Moment of Inertia about the Z-axis	kg*m <sup>**2</sup>		400.0	No
IXY		Inertia Cross Product of the X & Y axes	kg*m <sup>**2</sup>		20.0	No
IXZ		Inertia Cross Product of the X & Z axes	kg*m <sup>**2</sup>		40.0	No
IYZ		Inertia Cross Product of the Y & Z axes	kg*m <sup>**2</sup>		60.0	No
PHYS	STOP	End of <del>the</del> Space Object Physical Characteristics specification	n/a			Yes

## 6.2.6 OCM DATA: ORBIT STATE COVARIANCE TIME HISTORY

6.2.6.1 Table 6-96 provides an overview of the OCM orbit state covariance time history section. Only those keywords shown in Table 6-96 shall be used in the OCM orbit state covariance time history data specification.

~~6.2.6.2 Keyword values shall be provided in the units specified in the “Units” column of Table 6-9.~~

~~6.2.6.3 The order of occurrence of these orbit state covariance time history keywords shall be fixed as shown in Table 6-9.~~

~~6.2.6.4 The orbit state covariance time history section is optional; “mandatory” in the context of Table 6-9 denotes those keywords which must be included in this section if this section is included.~~

~~6.2.6.5~~6.2.6.2 Each orbit state covariance time history data block must begin with keyword COV\_START and end with keyword COV\_STOP.

~~6.2.6.6 Each of these keywords shall appear on a line by itself.~~

~~6.2.6.7~~6.2.6.3 Multiple orbit state covariance data blocks shall appear in an OCM only if they are delimited by separate COV\_START and COV\_STOP keywords

~~6.2.6.8 It is recommended that each data block be clearly differentiated from the others by a unique COV\_BASIS value or by one or more preceding explanatory comment(s).~~

~~6.2.6.9~~6.2.6.4 It is recommended that eachEach orbit state covariance data block **should** be unique from all others in at least one of the following respects:

- 1) the selected covariance element set (COV\_TYPE) is unique
- 2) the covariance time history basis (PREDICTED, DETERMINED\_OD, EMPIRICAL, MONTECARLO, HYPOTHETICALSIMULATION, OTHER)
- 3) the covariance time history is based upon a unique orbit determination, navigation solution, or Monte Carlo-simulation
- 4) the reference frame is unique
- 5) the orbit center is unique
- 6) the data interval timespan is unique (i.e., has no overlap with any other data interval(s))

~~6.2.6.10 The COV\_TYPE keyword value shall be selected from Table B4 or B5.~~

6.2.6.5 In the event that the only difference between multiple covariance time history data blocks is the selected element set (COV\_TYPE) and/or reference frame (COV\_REF\_FRAME), the top-most depiction (i.e., the time history occurring first in the OCM) shall be adopted as the true or master depiction, and those subsequent data blocks shall be treated as containing derivative depictions provided purely for informational purposes

~~6.2.6.6~~ Each orbit state covariance time history shall be time-ordered to be monotonically increasing, ~~with the exception that the message creator may indicate a change in state over which interpolation should not be performed by providing exactly two consecutive covariance data blocks containing a duplicate timestamp (e.g. following application of an impulsive maneuver or spacecraft or orbit event). In the case of such a duplicate timestamp, interpolation prior to the duplicate timestamp shall use the first of the two duplicate timestamp.~~

~~6.2.6.11~~6.2.6.7 Discontinuous covariance ~~matrices, and interpolation after the duplicate timestamp~~ time segments shall use the ~~second of the two~~ be represented by separate orbit state covariance time history data blocks.

~~6.2.6.12~~ While ~~discontinuous covariance time history spans could be accommodated via duplicate time stamps as noted above, it is recommended that such discontinuous time spans be stored in separate covariance data blocks.~~

~~6.2.6.13~~6.2.6.8 If the user includes orbit state covariances at key mission events or times, it ~~is recommended that they~~ may be useful to provide times, names, and significance for such mission events ~~be provided~~ in descriptive comment line(s) immediately following the COV\_START keyword.

~~6.2.6.14~~ Time tags of consecutive covariance information within the ordered sequence may be separated by uniform or non-uniform step size(s).

~~6.2.6.15~~ Covariance time tags may or may not match those of maneuver, orbit state and/or state transition matrix time histories.

~~6.2.6.16~~6.2.6.9 Values in the orbit state covariance matrix shall be expressed in the applicable reference frame specified via the 'COV\_REF\_FRAME' keyword.

~~6.2.6.17~~6.2.6.10 If an orbit state covariance time history section is included in the message, ~~it is recommended that~~ a corresponding perturbations section should be included as well to specify the perturbations incorporated in these orbit state covariances.

~~6.2.6.18~~ All orbit state covariance time history values in the OCM data shall be **time-tagged by either a relative time** (e.g., DT=20157.26) measured in seconds with respect to the epoch time specified via the COV\_EPOCH\_TZERO keyword (or default epoch in DEF\_EPOCH\_TZERO if COV\_EPOCH\_TZERO is not specified), **or an absolute time** (e.g., T=2018-11-13T11:13:20.5Z as formatted in Section 7.5.9) epoch time.

~~6.2.6.19~~6.2.6.11 For COV TYPE = TEIGVAL3EIGVEC3, the covariance time tag and eigenvalues and eigenvectors ~~and eigenvalues~~ shall all be presented on a single line, comprised of the time tag, followed by the major, medium and minor eigenvalues and then followed by the major, medium and minor eigenvectors, respectively.

~~6.2.6.20~~6.2.6.12 For all other COV TYPE values:

~~6.2.6.20.16.2.6.12.1~~ 6.2.6.12.1 The order in which data items are given shall be fixed, with the elements in each row of covariates and the number “N” of elements both being commensurate with the specified COV\_TYPE value.

~~6.2.6.20.26.2.6.12.2~~ 6.2.6.12.2 Each covariance shall be preceded by a single line containing the ~~time tag~~ (relative “DT=” or absolute “T=”) time tag of the covariance matrix.

~~6.2.6.20.36.2.6.12.3~~ 6.2.6.12.3 Directly following the time tag specification line, each of the “N” rows of the lower triangular covariance matrix shall be presented containing from one [1,1] to “N” numerical entries depending on what row of the matrix is being represented (first row has one element, second row has two, continuing in this fashion until the “Nth” row has “N” elements). Units are km, km/s and degrees. Units are as specified in the Covariance portion of the SANA registry [18].

~~6.2.6.20.46.2.6.12.4~~ 6.2.6.12.4 At least one space character must be used to separate the items in each covariance matrix data line.

~~6.2.6.216.2.6.13~~ 6.2.6.13 Variance and covariance values shall be expressed in ~~standard double precision floating point or scientific notaton~~ as related in 7.5. The digits of precision and time steps suitable for interpolation of a covariance time history should be chosen according to best practice to avoid covariance and interpolation loss of precision [M-~~86~~].

NOTE: Interpolation of covariance matrices at neighboring relative time points shall be done by (1) eigenvalue/vector decomposition; (2) linear (or higher-order) interpolation of neighboring eigenvalues; (3) Euler axis/angle rotation of eigenvectors at intermediate time(s) of interest; and (4) Re-composition of attained eigenvalues and eigenvectors into covariances at time(s) of interest [M-~~169~~]. Direct interpolation of covariance matrix components or failure to incorporate sufficient digits of precision on the interpolated covariance elements can produce invalid (non-positive-semidefinite) covariances.

**Table 6-6: OCM Data: Covariance Time History**

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
COV_	START	Start of a covariance time history section	n/a		n/a	Yes
COMMENT		Comments (a contiguous set of one or more comment lines <del>are</del> allowed in the OCM Covariance Time History section only immediately after the COV_START key word; see 7.7 for comment formatting rules).	n/a		<del>COMMENT</del> -This is a comment	No
COV_	ID	Optional alphanumeric free-text string containing the identification number for this covariance time history block	n/a		COV_20160402_XYZ	No
COV_	PREV_ID	Optional alphanumeric free-text string containing the identification number for the previous covariance time history. Note: if the message is not part of a sequence of covariance time histories or if this covariance time history is the first in a sequence of covariance time histories, then COV_PREV_ID should be excluded from this message.	n/a		COV_20160305A	No
COV_	NEXT_ID	Optional alphanumeric free-text string containing the identification number for the next covariance time history. Note: if the message is not part of a sequence of covariance time histories or if this covariance time history is the last in a sequence of covariance time histories, then COV_NEXT_ID should be excluded from this message.	n/a		COV_20160305C	No
COV_	BASIS	Basis of this covariance time history data. This is free text field with the following suggested values: <ol style="list-style-type: none"> <li>1. "PREDICTED"</li> <li>2. "DETERMINED_OD" when estimated from observation-based orbit determination reconstruction and/or calibration.</li> <li>3. EMPIRICAL (for empirically-determined such as overlap analyses)</li> <li>4. <del>MONTE_CARLOSIMULATION</del> for simulation-based (including Monte Carlo-based simulation) estimations-</li> <li>5.4. "HYPOTHETICAL" for future mission design and optimization studies.</li> <li>5. "OTHER" for other bases of this data</li> </ol> <p>Note: For definitive OD performed onboard whose solutions have been telemetered to the ground for inclusion in an OCM, the COV_BASIS shall be considered to be DETERMINED_OD.</p>	n/a	PREDICTED	PREDICTED EMPIRICAL DETERMINED_OD <del>MONTE_CARLOSIMULATION</del> OTHER	No
COV_	BASIS_ID	Optional alphanumeric free-text string containing the identification number for the orbit determination, navigation <del>solution</del> , or <del>Monte Carlo</del> simulation upon which this orbit state time history block is based.	n/a		OD_5910	No
COV_	EPOCH_TZERO	<del>Reference epoch for all relative times in the covariance time history block. See 7.5.10 for formatting rules. The time system of COV_EPOCH_TZERO may be set per Annex B, Section B3 via the "COV_TIME_SYSTEM" keyword.</del>	<del>§7.5.9</del>	<del>&lt;DEF_EPOCH_TZERO&gt;</del>	<del>2001-11-06T11:17:33</del>	<del>No</del>
COV_	TIME_SYSTEM	<del>Timing system of COV_EPOCH_TZERO, selected per Annex B, Section B3.</del>	n/a	<del>&lt;DEF_TIME_SYSTEM&gt;</del>	<del>UTC UT1</del>	<del>No</del>

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
COV_	REF_FRAME	Reference frame of the covariance time history. Select from the accepted set of values indicated in <del>ANNEX B, Section B4 and B5 (and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case).</del> ANNEX B, <del>Section B4 and B5.</del>	n/a	TNW	J2000	No
COV_	FRAME_EPOCH	Epoch of the covariance data reference frame, if not intrinsic to the definition of the reference frame. See 7.5.10 for formatting rules.	<del>§7.5.9n</del> /a	<del>&lt;DEF_EPOCH_TZER</del> O>	2001-11-06T11:17:33 2002-204T15:56:23Z	No
<del>COV_</del>	<del>NNXNN</del>	<del>Number of diagonal elements contained in full covariance if COV_TYPE is set to ICD. If COV_TYPE is not set to ICD, then the number of diagonal elements shall coincide with the selected COV_TYPE (ANNEX B, Sections B7 and B8).</del>	<del>n/a</del>	<del>6</del>	<del>10</del>	<del>No</del>
COV_	TYPE	Indicates covariance composition. Select from <del>ANNEX B</del> ANNEX B, Sections <del>B7</del> B7 and <del>B8</del> (and note the procedure to propose new values). <del>B8.</del>	n/a	CARTPV	n/a	Yes
COV_	SCALE_MIN	Minimum scale factor to apply to this covariance data to achieve realism	n/a	1	0.5	No
COV_	SCALE_MAX	Maximum scale factor to apply to this covariance data to achieve realism	n/a	1	5.0	No
COV_	CONFIDENCE	A measure of the confidence in the covariance errors matching reality <del>(AWAITING SPECIFIC INPUTS FROM CHERYL), as characterized via a Wald test, a Chi-squared test, the log of likelihood, or a numerical representation per mutual agreement. This is a free text field.</del>	n/a			No
...<	Insert covariance data here>	Covariance data shall be provided as specified <u>above</u> . <del>Units are as specified in sections 6.2.6.15—6.2.6.18</del> <u>the SANA Covariance Matrices registry.</u>	<del>km;</del> <del>km/s;</del> <del>deg</del>			Yes
COV_	STOP	End of a covariance time history section.	n/a		n/a	Yes

## 6.2.7 OCM DATA: STATE TRANSITION MATRIX TIME HISTORY

6.2.7.1 Table 6-107 provides an overview of the OCM state transition matrix time history section. Only those keywords shown in Table 6-107 shall be used in OCM state transition matrix time history data specification.

~~6.2.7.2 Keyword values shall be provided in the units specified in the “Units” column of Table 6-10.~~

~~6.2.7.3 The order of occurrence of these OCM state transition matrix time history keywords shall be fixed as shown in table 6-10.~~

~~6.2.7.4 The OCM state transition matrix time history section is optional; “mandatory” in the context of Table 6-10 denotes those keywords which must be included in this section if this section is included.~~

~~6.2.7.5~~6.2.7.2 Each state transition matrix time history data block must begin with keyword STM\_START and end with keyword STM\_STOP.

~~6.2.7.6 Each of these keywords shall appear on a line by itself.~~

~~6.2.7.7~~6.2.7.3 Multiple state transition matrix data blocks shall appear in an OCM only if they are delimited by separate STM\_START and STM\_STOP keywords

~~6.2.7.8 It is recommended that each data block be clearly differentiated from the others by a unique STM\_BASIS value or by one or more preceding explanatory comment(s).~~

~~6.2.7.9~~6.2.7.4 It is recommended that each STM data block**Each STM data block should be** be unique from all others in at least one of the following respects:

- 1) the selected orbit state element set (STM\_TYPE) is unique;
- 2) the state transition matrix time history is based upon a unique orbit determination, navigation solution, or ~~Monte Carlo~~ simulation;
- 3) the reference frame is unique;
- 4) the orbit center is unique;
- 5) the state transition matrix timespan is unique.

~~6.2.7.5 In the event that the only difference between multiple state transition matrix time history data blocks is the selected element set (STM\_TYPE), reference frame (STM\_REF\_FRAME), orbit center (STM\_CENTER\_NAME) and/or STM mapping mode (STM\_MAP\_MODE), the top-most depiction (i.e., the time history occurring first in the OCM) shall be adopted as the true or master depiction, and those subsequent data blocks shall be treated as containing derivative depictions provided purely for informational purposes.~~

~~6.2.7.10~~6.2.7.6 The STM\_TYPE keyword value shall be selected from ~~Table B4~~ANNEX B, Section B7 and B8, or alternately, “ICD” denotes state transition matrix composition definition via ICD.

~~6.2.7.7~~ Each state transition matrix time history shall be time-ordered to be monotonically increasing ~~with no duplicate time points permitted within each time history.~~

~~6.2.7.11~~6.2.7.8 Discontinuous segments of state transition matrix time histories (such as occurs when the STM basis state and accompanying STM\_ORB\_TIME is changed) shall be represented by separate STM data blocks.

~~6.2.7.12~~6.2.7.9 No interpolation of the state transition matrix time history shall be undertaken, since the state transition matrix pre- and post-multiplies the state (or covariance) in the mapping process to yield states and covariances that may then be properly interpolated.

~~6.2.7.13~~ ~~Discontinuous state transition matrix time spans be stored in separate state transition matrix data blocks.~~

~~6.2.7.14~~6.2.7.10 If the user includes state transition matrices at key mission events or times, it ~~is recommended that they~~ may be useful to provide times, names and significance for such mission events ~~are listed~~ in the descriptive comment line(s) immediately following the STM\_START keyword.

~~6.2.7.15~~ ~~Time tags of consecutive state transition matrices within the ordered sequence may be separated by uniform or non-uniform step size(s).~~

~~6.2.7.16~~ ~~State transition matrix time tags may or may not match those of maneuver, orbit state and/or covariance time histories.~~

~~6.2.7.17~~6.2.7.11 The reference frame of the state transition matrices must be provided via the 'STM\_REF\_FRAME' keyword.

~~6.2.7.18~~6.2.7.12 Values in each state transition matrix shall be expressed in the applicable reference frame and shall be presented sequentially from upper to lower and row-by-row from left to right. State transition matrix values shall be expressed in standard double precision as discussed in 7.5.

~~6.2.7.19~~ ~~All state transition matrices in the OCM data shall be **time tagged by either a relative time** (e.g., DT=20157.26) measured in seconds with respect to the epoch time specified via the STM\_EPOCH\_TZERO keyword (or default epoch in DEF\_EPOCH\_TZERO if STM\_EPOCH\_TZERO is not specified), **or an absolute time** (e.g., T=2018-11-13T11:13:20.5Z as formatted in Section 7.5.9) epoch time.~~

~~6.2.7.20~~6.2.7.13 Each row of each state transition matrix must be provided on a single line. The order in which data items are given shall be fixed. The elements in each row shall be defined commensurate with the STM\_TYPE keyword specification. The "N" rows of the state transition matrix shall each contain "N" numbers. ~~Units are km, km/s and degrees.~~

~~6.2.7.21~~6.2.7.14 At least one space character must be used to separate the items in each state transition matrix data line.

~~6.2.7.22~~6.2.7.15 The digits of precision and time steps suitable for state transition matrix time history should be chosen to avoid STM propagation loss of precision.

~~6.2.7.23~~6.2.7.16 If an STM time history section is included in the message, ~~it is recommended that~~ a corresponding perturbations section should be included as well to specify the perturbations incorporated in the STM data.

NOTE: State Transition Matrices (STMs) can be very useful in mapping both an initial state, and (separately) differences about that state, to other time(s) of interest. Following the terminology and definitions of reference [M-97], pp. 82, 778-780 and 809) allows the analyst to map states, or alternatively state differences, at time  $t_0$  to another time  $t_i$ . As noted in reference [M-97], these are distinctly different in definition and content from each other. Both types of State Transition Matrices are supported, as specified by the STM\_MAP\_MODE keyword.

**Table 6-7: OCM Data: State Transition Matrix Time History**

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
STM_START	Start of a state transition matrix time history	n/a		n/a	Yes
COMMENT	Comments (a contiguous set of one or more comment lines <del>are</del> allowed in the OCM State Transition Matrix Time History section only immediately after the STM_START key word; see 7.7 for comment formatting rules).	n/a		<del>COMMENT</del> -This is a comment	No
STM_ID	Optional alphanumeric free-text string containing the identification number for this state transition matrix time history block.	n/a		STM_20160402_XYZ	No
STM_PREV_ID	Optional alphanumeric free-text string containing the identification number for the previous state transition matrix time history block. Note: if the message is not part of a sequence of state transition matrix time history blocks or if this state transition matrix time history block is the first in a sequence of state transition matrix time history blocks, then STM_PREV_ID should be excluded from this message.	n/a		STM_20160305A	No
STM_NEXT_ID	Optional alphanumeric free-text string containing the identification number for the next state transition matrix time history block. Note: if the message is not part of a sequence of state transition matrix time history blocks or if this state transition matrix time history block is the last in a sequence of state transition matrix time history blocks, then <del>EC</del> STM_NEXT_ID should be excluded from this message.	n/a		STM_20160305C	No
STM_MAP_MODE	Indicates whether state transition matrix maps: <ul style="list-style-type: none"> <li>- An initial state to later states (STATE) or</li> <li>- Initial state differences (or uncertainties) to later differences (DIFFERENCES)</li> </ul>	n/a	DIFFERENCES	STATE DIFFERENCES	Yes
STM_ORB_STATEID	<del>Initial</del> !ID of the orbit state at STM_EPOCH_TZERO <del>from</del> ORB_STATE_TIME upon which the state transition mapping is derived and referenced	km, km/s, deg	<del>(consistent with "STM_TYP E")</del>	<del>ORB_ID_0012789600.0-280000.0-1746800.0-4730.0-2500.0-1040.0</del>	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
STM_BASIS	<p>Basis of this covariance time history data. This is free text field with the following suggested values:</p> <ol style="list-style-type: none"> <li>1. "PREDICTED"</li> <li>2. "DETERMINED_OD" when estimated from observation-based orbit determination reconstruction and/or calibration.</li> <li>3. EMPIRICAL (for empirically-determined such as overlap analyses)</li> <li>4. <del>MONTE_CARLOSIMULATION</del> for <u>simulation-based (including Monte Carlo-based simulation)</u> estimations-</li> <li>5.4. <del>"HYPOTHETICAL"</del> for future mission design and optimization studies</li> <li>5. <u>"OTHER" for other bases of this data</u></li> </ol> <p>Note: For definitive OD performed onboard whose solutions have been telemetered to the ground for inclusion in an OCM, the <del>COV</del>STM_BASIS shall be considered to be DETERMINED_OD.</p>	n/a	PREDICTED	<p>PREDICTED</p> <p><del>DETERMINED_OD</del></p> <p>EMPIRICAL</p> <p><del>DETERMINED</del></p> <p><del>MONTE_CARLOS</del></p> <p><del>IMULATION</del></p> <p><del>OTHER</del></p>	No
STM_BASIS_ID	Optional alphanumeric free-text string containing the identification number for the orbit determination, navigation <u>solution</u> , or <del>Monte Carlo</del> simulation upon which this STM time history block is based	n/a		OD_5910	No
STM_CENTER_NAME	<p><b>Origin of the STM reference frame</b>, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, or another <u>reference frame center (such as a spacecraft—Select, ground station, formation flying reference "chief" spacecraft, etc.)</u>.</p> <p><u>Natural bodies shall be selected</u> from the accepted set of values indicated in <del>ANNEX B</del>ANNEX B, Section <del>B2</del> (and note <del>B2</del>).</p> <p><u>For spacecraft, it is recommended to use either the procedure to propose a new value, if Object name or international designator of the participant as catalogued in the UN Office of Outer Space Affairs designator index (reference [2]). Alternately, the OBJECT DESIGNATOR may be used.</u></p> <p><u>For other reference frame origins, this set of existing ANNEX B values does not accommodate your particular use case—field is a free text descriptor which can draw upon ground station name, etc.</u></p>	n/a	EARTH	<p>EARTH</p> <p>MOON</p> <p>SOLAR SYSTEM</p> <p>BARYCENTER</p> <p>SUN</p> <p>ISS</p> <p>EROS</p> <p>EARTH_SUN_L2</p>	No
STM_ORB_STATE	<p><u>Initial orbit state at STM_ORB_TIME from which the state transition mapping is derived and referenced.</u></p> <p><u>Units are as specified in Reference [B-7].</u></p>			<p>2789600.0 -280000.0</p> <p>-1746800.0 4730.0 -</p> <p>2500.0 -1040.0</p>	<u>No</u>

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
<del>STM_EPOCH_TZERO</del> <del>ORB TIME</del>	The epoch ( <u>relative to EPOCH_TZERO or absolute</u> ) to which the STM_ORB_STATE and any state transition matrix relative times are referenced in the STM block, and at which time the STM = the identity matrix. <del>The time system of STM_EPOCH_TZERO may be set per Annex B, Section B3 via the “STM_TIME_SYSTEM” keyword.</del>	<del>§7.5.9 n/a</del>	<del>&lt;DEF_EPOCH_TZERO &gt;</del>	2001-11-06T11:17:33	Yes
<del>STM_TIME_SYSTEM</del>	<del>Timing system of STM_EPOCH_TZERO, selected per Annex B, Section B3.</del>	<del>n/a</del>	<del>&lt;DEF_TIME_SYSTEM&gt;</del>	<del>UTC UT1</del>	<del>No</del>
STM_REF_FRAME	Reference frame to which the state transition matrix is referenced, if not intrinsic to the definition of the STM data. Select from the accepted set of values indicated in <u>ANNEX B, Section B4 and ANNEX B, Section B4 and B5</u> ( <u>and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case</u> ). <del>.</del>	n/a	<b>ICRF3</b>	J2000	No
<del>STM_FRAME_EPOCH</del>	Epoch of the state transition matrix data reference frame, if not intrinsic to the definition of the reference frame. (See 7.5.10 for formatting rules.) <del>)</del>	<del>§7.5.9 n/a</del>	<del>&lt;DEF_EPOCH_TZERO &gt;</del>	2001-11-06T11:17:33 2002-204T15:56:23Z	No
<del>STM_N</del>	<del>Dimension “N” of the “N x N” state transition matrix if STM_TYPE is set to ICD. If STM_TYPE is not set to ICD, then the dimension “N” coincides with the number of elements implied by STM_TYPE (ANNEX B, Section B7 and B8).</del>	<del>n/a</del>	<del>6</del>	<del>6</del>	<del>No</del>
STM_TYPE	Indicates state transition matrix composition; selected from ANNEX B, Section <u>B7B7 and B8B8</u> , or alternately, “ICD” denotes state transition matrix composition definition via ICD <del>.</del>	n/a	CARTPV	CARTPV	Yes
...< Insert STM data here>	State transition matrices shall be provided as specified <u>in sections 6.2.7.17–6.2.7.20</u> above. Units shall be consistent with <u>ANNEX B, Section B7 and B8, or alternately per ICD</u> .	<del>km, km/s, deg</del>			Yes
STM_STOP	End of a state transition matrix time history section	n/a		n/a	Yes

## 6.2.8 OCM DATA: MANEUVER SPECIFICATION

~~6.2.8.1~~ The “OCM Data: Maneuver Specification” section is optional; “mandatory” in the context of Table 6-10 denotes those keywords which must be included in this section if this section is included.

~~6.2.8.2~~6.2.8.1 Table 6-10 provides an overview of the OCM maneuver specification section. Only those keywords shown in Table 6-10 shall be used as Key Value Notation keywords in the OCM maneuver specification.

~~6.2.8.3~~ Each of these keywords shall appear on a line by itself.

~~6.2.8.4~~ Keyword values shall be provided in the units specified in the “Units” column of Table 6-10 (m/s, m/s<sup>2</sup>, N, kg and degrees).

~~6.2.8.5~~6.2.8.2 The order of occurrence of these OCM Maneuver Specification keywords shall be fixed as shown in Table 6-10.

~~6.2.8.6~~6.2.8.3 Maneuver data in the OCM shall be indicated by two keywords: MAN\_START and MAN\_STOP.

~~6.2.8.7~~6.2.8.4 Multiple maneuver data blocks shall appear in an OCM only if they are when delimited by separate MAN\_START and MAN\_STOP keywords.

~~6.2.8.8~~ It is recommended that each data block be clearly differentiated from the others by either having a unique THR\_ID or by one or more preceding explanatory comment(s).

6.2.8.5 The time intervals of multiple maneuver data blocks may be separated in time, but, or overlap and/or be otherwise unsorted,

6.2.8.9 NOTE: This is done to accommodate multiple maneuver reference frames, multiple thrusters in simultaneous operation, or to accommodate changes in thrust direction, efficiency, mass change, deployments during thrusting phases, multiple basis definitions (MAN\_BASIS), etc.

~~6.2.8.10~~ Discontinuous maneuver sequence time spans be stored in separate maneuver data blocks.

~~6.2.8.11~~ Each maneuver data block shall be assigned an integer thruster a maneuver device ID (THRMAN\_DEVICE\_ID) value.

•6.2.8.6 Non-zero THR\_ID values specify the unique thruster identification number to, which specifies the unique thruster (or other propulsive device) identifier corresponding to this maneuver sequence time history data block belongs.

- ~~A THR\_ID value of “0” (zero) designates that this maneuver block applies generically to the space object as a whole and is not the result of a specific thruster unit.~~
- Except for the special values “ALL” and “DEPLOY”, MAN\_DEVICE\_ID is a free text field which allows the user to identify which specific thruster or other propulsive device performed this maneuver time history.
- A MAN\_DEVICE\_ID value of “ALL” shall be used to indicate that this maneuver sequence represents an aggregation of thrust, acceleration, and/or velocity increments imparted by any/all thrusters and/or other perturbative forces utilized in the maneuver which are not attributed to a single specific propulsive device.
- A MAN\_DEVICE\_ID value of “DEPLOY” shall be used to indicate that this maneuver data block represents ONLY maneuvers caused by a series of one or more deployments from this host vehicle.

6.2.8.7 Each maneuver data block shall only specify a single maneuver device ID (MAN\_DEVICE\_ID) value.

6.2.8.8 Multiple maneuver data blocks may specify the same maneuver device ID (MAN\_DEVICE\_ID) value.

6.2.8.126.2.8.9 The basis of each maneuver data block is set via MAN\_BASIS. Per Table 6-10, MAN\_BASIS shall be one of the following values:

- CANDIDATE
- PLANNED
- ANTICIPATED
- DETERMINED\_TLM
- DETERMINED\_OD

6.2.8.136.2.8.10 Maneuver descriptions shall be designated as either MAN\_IS\_ADDITIVE=“YES” or “NO”.

- “YES” designates that this described maneuver “constituent” shall be added to any/all other additive-designated maneuver descriptions **within the same MAN\_BASIS-category, MAN REF FRAME and MAN CENTER NAME categories** to arrive at the total composite maneuver description.
- “NO” designates that this described maneuver shall be interpreted as being the aggregated/total composite maneuver and that no other additive maneuver constituents are to be added to it.

6.2.8.10.1 Pairing these two possibilities with the five MAN\_BASIS categories, thereThe message recipient should exercise caution whenever maneuvers are ten possibleadditive (MAN\_IS\_ADDITIVE=YES), to prevent the unintentional accumulation of maneuver

contributions, for example across disparate orbit determination solutions (MAN\_OD\_ID).

**6.2.8.11 Each maneuver data block should be unique from all other maneuver data blocks in at least one of the following respects:**

- 1) the maneuver device ID (MAN\_DEVICE\_ID) is unique
- 2) the maneuver device ID is the same, but the “ON” time intervals are unique and do not overlap with any other data interval(s) for this maneuver device ID (e.g., during multiple interleaved duty cycle “ON” firings).
- 3) the maneuver basis (MAN\_BASIS) is unique
- 4) the reference frame is unique (MAN\_REF\_FRAME)
- 5) the orbit center is unique (MAN\_CENTER\_NAME)
- 6) the maneuver is based upon a unique orbit determination, navigation solution, or simulation (e.g., MAN\_OD\_ID)
- 7) the data interval timespan is unique (i.e., has no overlap description cases)

6.2.8.12 In the event that the only difference between multiple maneuver time history data blocks is the selected maneuver composition (MAN\_COMPOSITION), reference frame (MAN\_REF\_FRAME) and/or maneuver orbit center (MAN\_CENTER\_NAME), the top-most depiction (i.e., the time history occurring first in the OCM) shall be adopted as the true or master depiction, and those subsequent data blocks shall be treated as containing derivative depictions provided purely for informational purposes.

6.2.8.13 The message creator shall specify the maneuver time history elements of information (MAN\_COMPOSITION) to follow the maneuver time tag (in absolute or relative time, as discussed above) on each maneuver time history line, stipulated in comma-delimited format from an ordered combination of the options shown in Table 6-8: composition

6.2.8.14 The MAN\_COMPOSITION keyword shall specify the elements of information to be provided on each maneuver time history line, which shall be selected from one or more elements of Table 6-8 (for thrust, acceleration, and/or velocity increments imparted by any/all thrusters and/or other perturbative forces) and Table 6-9 (for deployment-induced orbit changes). The order of these elements shall retain the ordering shown in Table 6-8 and Table 6-9, which are alphabetized by broad category but not by subcategory):

**Table 6-8: OCM Data: ~~Maneuver specification cases~~Selectable propulsive (i.e., non-deployment) maneuver fields in the maneuver time history data**

Keyword	Description	Unit	Examples of Values
<del>Maneuver Basis</del> MAN_IS_AD DITIVE Setting: DURA	The maneuver duration associated with this impulsive ΔV, thrust, and/or acceleration-imparted event.	s	200.0
ACC X	Acceleration component A <sub>x</sub> in the selected maneuver frame YES	<del>NO</del> km/s <sup>2</sup>	.01

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<u>Keyword</u>	<u>Description</u>	<u>Units</u>	<u>Examples of Values</u>
<u>CANDIDATE</u> <sub>ACC_Y</sub>	<b>Case 1</b> Acceleration component $A_y$ in the selected maneuver frame	<b>Case</b> km/s <sup>2</sup>	<u>.02</u>
<u>ACC_Z</u>	Acceleration component $A_z$ in the selected maneuver frame	km/s <sup>2</sup>	<u>.03</u>
<u>ACC_INTERP</u>	Acceleration vector Euler axis/angle interpolation mode between current and next acceleration line	n/a	<u>OFF</u> <u>ON</u>
<u>ACC_DMASS</u>	Additional mass change (where a negative number denotes a mass decrement/loss to the host) associated with this acceleration interval	kg	<u>-5.0</u>
<u>ACC_SIGMA</u>	One-sigma percent error on acceleration magnitude	%	<u>1.0</u>
<u>DV_X</u>	Velocity increment $\Delta V_x$ in the selected maneuver reference frame. The actual $\Delta V$ should be impulsively applied at a time of <time tag> + ½ (MAN_DURA).	km/s	<u>1.0</u>
<u>DV_Y</u>	Velocity increment $\Delta V_y$ in the selected maneuver reference frame. The actual $\Delta V$ should be impulsively applied at a time of <time tag> + ½ (MAN_DURA).	km/s	<u>2.0</u>
<u>PLANNED</u> <sub>DV_Z</sub>	Velocity increment $\Delta V_z$ in the selected maneuver reference frame. The actual $\Delta V$ should be impulsively applied at a time of <b>Case 3</b> <time tag> + ½ (MAN_DURA).	<b>Case</b> <b>4</b> [DLO] km/s	<u>3.0</u>
<u>DV_DMASS</u>	The mass change to the host (where a NEGATIVE VALUE denotes a mass decrement/loss) associated with this $\Delta V$ event	kg	<u>-1.0</u>
<u>DV_SIGMA</u>	One-sigma percent error on $\Delta V$ magnitude	%	<u>2.0</u>
<u>THR_X</u>	Thrust component $T_x$ measured in the selected maneuver reference frame	N	<u>1.0</u>
<u>THR_Y</u>	Thrust component $T_y$ measured in the selected maneuver reference frame	N	<u>2.0</u>
<u>THR_Z</u>	Thrust component $T_z$ measured in the selected maneuver reference frame	N	<u>3.0</u>
<u>ANTICIPATED</u> <sub>THR_DMASS</sub>	Additional mass change (where a negative number denotes a mass decrement/loss to the host) associated with this thrust interval, beyond the mass change already prescribed by the rocket equation <b>Case 5</b>	<b>Case</b> <b>6</b> kg	<u>-5.0</u>
<u>DETERMINED_TLM</u> <sub>THR EFFIC</sub>	<b>Case 7</b> Thrust efficiency "η" ranging between 0.0 and 1.0	<b>Case</b> <b>8</b> n/a	<u>0.95</u>
<u>DETERMINED_OD</u> <sub>THR_INTERP</sub>	<b>Case 9</b> Thrust vector Euler axis/angle interpolation mode between current and next thrust line; values shall be selected as either "OFF" or "ON".	<b>Case</b> <b>10</b> n/a	<u>OFF</u> <u>ON</u>
<u>THR_ISP</u>	Thrust specific impulse	s	<u>330.0</u>
<u>THR_SIGMA</u>	One-sigma percent error on thrust magnitude	%	<u>2.0</u>

~~6.2.8.13.1~~ The message recipient should exercise caution whenever maneuvers are additive (~~MAN\_IS\_ADDITIVE=YES~~), to prevent the unintentional accumulation of maneuver contributions across disparate maneuver basis values (~~MAN\_BASIS~~), orbit determination solutions (~~MAN\_OD\_ID~~), reference frames (~~MAN\_REF\_FRAME~~) or orbit centers (~~MAN\_CENTER\_NAME~~).

~~6.2.8.14~~ It is recommended that each maneuver data block be unique from all other maneuver data blocks in at least one of the following respects:

- ~~1) the thruster ID is different (THR\_ID)~~
- ~~2) the maneuver basis (MAN\_BASIS)~~
- ~~3) the maneuver is based upon a unique orbit determination, navigation solution or Monte Carlo simulation (e.g., MAN\_OD\_ID)~~
- ~~4) the reference frame is unique (MAN\_REF\_FRAME)~~
- ~~5) 1) the orbit center is unique (MAN\_CENTER\_NAME)~~
- ~~6) the data interval timespan is unique (i.e., has no overlap with any other data interval(s))~~

~~6.2.8.15~~ All maneuver events in the OCM shall be ~~time tagged by either a relative time~~ (e.g., DT=20157.26) measured in seconds with respect to the epoch time specified via the ~~MAN\_EPOCH\_TZERO~~ keyword (or default epoch in ~~DEF\_EPOCH\_TZERO~~ if ~~MAN\_EPOCH\_TZERO~~ is not specified), ~~or an absolute time~~ (e.g., T=2018-11-13T11:13:20.5Z as formatted in Section 7.5.9) epoch time.

~~6.2.8.16~~ The message creator shall specify the maneuver time history elements of information (~~MAN\_EOI~~) that follow the maneuver time tag (DT= or T= as discussed above) on each and every maneuver time history line, stipulated in comma-delimited format from any combination of the options shown in Table 6-9:

**Table 6-9: OCM Data: Selectable maneuverdeployment fields in the maneuver time history data**

Keyword	Description	Units	Examples of Values
MAN_DURA	The maneuver duration (0=impulsive; non-zero for $\Delta V$ , thrust and/or acceleration imparted event)	s	200.0
DV_X	Velocity increment $\Delta V_x$ in the selected maneuver reference frame. The actual $\Delta V$ should be impulsively applied at a time of $(DT= \text{or } T= \langle \text{time tag} \rangle + \frac{1}{2} (DV\_DUR))$ .	m/s	1.0
DV_Y	Velocity increment $\Delta V_y$ in the selected maneuver reference frame. The actual $\Delta V$ should be impulsively applied at a time of $(DT= \text{or } T= \langle \text{time tag} \rangle + \frac{1}{2} (DV\_DUR))$ .	m/s	2.0
DV_Z	Velocity increment $\Delta V_z$ in the selected maneuver reference frame. The actual $\Delta V$ should be impulsively applied at a time of $(DT= \text{or } T= \langle \text{time tag} \rangle + \frac{1}{2} (DV\_DUR))$ .	m/s	3.0
DV_SIGMA	One sigma percent error on $\Delta V$ magnitude	%	2.0
DV_DMSS	The mass change to the host (where a NEGATIVE VALUE denotes a mass decrement/loss) associated with this $\Delta V$ event	kg	-1.0
DEPLOY_ID	Free-text identifier of the resulting "child" object deployed from this host during TIME_SPAN. Setting DEPLOY_ID to zero "0" indicates that a deployment did not occur at this time tag.	n/a	CubeSat_001
DEPLOY_DV_X	Velocity increment $\Delta V_x$ of the deployed "child" object measured in the selected maneuver reference frame. The actual $\Delta V$ should be impulsively applied instantaneously at the time tag of $(DT= \text{or } T= \langle \text{time tag} \rangle + \frac{1}{2} (DV\_DUR))$ .deployment.	mkm/s	1.0
DEPLOY_DV_Y	Velocity increment $\Delta V_y$ of the deployed "child" object measured in the selected maneuver reference frame. The actual $\Delta V$ should be impulsively applied instantaneously at the time tag of $(DT= \text{or } T= \langle \text{time tag} \rangle + \frac{1}{2} (DV\_DUR))$ .deployment.	mkm/s	2.0
DEPLOY_DV_Z	Velocity increment $\Delta V_z$ of the deployed "child" object measured in the selected maneuver reference frame. The actual $\Delta V$ should be impulsively applied instantaneously at the time tag of $(DT= \text{or } T= \langle \text{time tag} \rangle + \frac{1}{2} (DV\_DUR))$ .deployment.	mkm/s	3.0
DEPLOY_MASS	MassDecrement in host mass as a result of the deployed "child" object post-deployment (shall be $\leq 0.0$ )	kg	-1.0
THR_ID	Thruster ID (non-negative integer number)	n/a	1
THR_X	Thrust component $T_x$ measured in the selected maneuver reference frame	N	1.0
THR_Y	Thrust component $T_y$ measured in the selected maneuver reference frame	N	2.0
THR_Z	Thrust component $T_z$ measured in the selected maneuver reference frame	N	3.0
THRDEPLOY_DV_SIGMA	One-sigma percent error on thrustdeployment $\Delta V$ magnitude	%	15.0

Keyword	Description	Units	Examples of Values
THR_INTERP	Thrust vector Euler axis/angle interpolation mode between current and next thrust line	n/a	OFF ON
THR_ISP	Thrust specific impulse	s	330.0
THR_EFFIC	Thrust efficiency “η” ranging between 0.0 and 1.0	n/a	0.95
THR_DMASSEXPLO DV_RATIO	Ratio of child-to-host ΔV vectors, such that:  $\overline{\Delta v}_{host} = \text{DEPLOY\_DV\_RATIO} \times \overline{\Delta v}_{child}$ <p>NOTE: Since an opposite ΔV direction typically occurs, <b>this number is typically less than or equal to zero</b>. This ratio allows the user to specify what ΔV impacts the host vehicle. This is usually not -1.0 (i.e. an equal-and-opposite imparted velocity), to account for the mass fraction between the child and the host as well as any rotational torque acted upon the host due to any offsets between the deployment direction centerline and the host’s center of gravity. Additional mass change (where a negative number denotes a mass decrement/loss to the host) associated with this thrust interval, beyond the mass change already prescribed by the rocket equation</p>	kgn/a	-5.0.05
DEPLOY DV CDAACC =X	Typical (50 <sup>th</sup> percentile) product of drag coefficient (Cd) times cross-sectional area for the deployed “child” object. Acceleration component Ax in the selected maneuver frame	m/s <sup>Δ**</sup> 2	0.022.01
ACC_Y	Acceleration component Ay in the selected maneuver frame	m/s <sup>Δ2</sup>	.02
ACC_Z	Acceleration component Az in the selected maneuver frame	m/s <sup>Δ2</sup>	.03
ACC_SIGMA	One sigma percent error on acceleration magnitude	%	1.0
ACC_INTERP	Acceleration vector Euler axis/angle interpolation mode between current and next acceleration line	n/a	OFF ON
ACC_DMASSE	Additional mass change (where a negative number denotes a mass decrement/loss to the host) associated with this acceleration interval	kg	-5.0

**6.2.8.14.1** Maneuver time history lines shall be confined to only one host/parent space object.

**6.2.8.15** Maneuver time history lines shall begin with the time tag of the start of the maneuver event (T<sub>start</sub>). Time tags may be specified as either a relative time (e.g., 20157.26) measured in seconds with respect to the epoch time specified via the EPOCH\_TZERO keyword or an absolute time (e.g., 2018-11-13T11:13:20.5Z as formatted in Section 7.5.10) epoch time.

**6.2.8.15.1** Within a single maneuver time history line, acceleration, impulsive ΔV, and thrust parameters shall not be additive, but rather shall be interpreted as alternate representations of the same underlying propulsive phenomenology. For this reason, impulsive ΔV events shall applied at a time tag of T<sub>start</sub> + ½ (MAN\_DURA).

NOTE 1: This interpretation requires that the time tag associated with each line applies to the start of the maneuver, and that impulsive ΔV representations in the propulsive representation (Table 6-8) need to be applied at a time tag of T<sub>start</sub> + ½ (MAN\_DURA).

NOTE 2: While one could artificially make  $T_{\text{start}}$  and the impulsive maneuver time be the same by setting MAN\_DURA equal to zero, this practice is discouraged because even when a maneuver is approximated by a  $\Delta V$  impulse, the duration of the maneuver is typically not zero, and the actual MAN\_DURA duration greatly aids in modeling and reconstructing the maneuver.

NOTE 3: Specification of a time history of **acceleration parameters** ACC\_X, ACC\_Y, and ACC\_Z allows modeling of both individual and aggregate maneuvers and any additional non-conservative perturbations that are not already specified in the “OCM Perturbations Specification” section or other maneuver time histories (including thrust/ $\Delta V$ /acceleration alternate portrayals). This allows the OCM originator to model and share the effects of maneuver and perturbations information without the OCM recipient needing to do such modeling.

NOTE 4: It is recommended that acceleration parameter portrayals of additional non-conservative perturbations avoid intermixing thrust or impulsive  $\Delta V$  alternate portrayals, since such thrust or  $\Delta V$  specifications on the same line may be inconsistent with the accompanying acceleration parameters.

**6.2.8.17.2.8.16** Specification of  **$\Delta V$  parameters** allows modeling of impulsive maneuvers, i.e., maneuvers where the space object’s velocity is instantaneously changed. ~~Importantly, note that such impulsive maneuvers can and should be accompanied by the duration of the actual maneuver if/when known.~~ Impulsive  $\Delta V$  events shall be applied at a time tag of  $T_{\text{start}} + \frac{1}{2} (\text{MAN\_DURA})$ .

~~**6.2.8.17.1** Maneuver time history lines shall be based upon only one host/parent space object.~~

~~**6.2.8.17.2** Associated with this single host, the mass and impulsive  $\Delta V$  of any deployed “child” objects of a parent/child deployment sequence may also be characterized in the OCM maneuver time history.~~

~~Such objects shall be identified by the Deployed Object Number (DON), a positive number starting at “1” and incrementing through all deployed objects until “N” objects have separated. NOTE: While such impulsive maneuvers are modeled as instantaneous velocity changes, they can and should be accompanied by the actual duration of the maneuver if/when known.~~

~~**6.2.8.17.3**~~

~~6.2.8.17.4 Where appropriate (e.g. with spring deployment mechanisms), the OCM creator shall provide both host and deployed object impulsive  $\Delta V$ s to model/incorporate both the child's deployment  $\Delta V$  as well as the retrograde  $\Delta V$  imparted to the host by the spring (e.g., as a ratio of the host and deployed object relative masses such that momentum is conserved).~~

~~6.2.8.18.16.2.8.16.1~~ Specification of **thrusting parameters** provides a finite burn capability. In the case of low-thrust, long-duration burns, sequential low-thrust interval maneuver lines can be used to reflect the evolution of the low-thrust maneuver thrust parameters.

~~6.2.8.18.16.2.8.16.2~~ Multiple thruster maneuver contributions mayshall only be represented as separate maneuver time history data blocks.

~~6.2.8.18.26.2.8.16.3~~ Thrust for any ~~thrusterpropulsive device~~ shall be presumed to be "OFF" until explicitly turned "ON" by setting one or more of that thruster's maneuver thrust components (THR\_X, THR\_Y, and/or THR\_Z) to a non-zero value.

~~6.2.8.18.36.2.8.16.4~~ Thrusters shall be "OFF" after the time surpasses  $[ T_{start} + MAN\_DURA ]$ . Thrusters may also be subsequently turned "OFF" by setting all of that thruster's maneuver thrust components to zero (i.e., THR\_X = THR\_Y = THR\_Z = 0.0).

~~6.2.8.16.5~~ The Thruster duty cycles may be specified using the thrusting maneuver specifications include the ability to specify duty cycles specification (DUTY\_CYCLE\_TYPE  $\neq$  CONTINUOUSNONE) based on either a reference direction or reference time. This duty cycle specification imposes cut-outs of non-thrusting periods onto the thrusting (finite burn) parameters to reflect the periods of duty cycle inactivity.

6.2.8.16.6 When a duty cycle is invoked, specification of the reference direction, reference time and any/all other duty cycle parameters relevant to that duty cycle type is mandatory.

6.2.8.16.7 Optionally, "DC\_MIN\_CYCLES" and "DC\_MAX\_CYCLES" may be specified to constrain the number of duty cycles performed. These parameters may override the duty cycle maneuver stop time (DC\_EXEC\_STOP).

~~6.2.8.18.4~~ NOTE 1: Relationships between such duty cycle parameters is described in ANNEX C, Section C3. ~~When a duty cycle is invoked, specification of the reference direction, reference time and any/all other duty cycle parameters relevant to that duty cycle type is mandatory. Optionally, "Minimum number of repeats" and "Maximum number of repeats" may be specified.~~

~~6.2.8.19~~ Specification of **acceleration parameters** allows aggregate modeling of both maneuvers and any additional non-conservative perturbations that are not already specified in the "OCM Perturbations Specification" section (above). This allows the OCM originator to model and share such maneuver and perturbations information without the OCM recipient needing to do such modeling. Note that since additional non-conservative perturbations are allowed, thrust or  $\Delta V$  specifications on the same line may be inconsistent with the accompanying acceleration parameters.

NOTE 2: The effects of using a pulse width modulation thruster controller can be accommodated by applying a reduced thrust level or by invoking the duty cycle parameters, or a combination thereof (being careful to avoid double-booking of thruster degradations).

**Table 6-10: OCM Data: Maneuver Specification**

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
MAN_START	Start of a maneuver data block specification	n/a			Yes
COMMENT	Comments (a contiguous set of one or more comment lines <del>are</del> allowed in the OCM Maneuver Specification only immediately after the MAN_START key word; see 7.7 for comment formatting rules).	n/a		<del>COMMENT</del> This is a comment	No
MAN_ID	Optional alphanumeric free-text string containing the identification number for this maneuver	n/a		E_W_20160305B	No
<del>MAN_OD_ID</del>	<del>Optional alphanumeric free-text string containing the identification number of the orbit determination upon which this maneuver data is based</del>	<del>n/a</del>		<del>OD_20181122A</del>	<del>No</del>
<del>MAN_BASIS</del>	<del>Basis of this maneuver time history data, which shall be selected from one of the following values: 1. "CANDIDATE" for a proposed operational or a hypothetical (i.e., mission design and optimization studies) future maneuver 2. "PLANNED" for a currently planned future maneuver 3. "ANTICIPATED" for a non-cooperative future maneuver that is anticipated (i.e. likely) to occur 4. "DETERMINED_TLM" when a past maneuver is determined from propulsion and attitude system telemetry in near-real-time for reconstruction 5. "DETERMINED_OD" when a past maneuver is estimated from observation-based orbit determination reconstruction and/or calibration.</del>	<del>n/a</del>	<del>PLANNED</del>	<del>DETERMINED_TLM CANDIDATE</del>	<del>No</del>
<del>MAN_IS_ADDITIVE</del>	<del>Specifies (by either YES or NO) whether this maneuver is additive with other specified time-overlapping maneuvers when they share the same maneuver basis (MAN_BASIS). Note that if "NO" is selected, such time-overlapping maneuvers are to be interpreted as being multiple approaches to characterize the same composite (total) maneuver profile.</del>	<del>n/a</del>	<del>NO</del>	<del>YES NO</del>	<del>Yes (defaults to "NO")</del>
MAN_PREV_ID	Optional alphanumeric free-text string containing the identification number of the previous maneuver for this MAN_BASIS. Note: if the message is not part of a sequence of maneuver messages or if this maneuver is the first in a sequence of maneuvers, then MAN_PREV_ID should be excluded from this message.	n/a		E_W_20160305A	No

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	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
MAN	<u>PREV_TIME</u>	Identifies the completion time of the previous maneuver for this MAN_BASIS. This time may be specified as either “ <u>DT-YYY</u> ”, where “ <u>YYY</u> ” contains relative time in seconds (relative to MAN_EPOCH_TZERO if specified or DEF_EPOCH_TZERO if not), or “ <u>T-&lt;epoch&gt;</u> ” (see 7.5.10 for formatting rules.)	n/a		<u>DT=50.0</u> <u>T=2001-11-06T11:17:33</u> <u>T=2002-204T15:56:23Z</u>	<u>No</u>
MAN	<u>NEXT_ID</u>	Optional alphanumeric free-text string containing the identification number of the next maneuver for this MAN_BASIS. Note: if the message is not part of a sequence of maneuver messages or if this maneuver is the last in a sequence of maneuvers, then MAN_NEXT_ID should be excluded from this message.	n/a		<u>E_W_20160305C</u>	<u>No</u>
MAN	<u>BASIS</u>	Basis of this maneuver time history data, which shall be selected from one of the following values: 1. “ <u>CANDIDATE</u> ” for a proposed operational or a hypothetical (i.e., mission design and optimization studies) future maneuver 2. “ <u>PLANNED</u> ” for a currently planned future maneuver 3. “ <u>ANTICIPATED</u> ” for a non-cooperative future maneuver that is anticipated (i.e. likely) to occur (e.g., based upon patterns-of-life analysis). 4. “ <u>DETERMINED TLM</u> ” when a past maneuver is determined from propulsion and attitude system telemetry in near-real-time for reconstruction 5. “ <u>DETERMINED OD</u> ” when a past maneuver is estimated from observation-based orbit determination reconstruction and/or calibration.	n/a	<u>PLANNED</u>	<u>DETERMINED TLM CANDIDATE</u>	<u>No</u>
MAN	<u>OD_ID</u>	Optional alphanumeric free-text string containing the identification number of the orbit determination upon which this maneuver data is based	n/a		<u>OD_20181122A</u>	<u>No</u>
MAN	<u>DEVICE_ID</u>	MANDATORY Alphanumeric free-text string containing the maneuver device ID identifier used for this maneuver. “ALL” indicates that this maneuver represents the summed acceleration (or velocity increment) imparted by any/all thrusters utilized in the maneuver.	n/a		<u>ALL</u> <u>THR_02</u> <u>DEPLOYMENT</u>	<u>Yes</u>
MAN	<u>IS_ADDITIVE</u>	Specifies (by either YES or NO) whether this maneuver is additive with other specified time-overlapping maneuvers <b>when they share the same maneuver basis (MAN BASIS)</b> . If “YES”, then this maneuver is combined with all other maneuvers where MAN_IS_ADDITIVE is set to “YES”. Note that if “NO” is selected, such time-overlapping maneuvers are to be interpreted as being multiple approaches to characterize the same composite (total) maneuver profile.	n/a	<u>NO</u>	<u>YES</u> <u>NO</u>	<u>Yes (defaults to “NO”)</u>

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	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
MAN	<u>PREV_TIME</u>	Identifies the completion time of the previous maneuver for this MAN BASIS. This time may be specified as either “YYY”, where “YYY” contains relative time in seconds (relative to EPOCH_TZERO), or “<epoch>” (see 7.5.10 for formatting rules.).	n/a		50.0 2001-11-06T11:17:33 2002-204T15:56:23Z	No
MAN	<u>NEXT_TIME</u>	Identifies the start time of the next maneuver for this MAN BASIS. This time may be specified as either “DT=YYY”, where “YYY” contains relative time in seconds (relative to MAN_EPOCH_TZERO if specified), or DEF_EPOCH_TZERO if not), or “T=<epoch>” (see 7.5.10 for formatting rules.).	n/a		<del>DT</del> =50.0 T=2001-11-06T11:17:33 T=2002-204T15:56:23Z	No
MAN	<u>PURPOSE</u>	The user can specify the intention(s) of the maneuver. Multiple maneuver purposes can be provided as a comma-delimited list. While there is no CCSDS-based restriction on the value for this free-text keyword, it is suggested to use: Aerobraking -(AEROBRAKE), Attitude adjust ( <u>ATT_ADJUSTATTITUDE</u> ) Collision avoidance (COLA) Deployment (DEPLOY) Disposal (DISPOSAL) Gravity assist flyby <del>targeting</del> (GRAV_ASSIST_FROM XXXX, where XXXX=body center name, e.g.SANA Registry [12]) <u>Inclination adjustment (INCLINATION)</u> Launch & Early Orbit (LEOP) Maneuver cleanup -(MNVR_CLEANUP) Mass adjust (MASS_ADJUST) Momentum desaturation (MOM_DESAT) Orbit adjust -(ORBIT_ADJUST) Orbit trim -(TRIM) Other (OTHER) Period adjustment -(PERIOD_ADJ) Pointing Request Message (PRM_ID_xxxx) Relocation (RELOCATION) Science objective (SCI_OBJ) Spin rate adjust (SPIN_RATE_ADJUST) Station-keeping (SK) Trajectory correction -(TRAJ_CORR)	n/a		DISPOSAL	No
MAN	<u>EOICOMPOSITION</u>	The comma-delimited ordered set of maneuver elements of information to follow the maneuver time tag (DT=relative or T=absolute time, as discussed above) on every maneuver time history line, with elements of information as listed in values selected from Table 6-2, 8-1 or Table 6-9.	n/a		<del>THR_ID</del> ,THR_X, THR_Y, THR_Z, THR_ISP, THR_EFFIC, THR_DMSS, DV_X, DV_Y, DV_Z	Yes
MAN	<u>PRED_SOURCE</u>	For future maneuvers, specifies the source of the orbit and/or attitude state(s) upon which the maneuver is based. While there is no CCSDS-based restriction on the value for this free-text keyword, it is suggested to consider using ORB_ID and OD_ID keywords as described in Tables 6-4 and 6-1011 respectively, or a combination thereof.	n/a		OD_5	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
MAN_CENTER_NAME		<p><del>Origin of the maneuver central body</del><u>reference frame</u>, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, or another <u>reference frame center (such as a spacecraft. See, ground station, formation flying reference “chief” spacecraft, etc.).</u></p> <p><u>Natural bodies shall be selected from the accepted set of values indicated in ANNEX B, Section B2, for acceptable values (and the procedure B2.</u></p> <p><u>For spacecraft, it is recommended to propose new values): use either the Object name or international designator of the participant as catalogued in the UN Office of Outer Space Affairs designator index (reference [2]). Alternately, the OBJECT DESIGNATOR may be used.</u></p> <p><u>For other reference frame origins, this field is a free text descriptor which can draw upon ground station name, etc.</u></p>	n/a	EARTH	<p>EARTH MOON SOLAR SYSTEM BARYCENTER SUN ISS EROS EARTH_SUN_L2</p>	No
MAN_EPOCH_TZERO		<p><del>Reference epoch for all relative times in the maneuver time history block. See 7.5.10 for formatting rules. The time system of MAN_EPOCH_TZERO may be set per Annex B, Section B3 via the “MAN_TIME_SYSTEM” keyword.</del></p>	§7.5.9	<DEF_EPOCH_TZERO>	2001-11-06T11:17:33	No
MAN_TIME_SYSTEM		<p><del>Timing system of MAN_EPOCH_TZERO, selected per Annex B, Section B3.</del></p>	n/a	<DEF_TIME_SYSTEM>	UTC UT1	No
MAN_REF_FRAME		<p>Reference frame in which the maneuver vector direction data is provided, if not intrinsic to the definition of the maneuver data. Select from the accepted set of values indicated in <u>ANNEX B, Section B4 (and note the procedure to propose a new value, if this set of existing ANNEX B values does not accommodate your particular use case). ANNEX B, Section B4.</u> The reference frame must be the same for all data elements within a given Maneuver Time History block.</p>	n/a	TNW	J2000	No
MAN_FRAME_EPOCH		<p>Epoch of the maneuver data reference frame, if not intrinsic to the definition of the reference frame. See 7.5.10 for formatting rules.</p>	§7.5.9n/a		2001-11-06T11:17:33 2002-204T15:56:23Z	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
GRAV	ASSIST_NAME	Origin of maneuver gravitational assist body, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, <del>or another spacecraft.</del> See ANNEX BANEX B, Section B2B2, for acceptable <u>CENTERGRAV_ASSIST_NAME</u> values (and the procedure to propose new values).	n/a	EARTH	EARTH MOON SOLAR SYSTEM BARYCENTER SUN <del>ISS</del> EROS EARTH_SUN_L2	No
DUTY	CYCLE_TYPE	Specifies the type of duty cycle type to use for <del>these</del> <u>this</u> maneuver time history section: <ul style="list-style-type: none"> <li><del>NONE</del><u>CONTINUOUS</u> denotes full/continuous thrust;</li> <li>TIME denotes a time-based duty cycle driven by time past a reference time and the duty cycle ON and OFF durations;</li> <li><del>PHASE_ANGLE</del> denotes a duty cycle driven by the phasing/clocking of a space object body frame “trigger” direction past a reference direction</li> <li><del>CONE_ANGLE</del> denotes a duty cycle driven by the passage of a space object body frame “trigger” direction past ON and OFF conical angles about a reference direction.</li> </ul>	n/a	<del>NONE</del> <u>CONTINUOUS</u>	<del>NONE</del> <u>CONTINUOUS</u> TIME PHASE_ANGLE <u>CONE_ANGLE</u>	No
DC_WIN	OPEN	For ALL duty cycle types, specifies the start time of the duty cycle-based maneuver window that occurs on or prior to the actual maneuver execution start time. For example, this may identify the time at which the satellite is first placed into a special duty-cycle-based maneuver mode.  This start time may be specified as either “ <del>DT=YYY</del> ”, where “YYY” contains relative time in seconds (relative to <u>MAN_EPOCH_TZERO</u> if specified, or <u>DEF_EPOCH_TZERO</u> if not), or “ <del>T=&lt;“&lt;epoch&gt;</del> ” (see 7.5.10 for formatting rules. <del>);</del> ).  <del>Note 1: DC_WIN_OPEN</del> <u>This value</u> is mandatory if DUTY_CYCLE_TYPE <del>≠ NONE</del> <u>≠ “CONTINUOUS”</u> .	n/a		<del>DT=50.0</del> <u>T=2001-11-06T11:17:33</u> <u>T=2002-204T15:56:23Z</u>	<del>(see Note 1)</del> <u>No</u>
DC_WIN	CLOSE	Specifies the end time of the duty cycle-based maneuver window that occurs on or after the actual maneuver execution end time. For example, this may identify the time at which the satellite is taken out of a special duty-cycle-based maneuver mode.  This end time may be specified as either “ <del>DT=YYY</del> ”, where “YYY” contains relative time in seconds (relative to <u>MAN_EPOCH_TZERO</u> if specified, or <u>DEF_EPOCH_TZERO</u> if not), or “ <del>T=&lt;“&lt;epoch&gt;</del> ” (see 7.5.10 for formatting rules. <del>);</del> ).  <del>Note 1: DC_WIN_CLOSE</del> <u>This value</u> is mandatory if DUTY_CYCLE_TYPE <del>≠ NONE</del> <u>≠ “CONTINUOUS”</u> .	n/a		<del>DT=100.0</del> <u>T=2001-11-07T51:17:33</u> <u>T=2002-204T15:58:03Z</u>	<del>(see Note 1)</del> <u>No</u>

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
DC_MIN_CYCLES		<p>Minimum number of "ON" duty cycles (may override <u>MAN_WIN_CLOSE</u>).</p> <p>Note 1: <u>DC_WIN_CLOSE</u> is mandatory if <u>DUTY_CYCLE_TYPE</u> ≠ <u>NONEDC_EXEC_STOP</u>.</p>	DCsn /a	0	5	No (has default value of "0") No
DC_MAX_CYCLES		<p>Maximum number of "ON" duty cycles (may override <u>MAN_WIN_CLOSE</u>).</p> <p>Note 1: <u>DC_WIN_CLOSE</u> is mandatory if <u>DUTY_CYCLE_TYPE</u> ≠ <u>NONEDC_EXEC_STOP</u>. A value of zero disables this limit.</p>	DCsn /a	(unlimited)	5200	No (defaults to no limiting value) No
DC_EXEC_BEGINSTART		<p>(Provided for informational purposes only): The actual specified start time of the initial duty cycle-based maneuver sequence execution. <u>DC_EXEC_BEGIN</u> occurs <u>START</u> is defined to occur on or prior to the first maneuver "ON" portion within the duty cycle sequence. <u>DC_EXEC_START</u> must occur coincident with or after <u>DC_WIN_OPEN</u>.</p> <p>This maneuver execution start time may be specified as either "<u>DT=YYY</u>", where "YYY" contains relative time in seconds (relative to <u>MAN_EPOCH_TZERO</u> if specified or <u>DEF_EPOCH_TZERO</u> if not), or "<u>T=&lt;epoch&gt;</u>" (see 7.5.10 for formatting rules.).</p> <p>This value is mandatory if <u>DUTY_CYCLE_TYPE</u> ≠ "<u>CONTINUOUS</u>".</p>	n/a		<p><u>DT</u>=50.0  <u>T</u>=2001-11-06T11:17:33  <u>T</u>=2002-204T15:56:23Z</p>	No
DC_EXEC_ENDSTOP		<p>(Provided for informational purposes only): The actual specified end time of the final duty cycle-based maneuver sequence execution. <u>DC_EXEC_END_STOP</u> typically occurs on or after the end of the final maneuver "ON" portion within the duty cycle sequence. <u>DC_EXEC_STOP</u> occurs prior to or coincident with <u>DC_WIN_CLOSE</u>.</p> <p>This maneuver execution end time may be specified as either "<u>DT=YYY</u>", where "YYY" contains relative time in seconds (relative to <u>MAN_EPOCH_TZERO</u> if specified or <u>DEF_EPOCH_TZERO</u> if not), or "<u>T=&lt;epoch&gt;</u>" (see 7.5.10 for formatting rules.).</p> <p>This value is mandatory if <u>DUTY_CYCLE_TYPE</u> ≠ "<u>CONTINUOUS</u>".</p>	n/a		<p><u>DT</u>=100.0  <u>T</u>=2001-11-07T51:17:33  <u>T</u>=2002-204T15:58:03Z</p>	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
	DC_REF_TIME	<p>Specifies the THRUST duty cycle “on” reference time tag <u>specified as</u> either as “DT=“YYY”, where “YYY” contains relative time in seconds (relative to <u>MAN_EPOCH_TZERO if specified</u>), or <u>DEF_EPOCH_TZERO if not</u>), or “T=&lt;“&lt;epoch&gt;”&gt;” (see 7.5.10 for formatting rules).</p> <p>Note 1: DC_REF_TIME is mandatory if DUTY_CYCLE_TYPE is set to “TIME”</p> <p>Note 2: Depending upon the EPOCH_TZERO definition, DC_REF_TIME relative times may be negative.</p> <p>This value is mandatory if DUTY_CYCLE_TYPE ≠ “CONTINUOUS”.</p>	sn/a		<p><del>DT</del>=8000.0 T=2001-11-06T11:17:33</p>	(see Note 1) <u>No</u>
	DC_ON_DURATIME PULSE DURATION	<p>For time-based thruster duty cycle (DUTY_CYCLE_TYPE=TIME), specifies <u>duty cycle thruster pulse</u> “ON” duration, initiated at first satisfaction of the burn “ON” time <u>or phase angle constraints or at constraint or upon</u> completion of a Duty Cycle “OFF” duration (in seconds).</p> <p>Note 1: <u>the previous</u> DC_ON_DURATIME_PULSE_PERIOD cycle.</p> <p>This value is mandatory if DUTY_CYCLE_TYPE is set to “TIME” ≠ “CONTINUOUS”.</p>	s		200 <u>10</u> .0	(see Note 1) <u>No</u>
	DC_OFF_DURATIME PULSE PERIOD	<p>For time-based thruster duty cycle (DUTY_CYCLE_TYPE=TIME), specifies <u>duty cycle</u> “OFF” duration, <u>initiated at the completion the elapsed time between the start of a burn “ON” duration one pulse and the start of the next. Must be greater than</u> or upon a phase angle constraint violation.</p> <p>Note 1: <u>equal to</u> DC_OFF_DURATIME_PULSE_DURATION.</p> <p>This value is mandatory if DUTY_CYCLE_TYPE is set to “TIME” ≠ “CONTINUOUS”.</p>	s		200.0	(see Note 1) <u>No</u>
	DC_REF_DIR	<p>For phase angle <u>or cone based</u> thruster duty cycles (DUTY_CYCLE_TYPE=PHASE_ANGLE or <u>CONE_ANGLE</u>), specifies the “ON” reference unit vector direction in the “MAN_REF_FRAME” reference frame (i.e., the <u>start</u> of the duty cycle “ON” and <u>NOT</u> the duty cycle midpoint).</p> <p>Note 1: DC_REF_DIR This value is mandatory if DUTY_CYCLE_TYPE is set to “PHASE_ANGLE” or “CONE_ANGLE”.</p>	n/a		1.0 0.0 0.0	(see Note 1) <u>No</u>

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
DC_BODY_TRIGGER	Specifies the body frame reference unit vector direction which, when <del>it clocks past the</del> <u>projection is aligned with the projection</u> DC_REF_DIR direction, initiates thrusting <u>when both are projected into the spin plane.</u>  <u>Note 1: DC_BODY_TRIGGER</u> This value is mandatory if DUTY_CYCLE_TYPE is set to <u>"PHASE_ANGLE"</u> or <u>"CONE_ANGLE"</u> .	n/a		.707 0.0 .707	<del>(see Note 1)</del> <u>No</u>
DC_PA_START_ANGLE	<del>Thrust phase angle start.</del>  <u>Note 1: DC_PA_START</u> Phase angle offset of thruster pulse start, measured with respect to the occurrence of a DC_BODY_TRIGGER crossing of the DC_REF_DIR direction when both are projected into the spin plane (normal to the body spin axis). <u>DC_PA_START can be positive or negative to allow the duty cycle to begin prior to the next crossing of the DC_REF_DIR.</u> As this angular direction is to be used in a modulo sense, there is no requirement for the magnitude of DC_PA_START to be less than 360.  <u>This value</u> is mandatory if DUTY_CYCLE_TYPE is set to <u>"PHASE_ANGLE"</u> .	deg		25.0	<del>(see Note 1)</del> <u>No</u>
DC_PA_STOP_ANGLE	<del>Thrust phase angle stop.</del>  <u>Note 1: DC_PA_STOP</u> Phase angle of thruster pulse stop, measured with respect to the DC_BODY_TRIGGER crossing of the DC_REF_DIR direction when both are projected into the spin plane. <u>DC_PA_STOP can be positive or negative to allow the duty cycle to end after to the next crossing of the DC_REF_DIR.</u> As this angular direction is to be used in a modulo sense, there is no requirement for the magnitude of DC_PA_STOP to be less than 360.  <u>This value</u> is mandatory if DUTY_CYCLE_TYPE is set to <u>"PHASE_ANGLE"</u> .	deg		35.0	<del>(see Note 1)</del> <u>No</u>
DC_CONE_ON	<del>Thrust conical angle start.</del>  <u>Note 1: DC_CONE_ON</u> is mandatory if DUTY_CYCLE_TYPE is set to <u>"CONE_ANGLE"</u>	deg		35.0	<del>(see Note 1)</del>
DC_CONE_OFF	<del>Thrust conical angle stop.</del>  <u>Note 1: DC_CONE_OFF</u> is mandatory if DUTY_CYCLE_TYPE is set to <u>"CONE_ANGLE"</u>	deg		35.0	<del>(see Note 1)</del>
... < Insert maneuver lines here >	<b>Maneuver time history data/content shall be provided as specified in sections 6.2.8.16 described above.</b>				Yes
MAN_STOP	End maneuver data block specification	n/a			Yes

**6.2.9 OCM DATA: PERTURBATIONS SPECIFICATION**

**6.2.9.1** Table 6-510 provides an overview of the OCM Perturbations Specification section. Only those keywords shown in Table 6-510 shall be used in OCM perturbations specification.

~~6.2.9.2~~ Keyword values shall be provided in the units specified in the “Units” column of Table 6-5.

~~6.2.9.3~~ The order of occurrence of these OCM Perturbations Specification keywords shall be fixed as shown in Table 6-5.

~~6.2.9.4~~ The OCM Perturbations Specification section is optional; “mandatory” in the context of Table 6-5 denotes those keywords which must be included in this section if this section is included.

~~6.2.9.5~~6.2.9.2 Only one OCM Perturbations Specification section shall appear in an OCM.

~~6.2.9.6~~6.2.9.3 The OCM Perturbations Specification section shall be delimited by two keywords: PERT\_START and PERT\_STOP.

6.2.9.4 The gravity model (GRAVITY\_MODEL) degree (D) and order (O) of the spherical harmonic coefficients applied should be given along with the name of the model. Note that specifying a zero value for “order” (i.e. 2 0) denotes zonals (J2 ... JD) only.

**Table 6-11: OCM Data: Perturbations Specification**

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
PERT_START	Start of the perturbations specification	n/a			Yes

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
	COMMENT	Comments (a contiguous set of one or more comment lines <del>are</del> allowed in the OCM Perturbations Specification only immediately after the PERT_START key word; see 7.7 for comment formatting rules).	n/a		<del>COMMENT</del> -This is a comment	No
	<del>PERT</del> ORBIT_CENTER_NAME	<p>Origin of the perturbations central bodies, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, <del>or another spacecraft.</del> Select from the accepted set of values indicated in <del>ANNEX B</del> ANNEX B, Section <del>B2</del> (and note B2).</p> <p><del>Origin of the procedure to propose perturbing central bodies, which may be a new value, if this natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter.</del></p> <p><del>Natural bodies shall be selected from the accepted set of existing ANNEX B values does not accommodate your particular use case)-indicated in ANNEX B, Section B2.</del></p> <p><del>For other reference frame origins, this field is a free text descriptor which can draw upon ground station name, etc.</del></p>	n/a	EARTH	EARTH MOON SOLAR SYSTEM BARYCENTER SUN <del>SS</del> EROS EARTH_SUN_L2	No
	ATMOSPHERIC_MODEL	Name of atmosphere model. <del>This is a free text field [DLO3], so if, which shall be selected from the examples on the right are insufficient, others may be used.</del> accepted set of values indicated in ANNEX B, Section <del>B9</del> B9.	n/a		MSISE90 NRLMSIS00 J70 J71 <del>JRob</del> JROBERTS DTM JB2008 ...	No
	GRAVITY_MODEL	<del>The name of the geopotential model for central body, followed by the degree and order of the spherical harmonic coefficients applied. Note that specifying a zero value for “order” (i.e. The gravity model used in the simulation, which shall be selected from the accepted set of values indicated in ANNEX B, Section B10. 2 0) denotes zonals (J<sub>2</sub>-J<sub>n</sub>) only. This is a free text field [DLO4], so if the examples on the right are insufficient, others may be used.</del>	n/a		EGM-96- <del>36 36</del> WGS-84- <del>8 8</del> GGM-01- <del>12 12</del> TEG-4- <del>8 2</del>	No
	GRAVITY_MODEL_DEGREE	<del>The GRAVITY_MODEL degree used in the simulation.</del>	n/a		<del>36</del> <del>12</del> <del>8</del>	<del>No</del>
	GRAVITY_MODEL_ORDER	<del>The GRAVITY_MODEL order used in the simulation.</del>	n/a		<del>36</del> <del>12</del> <del>2</del>	<del>No</del>

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
EQUATORIAL_RADIUS		Oblate spheroid equatorial radius	<u>mkm</u>		<u>6378137.06378.137</u>	No
GM		Gravitational Coefficient of attracting body (Gravitational Constant x Central Mass)	km**3 /s**2		3.986004e5	No
N_BODY_PERTURBATIONS		One <b>OR MORE</b> (N-body) gravitational perturbations bodies used. Values, listed serially in comma-delimited fashion, denote a natural solar or extra-solar system body (stars, planets, asteroids, comets, and natural satellites), <del>or another spacecraft.</del> Note that only those entries (or those procedurally added to the CENTER_NAME content as specified in <u>ANNEX B</u> <del>ANNEX B</del> ) that are denoted as an “ <b>Attracting Body</b> ” in <u>ANNEX B</u> <del>ANNEX B</del> , Section <u>B2B2</u> are acceptable values.	n/a		MOON, SUN, JUPITER	No
CENTRAL_BODY_ROTATION	<u>ROTATION</u>	Central body angular rotation rate, measured about the major principal axis of the inertia tensor of the central body, relating inertial and central-body-fixed reference frames.	deg/s		4.17807421629e-3	No
OBLATE_FLATTENING		Inverse of the central body’s oblate spheroid oblateness for the polar-symmetric oblate central body model.	n/a		298.257223563	No
OCEAN_TIDES_MODEL		Name of ocean tides model (optionally specify order or constituent effects, diurnal, semi-diurnal, etc.)	n/a		DIURNAL SEMI-DIURNAL	No
SOLID_TIDES_MODEL		Name of solid tides model (optionally specify order or constituent effects, diurnal, semi-diurnal, etc.)	n/a		DIURNAL SEMI-DIURNAL	No
REDUCTION_THEORY		Specification of the reduction theory used for precession and nutation modeling. This is a free text field, so if the examples on the right are insufficient, others may be used.	n/a		IAU1976/FK5 IAU2010 IERS1996	No
ALBEDO		Name of the albedo model	n/a		STK	No
ALBEDO_GRID_SIZE		# of grid points used in the albedo model	n/a		100	No
SHADOW_MODEL		Shadow modeling for Solar Radiation Pressure; dual cone uses both umbra/penumbra regions. Selected option should be one of “NONE”, “CYLINDRICAL”, <u>“CONE”</u> or “DUAL CONE”	n/a		NONE CYLINDRICAL DUAL CONE	No
SHADOW_BODIES		Comma-separated list of planetary bodies for which SRP shadowing is modeled. See <u>ANNEX B</u> <del>ANNEX B</del> for acceptable <u>PERTORBIT_CENTER_NAME</u> values (and the procedure to propose new values).	n/a	Earth	Earth, Moon	No
SRP_MODEL		Name of SRP model. This is a free text field, so if the examples on the right are insufficient, others may be used.	n/a		GPS_ROCK BOX_WING CANNONBALL COD ...	No
SPACE_WXSW_SOURCE		Free text field specifying the source and version of the Space Weather data used in the creation of this message. Multiple space weather sources can be specified in a comma-delimited fashion.	n/a		e.g., “Celestrak space weather file downloaded from <a href="http://celestrak.com/SpaceData/SW-Last5Years.txt">http://celestrak.com/SpaceData/SW-Last5Years.txt</a> <a href="http://celestrak.com/SpaceData/SW-Last5Years.txt">http://celestrak.com/SpaceData/SW-Last5Years.txt</a> at 2001-11-08T00:00:00”	No

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
INTERP_METHOD_SPWX		Free text field specifying the method used to select or interpolate any and all sequential space weather data ( $K_p$ , $a_p$ , $Dst$ , $F_{10.7}$ , $M_{10.7}$ , $S_{10.7}$ , $Y_{10.7}$ , etc.)	n/a		PRECEDING_VALUE NEAREST_NEIGHBOR LINEAR LAGRANGE_ORDER_5	No
FIXED_GEOMAG_KP		A fixed (time invariant) value of the planetary 3-hour-range geomagnetic index $K_p$ used to override the normal time-varying 3-hourly $K_p$ values (e.g., obtained from <a href="#">SPACE_WXSW_SOURCE</a> ) for drag perturbations estimation throughout this message's timespan.  $K_p$ is the planetary 3-hour-range mean standardized index derived from the K-index of 13 geomagnetic observatories between 44 degrees and 60 degrees northern or southern geomagnetic latitude. The scale is 0 to 9 expressed in thirds of a unit, e.g. 5- is $4 \frac{2}{3}$ , 5 is 5 and 5+ is $5 \frac{1}{3}$ . This planetary index is designed to measure solar particle radiation by its magnetic effects.	nT		3.2	No
FIXED_GEOMAG_AP		A fixed (time invariant) value of the 3-hourly (equivalent range) geomagnetic index $a_p$ used to override the normal time-varying 3-hourly $a_p$ values (e.g., obtained from <a href="#">SPACE_WXSW_SOURCE</a> ) for drag perturbations estimation throughout this message's timespan.  The 3-hourly (equivalent range) geomagnetic index $a_p$ reports the amplitude of planetary geomagnetic activity for a given day and is translated from the $K_p$ index.	nT		21	No
FIXED_GEOMAG_DST		A fixed (time invariant) value of the planetary 1-hour-range geomagnetic index $Dst$ used to override the normal time-varying daily $Dst$ values (e.g., obtained from <a href="#">SPACE_WXSW_SOURCE</a> ) for drag perturbations estimation throughout this message's timespan.  The Disturbance Storm Time ( $Dst$ ) index is a proxy for magnetic activity derived from a network of near-equatorial geomagnetic observatories that measures the intensity of the globally symmetrical equatorial electrojet (the storm-time "ring current" in the inner magnetosphere).	nT		-20	No
FIXED_F10P7		A fixed (time invariant) value of the solar flux daily proxy $F_{10.7}$ used to override the normal time-varying daily $F_{10.7}$ values (e.g., obtained from <a href="#">SPACE_WXSW_SOURCE</a> ) for drag perturbations estimation throughout this message's timespan.	Solar Flux Units = $10^4$ Jansky = $10^{-22}$ W/( <del>m</del> <sup>2</sup> <del>m</del> <sup>**2</sup> Hz)		120.0	No

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	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
FIXED	F10P7_MEAN	A fixed (time invariant) value of the solar flux 81-day running center-averaged proxy $F_{10.7}$ used to override the normal time-varying averaged $F_{10.7}$ values (e.g., obtained from <a href="#">SPACE_WXSW</a> SOURCE) for drag perturbations estimation throughout this message's timespan.	Solar Flux Units = $10^4$ Jansky = $10^{-22}$ W/(m <sup>2</sup> *Hz)		132.0	No
FIXED	M10P7	A fixed (time invariant) value of the solar flux daily proxy $M_{10.7}$ used to override the normal time-varying daily $M_{10.7}$ values (e.g., obtained from <a href="#">SPACE_WXSW</a> SOURCE) for drag perturbations estimation throughout this message's timespan.  $M_{10.7}$ is derived from the Mg II core—o—wing ratio that originated from the NOAA series operational satellites, e.g., NOAA—16,—, NOAA-17,—, NOAA-18, which host the Solar Backscatter Ultraviolet (SBUV) spectrometer	$10^{-22}$ W/(m <sup>2</sup> *Hz)		120.0	No
FIXED	M10P7_MEAN	A fixed (time invariant) value of the solar flux 81-day running center-averaged proxy $M_{10.7}$ used to override the normal time-varying averaged $M_{10.7}$ values (e.g., obtained from <a href="#">SPACE_WXSW</a> SOURCE) for drag perturbations estimation throughout this message's timespan.	$10^{-22}$ W/(m <sup>2</sup> *Hz)		120.0	No
FIXED	S10P7	A fixed (time invariant) value of the solar flux daily proxy $S_{10.7}$ used to override the normal time-varying daily $S_{10.7}$ values (e.g., obtained from <a href="#">SPACE_WXSW</a> SOURCE) for drag perturbations estimation throughout this message's timespan.  $S_{10.7}$ is the integrated 26–34 nm solar irradiance measured by the Solar Extreme Ultraviolet Monitor (SEM) instrument on the NASA/ESA Solar and Heliospheric Observatory (SOHO) research satellite	$10^{-22}$ W/(m <sup>2</sup> *Hz)		120.0	No
FIXED	S10P7_MEAN	A fixed (time invariant) value of the solar flux 81-day running center-averaged proxy $S_{10.7}$ used to override the normal time-varying averaged $S_{10.7}$ values (e.g., obtained from <a href="#">SPACE_WXSW</a> SOURCE) for drag perturbations estimation throughout this message's timespan.	$10^{-22}$ W/(m <sup>2</sup> *Hz)		120.0	No
FIXED	Y10P7	A fixed (time invariant) value of the solar flux daily proxy $Y_{10.7}$ used to override the normal time-varying daily $Y_{10.7}$ values (e.g., obtained from <a href="#">SPACE_WXSW</a> SOURCE) for drag perturbations estimation throughout this message's timespan.  $Y_{10.7}$ is a composite index of the $X_{b10}$ and Lyman- $\alpha$ solar indices, weighted to represent mostly $X_{b10}$ during solar maximum and to represent mostly Lyman- $\alpha$ during moderate and low solar activity.	$10^{-22}$ W/(m <sup>2</sup> *Hz)		120.0	No

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	Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
FIXED	Y10P7_MEAN	A fixed (time invariant) value of the solar flux 81-day running center-averaged proxy $Y_{10.7}$ used to override the normal time-varying averaged $Y_{10.7}$ values (e.g., obtained from <u>SPACE_WXSW</u> SOURCE) for drag perturbations estimation throughout this message's timespan.	$10^{-22}$ W/(m* *2*Hz)		120.0	No
PERT	_STOP	End of the perturbations specification	n/a			Yes

## 6.2.10 OCM DATA: ORBIT DETERMINATION DATA

~~NOTE: THIS SECTION APPLIES TO ALL ORBIT AND COVARIANCE DATA BASED UPON “DETERMINED” ORBIT SOLUTIONS~~

~~6.2.10.1~~ Table 6-~~611~~ provides an overview of the OCM orbit determination data section. Only those keywords shown in Table 6-~~611~~ shall be used in OCM orbit determination data specification.

~~6.2.10.2~~ Keyword values shall be provided in the units specified in the “Units” column of Table 6-6.

~~6.2.10.3~~ The order of occurrence of these OCM Orbit Determination Data keywords shall be fixed as shown in Table 6-6.

~~6.2.10.4~~ The “OCM Data: Orbit Determination Data” section is optional; “mandatory” in the context of Table 6-6 denotes those keywords which must be included in this section if this section is included.

~~6.2.10.5~~6.2.10.2 At most, only one Orbit Determination Data section shall appear in an OCM.

~~6.2.10.6~~6.2.10.3 Orbit determination data in the OCM shall be indicated by two keywords: OD\_START and OD\_STOP.

~~6.2.10.7~~6.2.10.4 All orbit determination event times shall be specified relative to the orbit determination epoch specified via the OD\_EPOCH keyword (in SI days, ~~with one day = each consisting of 86400.0 s seconds~~) as a double precision number. Event times may be negative, zero or positive, ~~depending upon the definition of the event time (i.e., OD\_EPOCH with respect to event time versus event time with respect to OD\_EPOCH).~~

~~6.2.10.8~~6.2.10.5 A “Sensor Track” is defined above in Section 1.~~65~~.

~~6.2.10.9~~6.2.10.6 This orbit determination parameters section should reflect the orbit determination settings used to generate all orbit, covariance and state transition matrix sections of the message that are based upon “determined” orbit solutions.

~~6.2.10.10~~6.2.10.7 If an orbit determination parameters section is included in the message, ~~it is recommended that~~ a corresponding perturbations section should be included as well to specify the perturbations incorporated in the orbit determination.

6.2.10.8 The Orbit Determination specification shall apply to all OCM orbit and covariance time history data sections that are based upon “determined” orbit solutions

~~NOTE: THIS SECTION APPLIES TO ALL ORBIT AND COVAR DATA BASED UPON “DETERMINED” ORBIT SOLUTIONS~~

**Table 6-12: OCM Data: Orbit Determination Data**

Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
OD_START	Start of an orbit determination data section	n/a		n/a	Yes
COMMENT	Comments (a contiguous set of one or more comment lines <b>are</b> allowed in the OCM Orbit Determination Data section only immediately after the OD_START key word; see 7.7 for comment formatting rules).	n/a		<del>COMMENT</del> -This is a comment	No
OD_ID	Optional identification number for this orbit determination	n/a		OD_20160402	No
OD_PREV_ID	Optional identification number for the previous orbit determination. Note: if this orbit determination is the first one, then OD_PREV_ID should be excluded from this message.	n/a		OD_20160401	No
OD_METHOD	Type of orbit determination method used to produce the orbit estimate. <del>This</del> While this is a free-text field, <del>but it is suggested that it be comprised of the method</del> (commonly used methods could include Batch Weighted Least Squares (BWLS), Extended Kalman Filter (EKF), Sequential Filter (SF), Square Root Information Filter (SRIF), Sequential Simultaneous Estimation Method (SSEM-)), <del>followed by a colon delimiter and the actual OD tool used to estimate the orbit (e.g., BAHN, ODIN, ODTK).</del>	n/a		BWLS-; <u>BAHN</u> BWLS; <u>ODIN</u> EKF; <del>SF</del> ; <u>ODTK</u>	Yes
OD_EPOCH	UTC epoch of the orbit determination solved-for state (See 7.5.10 for formatting rules.).	n/a		2001-11-06T11:17:33 2002-204T15:56:23Z	Yes
DAYS_SINCE_FIRST_OBS	Days ( <del>defined by SEC_PER_DAY duration in the OCM metadata section</del> SI days, with one day = 86400.0 s) elapsed between first accepted observation and OD EPOCH	d		3.5	No
DAYS_SINCE_LAST_OBS	Days ( <del>defined by SEC_PER_DAY duration in the OCM metadata section</del> SI days, with one day = 86400.0 s) elapsed between last accepted observation and OD EPOCH	d		1.2	No
RECOMMENDED_OD_SPAN	Number of days ( <del>defined by SEC_PER_DAY duration in the OCM metadata section</del> SI days, with one day = 86400.0 s) of observations recommended for the OD of the object ( <i>useful only for Batch OD systems</i> )	d		5.2	No
ACTUAL_OD_SPAN	Actual time span in days ( <del>defined by SEC_PER_DAY duration in the OCM metadata section</del> SI days, with one day = 86400.0 s) used for the OD of the object (NOTE: should equal (DAYS_SINCE_FIRST_OBS - DAYS SINCE LAST OBS))	d		2.3	No
OBS_AVAILABLE	The number of observations available within the actual OD time span	n/a		100	No
OBS_USED	The number of observations accepted within the actual OD time span	n/a		90	No
TRACKS_AVAILABLE	The number of sensor tracks, for the actual time span, that were available for the OD	n/a		33	No
TRACKS_USED	The number of sensor tracks, for the actual time span, that were accepted for the OD	n/a		30	No
MAXIMUM_OBS_GAP	The maximum time between observations in the OD of the object	d		1.0	No
OD_EPOCH_EIGMAJ	Positional error ellipsoid 1 $\sigma$ major eigenvalue at the epoch of the OD	m		58.73	No

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Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
OD_EPOCH_EIGMED	Positional error ellipsoid $1\sigma$ medium eigenvalue at the epoch of the OD	m		35.7	No
OD_EPOCH_EIGMIN	Positional error ellipsoid $1\sigma$ minor eigenvalue at the epoch of the OD	m		21.5	No
<del>OD_MIN_EIGMAJ</del>	<del>The resulting minimum <b>predicted</b> major eigenvalue of the <math>1\sigma</math> positional error ellipsoid over the entire TIME_SPAN of the OCM, stemming from this OD</del>	<del>m</del>		<del>21.5</del>	<del>No</del>
OD_MAX_EIGMAJ	The resulting maximum <b>predicted</b> major eigenvalue of the $1\sigma$ positional error ellipsoid over the entire TIME_SPAN of the OCM, stemming from this OD	m		21.5	No
<del>OD_MIN_EIGMAJ</del>	<del>The resulting minimum <b>predicted</b> major eigenvalue of the <math>1\sigma</math> positional error ellipsoid over the entire TIME_SPAN of the OCM, stemming from this OD</del>	<del>m</del>		<del>21.5</del>	<del>No</del>
OD_CONFIDENCE	OD confidence metric, which by definition spans 0 to 100%. (useful only for Filter-based OD systems). The OD confidence metric <del>should</del> shall be <u>as mutually defined by ICD message exchange participants.</u>	Percent		95.3	No
GDOP	Generalized Dilution Of Precision for this orbit determination, based on the observability grammian as defined in Kaplan "Understanding GPS: Principles and Applications <sup>22</sup> ," <u>and expressed in Informative Annex C4.</u> GDOP provides a rating metric of the observability of the element set from the OD. <del>(AWAITING SPECIFIC INPUTS FROM CHERYL)</del> <u>Alternate GDOP formations may be used as mutually defined by message exchange participants.</u>	n/a		.857	No
SOLVE_N	The number of solve-for states in the orbit determination	n/a		6	No
SOLVE_STATES	Free-text comma-delimited description of the state elements solved for in the orbit determination	n/a		POS(3), VEL(3)	No
CONSIDER_N	The number of consider parameters used in the orbit determination	n/a		3	No
CONSIDER_PARAMS	Free-text comma-delimited description of the consider parameters used in the orbit determination	n/a		DRAG, SRP	No
SENSORS_N	The number of sensors used in the orbit determination	n/a		3	No
SENSORS	Free-text comma-delimited description of the sensors used in the orbit determination	n/a		EGLIN, FYLINGDALES	No
INTEG_STEP_SIZE	Integration step size. A value of zero '0' shall be used to denote a variable integration step size, if this optional parameter is specified.	s		60.0	No

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Keyword	Description	Units	Default (if any)	Examples of Values	Mandatory
<del>CONSIDER_PARAMS</del>	<del>Measurement update interval. A value of zero '0' shall be used to denote a variable measurement update interval, if this optional parameter is specified.</del>	s		86400.0	No
WEIGHTED_RMS	<p><b>(Useful / valid only for Batch OD systems).</b></p> <p>The weighted RMS residual ratio, defined as:</p> $\text{Weighted RMS} = \sqrt{\frac{\sum_{i=1}^N w_i (y_i - \hat{y}_i)^2}{N}}$ <p>Where <math>y_i</math> is the observation measurement at the <math>i</math>th time</p> <p><math>\hat{y}_i</math> is the current estimate of <math>y_i</math>,</p> <p><math>w_i = \frac{1}{\sigma_i^2}</math> is the weight (sigma) associated with the measurement at the <math>i</math>th time and <math>N</math> is the number of observations.</p> <p>This is a value that can generally identify the quality of the most recent vector update, and is used by the analyst in evaluating the OD process. A value of 1.00 is ideal.</p>	(measurement units)		1.3	No
TDM_IDS	An alphanumeric free-text string containing a comma-separated list of file name(s) and/or associated identification number(s) of Tracking Data Message (TDM) [9] observations upon which this OD is based.	n/a		TDM_0005.txt	No
DATA_TYPES	Comma-separated list of observation data types utilized in this orbit determination. Although this is a free-text field, it is recommended at a minimum to use data type descriptor(s) as provided in Table 3-5 of the TDM standard [9] (excluding the DATA_START, DATA_STOP, and COMMENT keywords). <del>Orbit determine event times are in double precision days.</del> Additional descriptors/detail is encouraged if the descriptors of Table 3-5 are not sufficiently clear, e.g., could replace ANGLE_1 and ANGLE_2 with RADEC (e.g., from a telescope), AZEL (e.g., from a ground radar), RANGE (whether from radar or laser ranging), etc.	n/a		n/a	No
OD_STOP	End of an orbit determination data section	n/a		n/a	Yes

## 6.2.11 OCM DATA: USER-DEFINED PARAMETERS

**6.2.11.1** A section of User Defined Parameters may be provided if necessary. In principle, this provides flexibility, but also introduces complexity, non-standardization, potential ambiguity, and potential processing errors. Accordingly, if used, the keywords and their meanings must be described in an ICD-; comments are also encouraged to further describe the user parameters. User Defined Parameters, if included in an OCM, should be used as sparingly as possible; their use is not encouraged.

~~6.2.11.2 The “OCM Data: User Defined Parameters” section is optional; “mandatory” in the context of Table 6-13 denotes those keywords which must be included in this section if this section is included.~~

~~6.2.11.3~~ 6.2.11.2 At most, only one User-Defined Parameters section shall appear in an OCM.

~~6.2.11.4 Each user-defined user parameter line may be preceded by one or more comment lines.~~

~~6.2.11.5~~ 6.2.11.3 Table 6-~~13~~12 provides an overview of the OCM user-defined data section. Only those keywords shown in Table 6-12 shall be used in OCM user-defined data specification.

**Table 6-13: OCM Data: User-Defined Parameters**

Keyword	Description	Units	Examples of Values	Mandatory
USER_START	Start of a User-defined parameters data block	n/a		Yes
COMMENT	Comments (a contiguous set of one or more comment lines <del>are</del> <u>is</u> allowed immediately following the USER_START keyword <del>(See 7.7 for formatting rules.)</del> )	n/a	<del>COMMENT</del> -This is a comment	No
(USER-DEFINED)	User-defined keyword(s) paired with user-specified variable length character string values. Multiple user-defined parameters may be specified in this manner, but only as necessary to provide essential information that cannot be otherwise conveyed in standard OCM content and accompanying comments.	n/a	EARTH_MODEL = WGS-84	No
USER_STOP	End- of a User-defined parameters data block	n/a		Yes

## 6.3 OCM EXAMPLES AND SUPPLEMENTARY INFORMATION

Example OCMs and associated supplementary (non-normative) information are provided in G-1-Annex G.

## 7 ORBIT DATA MESSAGE SYNTAX

### 7.1 OVERVIEW

This section details the syntax requirements for each of the Orbit Data Messages.

### 7.2 GENERAL

The Orbit Data Messages (OPM, OMM, OEM ~~or~~, and OCM) shall observe the syntax described in 7.3 through 7.7.7.8.

### 7.3 ODM LINES

**7.3.1** Each OPM, OMM, OEM or OCM line shall be one of the following:

- Header line;
- Metadata line;
- Data line;
- Comment line; or
- Blank line.

**7.3.2** Each OPM, OMM, or OEM line must not exceed 254 ASCII characters and spaces (excluding line termination character[s]).

**7.3.3** OCM lines may be of arbitrary length. If exchange between the two parties requires a maximum line length, that limit should be negotiated and specified in an ICD.

**7.3.4** Only printable ASCII characters and blanks shall be used. Control characters (such as TAB, etc.) shall not be used, with the exception of the line termination characters specified below.

**7.3.5** Blank lines may be used at any position within the file. Blank lines shall have no assignable meaning, and may be ignored.

**7.3.6** The first header line must be the first non-blank line in the file.

**7.3.7** All lines shall be terminated by a single Carriage Return or a single Line Feed, or a Carriage Return/Line Feed pair or a Line Feed/Carriage Return pair.

## 7.4 KEYWORD = VALUE NOTATION (I.E., NON-XML) AND ORDER OF ASSIGNMENT STATEMENTS

7.4.1 For the OPM and OMM, all header, metadata, and data lines shall use ‘keyword = value’ notation, abbreviated as KVN.

7.4.1.1 For the OEM, all header and metadata elements shall use KVN notation.

7.4.1.2 OEM ephemeris data lines shall not use KVN format; rather, the OEM ephemeris data line has a fixed structure containing seven required fields (epoch time, three position components, three velocity components), and three optional acceleration components. (See 5.2.4.)

7.4.1.3 OEM covariance matrix epoch and covariance reference frame (if used) shall use KVN format. The OEM covariance data lines shall not use KVN format; rather, the OEM covariance data line has a fixed structure containing from one to six required fields (a row from the 6x6 lower triangular form covariance matrix). (See 5.2.5.)

7.4.1.4 For the OCM, all header and metadata elements shall use KVN notation.

~~7.4.1.5 All OCM KVN keyword specified lines can contain interspersed blank lines as desired, for example to enhance message clarity and readability.~~

~~7.4.1.6~~ 7.4.1.5 OCM orbit state time history data lines shall not use KVN format; rather, the structure of such OCM orbit state time history data lines shall be comprised of a contiguous set of lines containing time tag followed by the parameters corresponding to the selected orbit set (See 6.2.4).

~~7.4.1.7~~ 7.4.1.6 OCM covariance matrix epoch and covariance reference frame (if used) shall use KVN format. The OCM covariance data lines shall not use KVN format; rather, the OCM covariance data line has a fixed structure which shall be comprised of a contiguous set of lines containing from one to “N” required fields (a row from the N x N lower triangular form of a square covariance matrix) ~~or~~. Alternately, the covariance may be represented by a single line containing epoch, eigenvalues followed by the major eigenvalue, medium eigenvalue, minor eigenvalue and their corresponding major, medium and minor eigenvectors. (See 6.2.6.)

~~7.4.1.8~~ 7.4.1.7 OCM state transition matrix data lines shall not use KVN format; rather, OCM state transition matrix data shall be comprised of a contiguous set of lines containing a fixed structure as presented in Sec. 6.2.7.

~~7.4.1.9~~ 7.4.1.8 OCM maneuver data lines shall not use KVN format; rather, OCM maneuver data shall be comprised of a contiguous set of lines containing a fixed structure as presented in Sec. ~~6-316.2.8~~ 6.2.8.

7.4.2 The keywords ‘COMMENT’, [wild card]‘\_START’ and [wild card]‘\_STOP’ are exceptions to the KVN syntax assignment.

7.4.3 Only a single ‘keyword = value’ assignment shall be made on a line.

7.4.4 Keywords must be uppercase and must not contain blanks.

7.4.5 Any white space immediately preceding or following the keyword shall not be significant.

7.4.6 Any white space immediately preceding or following the 'equals' sign shall not be significant.

7.4.7 Any white space immediately preceding the end of line shall not be significant.

7.4.8 The order of occurrence of mandatory and optional KVN assignments shall be fixed as shown in the tables in sections 3, 4, 5 and 6 that describe the OPM, OMM, OEM and OCM keywords.

## 7.5 VALUES

7.5.1 A non-empty value field must be specified for each mandatory keyword except as noted in §7.4.2 above.

~~7.5.2 Non-numeric values~~ Comments and free-text value fields may ~~contain~~ ~~be in any case~~ (or mix of lowercase and uppercase ~~[DLOS]~~ letters OR Text case) desired by the user.

~~7.5.2~~7.5.3 Apart from comments and free-text fields, normative text value fields must be constructed using only **exclusively all uppercase**. ~~An exception is made for comment values (see 6.2.5 for formatting rules).~~ **or exclusively all lowercase.**

~~7.5.3~~7.5.4 Integer values shall consist of a sequence of decimal digits with an optional leading sign ('+' or '-'). If the sign is omitted, '+' shall be assumed. Leading zeroes may be used. The range of values that may be expressed as an integer is:

$$-2,147,483,648 \leq x \leq +2,147,483,647 \quad (\text{i.e., } -2^{31} \leq x \leq 2^{31}-1).$$

NOTE – The commas in the range of values above are thousands separators and are used only for readability. They should not appear in an actual message.

~~7.5.4~~7.5.5 Non-integer numeric values may be expressed in either fixed-point or floating-point notation. Both representations may be used within an OPM, OMM, OEM or OCM.

~~7.5.5~~7.5.6 Non-integer numeric values expressed in fixed-point notation shall consist of a sequence of decimal digits separated by a period as a decimal point indicator, with an optional leading sign ('+' or '-'). If the sign is omitted, '+' shall be assumed. Leading and trailing zeroes may be used. At least one digit shall appear before and after a decimal point.

~~7.5.6~~7.5.7 Non-integer numeric values expressed in floating point notation shall consist of a sign, a mantissa, an alphabetic character indicating the division between the mantissa and exponent, and an exponent, constructed according to the following rules:

- a) The sign may be '+' or '-'. If the sign is omitted, '+' shall be assumed.
- b) The mantissa must be a string of no more than 16 decimal digits with a decimal point ('.') in the second position of the ASCII string, separating the integer portion of the mantissa from the fractional part of the mantissa.
- c) The character used to denote exponentiation shall be 'E' or 'e'. If the character indicating the exponent and the following exponent are omitted, an exponent value of zero shall be assumed (essentially yielding a fixed point value).
- d) The exponent must be an integer, and may have either a '+' or '-' sign (if the sign is omitted, then '+' shall be assumed).
- e) The maximum positive floating-point value is approximately 1.798E+308, with 16 significant decimal digits precision. The minimum positive floating point value is approximately 4.94E-324, with 16 significant decimal digits precision.

**7.5.7** Text value fields must be constructed using only all uppercase or all lowercase.

**7.5.8** Blanks shall not be permitted within numeric values and time strings.

**7.5.9** In value fields that are text, an underscore shall be equivalent to a single blank. Individual blanks shall be retained (shall be significant), but multiple contiguous blanks shall be equivalent to a single blank.

**7.5.10** In value fields that represent an absolute time tag or epoch, times shall be given in one of the following two formats:

YYYY-MM-DDThh:mm:ss[.d→d][Z]

or

YYYY-DDDThh:mm:ss[.d→d][Z]

where 'YYYY' is the year, 'MM' is the two-digit month, 'DD' is the two-digit day, 'DDD' is the three-digit day of year, 'T' is constant, 'hh:mm:ss[.d→d]' is the time in hours, minutes seconds, and optional fractional seconds; 'Z' is an optional time code terminator (the only permitted value is 'Z' for Zulu, i.e., UTC). As many 'd' characters to the right of the period as required may be used to obtain the required precision, up to the maximum allowed for a fixed-point number. All fields shall have leading zeros. (See reference [1], ASCII Time Code A or B.). Where such epochs occur within one second after leap second introduction, the hh:mm:ss portion of the above time specification shall use the convention XX:XX:60.XXXX.

**7.5.11** The time system for CREATION\_DATE is UTC; for all other keywords representing times or epochs, the time system is determined by the TIME\_SYSTEM metadata keyword.

## 7.6 UNITS IN THE ORBIT DATA MESSAGES

### 7.6.1 OPM/OMM/~~OCM~~ UNITS

**7.6.1.1** For documentation purposes and clarity only, units may be included as ASCII text after a value in the OPM, ~~OMM~~ and ~~OCM~~OMM. If units are displayed, they must exactly match the units (including lower/upper case) as specified in tables 3-3, 4-3, ~~56~~-3 and 6-4 through 6-12. If units are displayed, then:

- a) there must be at least one blank character between the value and the units text;
- b) the units must be enclosed within square brackets (e.g., '[km]');
- c) multiplication shall be denoted by a single asterisk (e.g., '[N\*m]');
- d) division shall be denoted by a single forward slash (e.g., meters per second is ~~m~~km/s);
- e) exponents of units shall be denoted with a double asterisk (i.e., '\*\*', for example, ~~m<sup>2</sup>=mkm<sup>2</sup>=km~~\*\*2);
- f) The usual order of operations ordering applies (e.g., exponents before multiplication).

**7.6.1.2** Some of the items in the applicable tables are dimensionless. The table shows a unit value of 'n/a', which in this case means that there is no applicable units designator for these items (e.g., for ECCENTRICITY). The notation '[n/a]' should not appear in an OPM, OCM or OMM.

### 7.6.2 OEM UNITS

**7.6.2.1** In an OEM ephemeris data line, units shall be km, km/s, and km/s\*\*2 for position, velocity, and acceleration components, respectively, but the units shall not be displayed.

**7.6.2.2** In an OEM covariance matrix line, units shall be km\*\*2, km\*\*2/s, or km\*\*2/s\*\*2 depending on whether the element is computed from two position components, one position component and one velocity component, or two velocity components. The units shall not be displayed.

### 7.6.3 OCM UNITS

~~**7.6.3.1** In an OCM orbit state data line, units shall be degrees for angular quantities, kilometers for distance quantities and seconds for time quantities. The units shall not be displayed.~~

~~7.6.3.2~~ In an OCM covariance matrix line, units shall be comprised of the requisite combination of degrees for angular quantities, kilometers for distance quantities and seconds for time quantities. The units shall not be displayed.

~~7.6.3.3~~ In an OCM state transition matrix data section, units Units for OCM keyword values shall be compatible with the corresponding orbit-, covariance, or state transition matrix type's requisite combination of ~~degrees for angular quantities, kilometers for distance quantities and seconds for time quantities.~~ The units shall not be displayed.

~~7.6.3.4~~ In an OCM ephemeris compression data section, units shall be compatible with the corresponding orbit type's requisite combination of degrees for angular quantities, kilometers for distance quantities and seconds for time quantities. The units shall not be displayed.

~~7.6.3.5~~7.6.4 Units for all other OCM quantities are as units specified in section the SANA registry [11 – 18], or if not provided there for a specific keyword, then the “Units” column of the accompanying Keyword Value Tables (i.e., Tables 6.2.4 through 6.12) for each section definition.

NOTE: While the units used throughout the OCM are generally a combination of kilometers for distance and seconds for time (e.g., km/s for velocity, km/s<sup>2</sup> for acceleration and so forth). Mass is in kilograms, and force is in Netwons).

7.6.4.1 In OCM orbit state, covariance, or state transition matrix data line, units shall not be displayed.

## 7.7 COMMENTS IN THE ORBIT DATA MESSAGES

7.7.1 There are certain pieces of information that provide clarity and remove ambiguity about the interpretation of the information in a file, yet are not standardized so as to fit cleanly into the ‘keyword = value’ paradigm. Rather than force the information to fit into a space limited to one line, the ODM producer should put certain information into comments and use the ICD to provide further specifications.

7.7.2 Comments may be used to provide provenance information or to help describe dynamical events or other pertinent information associated with the data. This additional information is intended to aid in consistency checks and elaboration where needed, but shall not be required for successful processing of a file.

7.7.3 For the OPM, OMM, OEM and OCM, comment lines shall be optional.

7.7.4 Comment text may be in any case (or mix of case) desired by the user.

~~7.7.4~~7.7.5 All comment lines shall begin with the ‘~~COMMENT~~’COMMENT’ keyword followed by at least one space. This keyword must appear on every comment line, not just the first such line. The remainder of the line shall be the comment value. White space shall be retained (shall be significant) in comment values.

**7.7.57.7.6** Placement of comments shall be as specified in the tables in sections 3, 4, 5 and 6 that describe the OPM, OMM, OEM and OCM keywords.

**7.7.67.7.7** Comments in the OPM may appear in the OPM Header immediately after the ‘CCSDS\_OPM\_VERS’ keyword, at the very beginning of the OPM Metadata section, and at the beginning of a logical block in the OPM Data section. Comments must not appear between the components of any logical block in the OPM Data section.

NOTE – The logical blocks in the OPM Data section are indicated in table 3-3.

**7.7.77.7.8** Comments in the OMM may appear in the OMM Header immediately after the ‘CCSDS\_OMM\_VERS’ keyword, at the very beginning of the OMM Metadata section, and at the beginning of a logical block in the OMM Data section. Comments must not appear between the components of any logical block in the OMM Data section.

NOTE – The logical blocks in the OMM Data section are indicated in table 4-3.

**7.7.87.7.9** Comments in the OEM may appear in the OEM Header immediately after the ‘CCSDS\_OEM\_VERS’ keyword, at the very beginning of the OEM Metadata section (after the ‘META\_START’ keyword), at the beginning of the OEM Ephemeris Data Section, and at the beginning of the OEM Covariance Data section (after the ‘COV\_START’ keyword). Comment lines must not appear within any block of ephemeris lines or covariance matrix lines.

**7.7.97.7.10** Comments in the OCM may appear in the OCM Header, Metadata, Space Object Physical Characteristics, Force Model, Maneuver, Orbit State Time History, Covariance Time History, State Transition Matrix Time History, ~~Ephemeris Compression~~ and User-Defined Parameters data sections only at the positions shown in the defining Tables (generally at the top of each section, following the \*\_START section delimiting keyword).

**7.7.107.7.11** Extensive comments in an ODM are recommended in cases where there is insufficient time to negotiate an ICD.

**7.7.117.7.12** The following comments should be provided:

- a) Information regarding the genesis, history, interpretation, intended use, etc., of the state vector, spacecraft, maneuver, or ephemeris that may be of use to the receiver of the OPM, OMM, or OEM:

COMMENT Source: File created by JPL Multi-Mission Navigation Team as part  
COMMENT of Launch Operations Readiness Test held on 20 April 2001.

- b) Natural body ephemeris information: When the Earth is not the center of motion, the ephemerides of the planets, satellites, asteroids, and/or comets (including associated constants) consistent with the ODM should be identified so that the recipient can, in a consistent manner, make computations involving other centers:

<p>COMMENT Based on latest orbit solution which includes observations  COMMENT through 2000-May-15 relative to planetary ephemeris DE-0405.</p>
---

- c) OEM accuracy vs. efficiency: If the covariance data section of the OEM is not utilized, the producer of an OEM should report in comment lines what the expected accuracy of the ephemeris is, so the user can smooth or otherwise compress the data without affecting the accuracy of the trajectory. The OEM producer also should strive to achieve not only the best accuracy possible, taking into account prediction errors, but also consider the efficiency of the trajectory representation (e.g., step sizes of fractional seconds between ephemeris lines may be necessary for precision scientific reconstruction of an orbit, but are excessive from the standpoint of antenna pointing predicts generation).

## 7.8 ORBIT DATA MESSAGE KEYWORDS

### 7.8.1 VERSION KEYWORDS

The Header of the OPM, OMM, OEM and OCM shall provide a CCSDS Orbit Data Message version number that identifies the format version; this is included to anticipate future changes. The version keywords for the OPM, OMM, OEM and OCM shall be `CCSDS_OPM_VERS`, `CCSDS_OMM_VERS`, `CCSDS_OEM_VERS` and `CCSDS_OCM_VERS`, respectively. The value shall have the form of 'x.y', where 'y' shall be incremented for corrections and minor changes, and 'x' shall be incremented for major changes. Version x.0 shall be reserved for versions accepted by the CCSDS as an official Recommended Standard ('Blue Book'). Testing shall be conducted using OPM, OMM, OEM and OCM version numbers less than 1.0 (e.g., 0.x). Exchange participants should specify in the ICD the specific OPM, OMM, OEM and OCM version numbers they will support. The following version numbers are supported (Blue Book) or have been supported in the past (Silver Book):

Version Keyword	Version Number	Applicable Recommendation
CCSDS_OPM_VERS	1.0	Silver Book 1.0, 09/2004
CCSDS_OPM_VERS	2.0	Silver Book 2.0, 09/2009
CCSDS_OPM_VERS	3.0	Blue Book 3.0 (this document)
CCSDS_OMM_VERS	2.0	Silver Book 2.0, 09/2009
CCSDS_OMM_VERS	3.0	Blue Book 3.0 (this document)
CCSDS_OEM_VERS	1.0	Silver Book 1.0, 09/2004
CCSDS_OEM_VERS	2.0	Silver Book 2.0, 09/2009
CCSDS_OEM_VERS	3.0	Blue Book 3.0 (this document)
CCSDS_OCM_VERS	3.0	Blue Book 3.0 (this document)

## 7.8.2 GENERAL KEYWORDS

**7.8.2.1** Only those keywords shown in table 3-1, table 3-2, and table 3-3 shall be used in an OPM. Some keywords represent mandatory items and some are optional. KVN assignments representing optional items may be omitted.

**7.8.2.2** Only those keywords shown in table 4-1, table 4-2, and table 4-3 shall be used in an OMM. Some keywords represent mandatory items and some are optional. KVN assignments representing optional items may be omitted.

**7.8.2.3** Only those keywords shown in table 5-2 and table 5-3 shall be used in an OEM. Some keywords represent mandatory items and some are optional. KVN assignments representing optional items may be omitted.

**7.8.2.4** Only those keywords shown in tables 6-2, table 6-3, table 6-4, table 6-5, table 6-6, table 6-7, table 6-8, ~~table 6-9~~, table 6-10, ~~table 6-11~~, ~~table 6-12~~ and table 6-~~11~~13 shall be used

in an OCM. Some keywords represent mandatory items and some are optional. KVN assignments representing optional items may be omitted.

## 8 CONSTRUCTING AN ODM/XML INSTANCE

### 8.1 OVERVIEW

This section provides detailed instructions for the user on how to create an XML message based on one of the ASCII-text KVN-formatted messages described in Section 3, Section 4, Section 5 and Section 6.

### 8.2 XML VERSION

The first line of each instantiation shall specify the XML version, exactly as follows:

```
<?xml version="1.0" encoding="UTF-8"?>
```

### 8.3 BEGINNING THE INSTANTIATION: ROOT ELEMENT TAG

**8.3.1** Each instantiation shall have a ‘root element tag’ that identifies the message type and other information such as where to find the applicable schema, required attributes, etc.

**8.3.2** The root element tag in an ODM/XML instantiation shall be one of those listed in Table 8-1.

**Table 8-1: ODM/XML Root Element Tags**

Root Element Tag	Message Type
<opm></opm>	Orbit Parameter Message
<omm></omm>	Orbit Mean Elements Message
<oem></oem>	Orbit Ephemeris Message
<ocm></ocm>	Orbit Comprehensive Message

**8.3.3** The XML Schema Instance namespace attribute must appear in the root element tag of all ODM/XML instantiations, exactly as shown:

```
xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
```

If it is desired to validate an instantiation against the CCSDS Web-based schema, the `xsi:noNamespaceSchemaLocation` attribute must be coded as a single string of non-blank characters, with no line breaks exactly as shown:

```
xsi:noNamespaceSchemaLocation="http://sanaregistry.org/r/ndmxml/ndmxml-1.0-master.xsd"
```

NOTE – The value associated with the `xsi:noNamespaceSchemaLocation` attribute shown in this document is too long to appear on a single line.

**8.3.4** For use in a local operations environment, the schema set may be downloaded from the CCSDS Web site to a local server that meets local requirements for operations robustness.

**8.3.5** If a local version is used, the value associated with the `xsi:noNamespaceSchemaLocation` attribute must be changed to a URL that is accessible to the local server.

**8.3.6** Two attributes shall appear in the root element tag of an ODM/XML single message instantiation, specifically, the `CCSDS_XXX_VERS` keyword that is also part of the standard KVN header, and the Blue Book version number.

**8.3.7** The `CCSDS_XXX_VERS` keyword shall be supplied via the 'id' attribute of the root element tag (`xxx = OPM, OMM, OEM, OCM`).

**8.3.8** The version number of the Blue Book to which the schema applies shall be supplied via the 'version' attribute.

NOTE – The following example root element tag for an OPM instantiation combines all the directions in the preceding several Sections:

```
<?xml version="1.0" encoding="UTF-8"?>
<opm xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:noNamespaceSchemaLocation="http://sanaregistry.org/r/ndmxml/ndmxml-1.0-master.xsd"
      id="CCSDS_OPM_VERS" version="3.0">
```

## 8.4 THE STANDARD ODM/XML HEADER SECTION

**8.4.1** The ODMs shall share a standard header [formatsection](#), with tags `<header>` and `</header>`.

**8.4.2** Immediately following the `<header>` tag the message may have any number of `<COMMENT>`~~`</COMMENT>`~~ [tag pairs](#) [elements](#).

**8.4.3** The standard ODM header shall contain the `<CREATION_DATE>` and the `<ORIGINATOR>` [tagselements](#).

NOTE – An example `<header>` section is shown immediately below.

```
<header>
  <COMMENT>This is the common ODM/XML header</COMMENT>
  <COMMENT>I can put as many comments here as I
    want,</COMMENT>
  <COMMENT>including none.</COMMENT>
```

```

<CREATION_DATE>2004-281T17:26:06</CREATION_DATE>
<ORIGINATOR>AGENCY-X</ORIGINATOR>
<MESSAGE_ID>XYZ123-2019</MESSAGE_ID>
</header>

```

## 8.5 THE ODM BODY SECTION

**8.5.1** After coding the <header>, the instantiation must include a ~~<body></body>~~ tag pair section.

**8.5.2** Inside the ~~<body></body>~~ tag pair section must appear at least one ~~<segment></segment>~~ tag pair section.

**8.5.3** Each segment must be made up of one or more ~~<metadata></metadata>~~ and ~~<data></data>~~ tag pairs sections, depending on the specific message type.

## 8.6 THE ODM METADATA SECTION

**8.6.1** All ODMs must have a metadata section.

**8.6.2** The metadata section shall be set-offdelimited by the ~~<metadata></metadata>~~ tag combination element.

**8.6.3** Between the <metadata> and </metadata> tags, the keywords shall be the same as those in the metadata sections in Section 3, Section 4, Section 5 and Section 6, with possible exceptions as noted in the Sections that discuss creating instantiations of the specific messages.

## 8.7 THE ODM DATA SECTION

**8.7.1** All ODMs must have a data section.

**8.7.2** The data section shall follow the metadata section and shall be set-offdelimited the by the ~~<data></data>~~ tag combination element.

**8.7.3** Between the <data> and </data> tags, the keywords shall be the same as those in the data sections in Section 3, Section 4, Section 5 and Section 6, with possible exceptions as noted in the Sections that discuss creating instantiations of the specific messages.

## 8.8 CREATING AN OPM INSTANTIATION

**8.8.1** An OPM instantiation shall be delimited with the <opm></opm> root element tags using the standard attributes documented in **8.3**.

**8.8.2** The final attributes of the <opm> tag shall be 'id' and 'version'.

**8.8.3** The 'id' attribute shall be 'id="CCSDS\_OPM\_VERS"'.

**8.8.4** The 'version' attribute shall be 'version="3.0"'.

**8.8.5** The standard NDM header shall follow the <opm> tag (see **8.4**).

**8.8.6** The OPM <body> shall consist of a single <segment>.

**8.8.7** The <segment> shall consist of a <metadata> section and a <data> section.

**8.8.8** The keywords in the <metadata> and <data> sections shall be those specified in Section 3. The rules for including any of the keyword tags in the OPM/XML are the same as those specified for the OPM/KVN.

**8.8.9** Tags for keywords specified in Section 3 shall be all uppercase.

**8.8.10** Several of the OPM/XML keywords may have athe unit attribute, ~~if desired by the OPM producer.~~

**8.8.11** In all cases, the units shall match those defined in the tables in Section 3.

**8.8.12** The following table lists examples of the keyword tags for which use of units may in the OPM/XML. [NOTE TO DAN: Previously this was an exhaustive list, but the number of elements in the OCM suggested to me that provision of examples would be ~~specified sufficient to illustrate the method.~~]

Keyword	Units	Example
X	km	<X units="km">numeric-value</X>
<del>Y</del>	<del>km</del>	<del>&lt;Y units="km"&gt;numeric-value&lt;/Y&gt;</del>
<del>Z</del>	<del>km</del>	<del>&lt;Z units="km"&gt;numeric-value&lt;/Z&gt;</del>
X_DOT	km/s	<X_DOT units="km/s">numeric-value</X_DOT>
<del>Y_DOT</del>	<del>km/s</del>	<del>&lt;Y_DOT units="km/s"&gt;numeric-value&lt;/Y_DOT&gt;</del>
<del>Z_DOT</del>	<del>km/s</del>	<del>&lt;Z_DOT units="km/s"&gt;numeric-value&lt;/Z_DOT&gt;</del>
SEMI-MAJOR-AXIS	km	<SEMI-MAJOR-AXIS units="km">numeric-value</SEMI-MAJOR-AXIS>
INCLINATION	deg	<INCLINATION units="deg">numeric-value</INCLINATION>
<del>RA_OF_ASC_NODE</del>	<del>deg</del>	<del>&lt;RA_OF_ASC_NODE units="deg"&gt;numeric-value&lt;/RA_OF_ASC_NODE&gt;</del>
<del>ARG_OF_PERICENTER</del>	<del>deg</del>	<del>&lt;ARG_OF_PERICENTER units="deg"&gt;numeric-value&lt;/ARG_OF_PERICENTER&gt;</del>
<del>TRUE_ANOMALY</del>	<del>deg</del>	<del>&lt;TRUE_ANOMALY units="deg"&gt;numeric-value&lt;/TRUE_ANOMALY&gt;</del>
<del>MEAN_ANOMALY</del>	<del>deg</del>	<del>&lt;MEAN_ANOMALY units="deg"&gt;numeric-value&lt;/MEAN_ANOMALY&gt;</del>
GM	km**3/s**2	<GM units="km**3/s**2">numeric-value</GM>
MASS	kg	<MASS units="kg">numeric-value</MASS>
SOLAR_RAD_AREA	m**2	<SOLAR_RAD_AREA units="m**2">numeric-value</SOLAR_RAD_AREA>
<del>DRAG_AREA</del>	<del>m**2</del>	<del>&lt;DRAG_AREA units="m**2"&gt;numeric-value&lt;/DRAG_AREA&gt;</del>
<del>CX_X, CX_X, CY_X, CY_Y, CZ_X, CZ_Y, CZ_Z</del>	km**2	<CX_X units="km**2">numeric-value</CX_X>
<del>CX_DOT_X, CX_DOT_Y, CX_DOT_Z, CX_DOT_X, CY_DOT_X, CY_DOT_Y</del>	km**2/s	<CX_DOT_X units="km**2/s">numeric-value</CX_DOT_X>

Keyword	Units	Example
<del>CY_DOT_Z, GZ_DOT_X, GZ_DOT_Y,GZ_DOT_Z</del>		
<del>CX_DOT_X_DOT, CY_DOT_X_DOT, CY_DOT_Y_DOT, GZ_DOT_X_DOT, GZ_DOT_Y_DOT, GZ_DOT_Z_DOT</del>	km**2/s**2	<CX_DOT_X_DOT units="km**2/s**2">numeric-value</CX_DOT_X_DOT>
MAN_DURATION	s	<MAN_DURATION units="s">numeric-value</MAN_DURATION>
<del>MAN_DELTA_MASS</del>	<del>kg</del>	<del>&lt;MAN_DELTA_MASS units="kg"&gt;numeric-value&lt;/MAN_DELTA_MASS&gt;</del>
MAN_DV_1	km/s	<MAN_DV_1 units="km/s">numeric-value</MAN_DV_1>
<del>MAN_DV_2</del>	<del>km/s</del>	<del>&lt;MAN_DV_2 units="km/s"&gt;numeric-value&lt;/MAN_DV_2&gt;</del>
<del>MAN_DV_3</del>	<del>km/s</del>	<del>&lt;MAN_DV_3 units="km/s"&gt;numeric-value&lt;/MAN_DV_3&gt;</del>

**8.8.13** In addition to the OPM keywords specified in Section 3, there are several special tags associated with the OPM body as described in the next few Sections. The information content in the OPM is separated into ‘logical blocks’. Special tags in the OPM are used to encapsulate the information in the logical blocks of the OPM.

**8.8.14** The ~~ODMOPM~~/XML tags used to delimit the logical blocks of the OPM shall be drawn from the following table:

OPM Logical Block	Associated ODM/XML OPM Tag
State Vector	<stateVector>
Keplerian Elements	<keplerianElements>
Spacecraft Parameters	<spacecraftParameters>
Covariance Matrix	<covarianceMatrix>
Maneuver Parameters	<maneuverParameters>
User Defined Parameters	<userDefinedParameters> <u>(see 8.??)</u>

**8.8.15** Between the begin tag and end tag (i.e., between <spacecraftParameters> and </spacecraftParameters>), the user shall place the keywords required by the specific logical block as specified in Section 3.

## 8.9 CREATING AN OMM INSTANTIATION

**8.9.1** An OMM instantiation shall be delimited with the `<omm></omm>` root element tags using the standard attributes documented in **8.3**.

**8.9.2** The final attributes of the `<omm>` tag shall be 'id' and 'version'.

**8.9.3** The 'id' attribute shall be 'id="CCSDS\_OMM\_VERS"'.

**8.9.4** The 'version' attribute for the version of the OMM described in Section 4 shall be 'version="3.0"'.

**8.9.5** The standard NDM header shall follow the `<omm>` tag (see **8.4**).

**8.9.6** The OMM `<body>` shall consist of a single `<segment>`.

**8.9.7** The `<segment>` shall consist of a `<metadata>` section and a `<data>` section.

**8.9.8** The keywords in the `<metadata>` and `<data>` sections shall be those specified in Section 4. The rules for including any of the keyword tags in the OMM/XML are the same as those specified for the OMM/KVN in Section 4.

**8.9.9** Tags for keywords specified in Section 4 shall be all uppercase.

**8.9.10** Several of the OMM/XML keywords may have athe unit attribute, ~~if desired by the OMM producer.~~

**8.9.11** In all cases, the units shall match those defined in the tables in Section 4.

**8.9.12** The following table lists examples of the keyword tags for which use of units may be specified in the OMM/XML.

Keyword	Units	Example
SEMI_MAJOR_AXIS	km	<code>&lt;SEMI_MAJOR_AXIS units="km"&gt;numeric-value&lt;/SEMI_MAJOR_AXIS&gt;</code>
MEAN_MOTION	rev/day	<code>&lt;MEAN_MOTION units="rev/day"&gt;numeric-value&lt;/MEAN_MOTION&gt;</code>
INCLINATION	deg	<code>&lt;INCLINATION units="deg"&gt;numeric-value&lt;/INCLINATION&gt;</code>
<del>RA_OF_ASC_NODE</del>	<del>deg</del>	<del><code>&lt;RA_OF_ASC_NODE units="deg"&gt;numeric-value&lt;/RA_OF_ASC_NODE&gt;</code></del>
<del>ARG_OF_PERICENTER</del>	<del>deg</del>	<del><code>&lt;ARG_OF_PERICENTER units="deg"&gt;numeric-value&lt;/ARG_OF_PERICENTER&gt;</code></del>
<del>MEAN_ANOMALY</del>	<del>deg</del>	<del><code>&lt;MEAN_ANOMALY units="deg"&gt;numeric-value&lt;/MEAN_ANOMALY&gt;</code></del>
GM	km**3/s**2	<code>&lt;GM units="km**3/s**2"&gt;numeric-value&lt;/GM&gt;</code>
MASS	kg	<code>&lt;MASS units="kg"&gt;numeric-value&lt;/MASS&gt;</code>
SOLAR_RAD_AREA	m**2	<code>&lt;SOLAR_RAD_AREA units="m**2"&gt;numeric-value&lt;/SOLAR_RAD_AREA&gt;</code>
<del>DRAG_AREA</del>	<del>m**2</del>	<del><code>&lt;DRAG_AREA units="m**2"&gt;numeric-value&lt;/DRAG_AREA&gt;</code></del>
BSTAR	1/ER	<code>&lt;BSTAR units="1/ER"&gt;numeric-value&lt;/BSTAR&gt;</code>

Keyword	Units	Example
MEAN_MOTION_DOT	rev/day**2	<MEAN_MOTION_DOT units="rev/day**2">numeric-value</MEAN_MOTION_DOT>
<del>MEAN_MOTION_DDOT</del>	<del>rev/day**3</del>	<del>&lt;MEAN_MOTION_DDOT units="rev/day**3"&gt;numeric-value&lt;/MEAN_MOTION_DDOT&gt;</del>
<del>CX_X</del> , <del>CY_X</del> , <del>CY_Y</del> , <del>CZ_X</del> , <del>CZ_Y</del> , <del>CZ_Z</del>	km**2	<CX_X units="km**2">numeric-value</CX_X>
<del>CX_DOT_X</del> , <del>CX_DOT_Y</del> , <del>CX_DOT_Z</del> , <del>CY_DOT_X</del> , <del>CY_DOT_Y</del> , <del>CY_DOT_Z</del> , <del>CZ_DOT_X</del> , <del>CZ_DOT_Y</del> , <del>CZ_DOT_Z</del>	km**2/s	<CX_DOT_X units="km**2/s">numeric-value</CX_DOT_X>
<del>CX_DOT_X_DOT</del> , <del>CY_DOT_X_DOT</del> , <del>CY_DOT_Y_DOT</del> , <del>CZ_DOT_X_DOT</del> , <del>CZ_DOT_Y_DOT</del> , <del>CZ_DOT_Z_DOT</del>	km**2/s**2	<CX_DOT_X_DOT units="km**2/s**2">numeric-value</CX_DOT_X_DOT>

**8.9.13** In addition to the OMM keywords specified in Section 4, there are several special tags associated with the OMM body as described in the next few Sections. The information content in the OMM is separated into constructs described in Section 4 as ‘logical blocks’. Special tags in the OMM are used to encapsulate the information in the logical blocks of the OMM.

**8.9.14** The ~~ODM~~OMM/XML tags used to delimit the logical blocks of the OMM shall be drawn from the following table:

OMM Logical Block	Associated ODM/XML OMM Tag
Mean Keplerian Elements	<meanElements>
Spacecraft Parameters	<spacecraftParameters>
TLE Parameters	<tleParameters>
Covariance Matrix	<covarianceMatrix>
User Defined Parameters	<userDefinedParameters> <u>(see 8.??)</u>

**8.9.15** Between the begin tag and end tag (i.e.g., between <spacecraftParameters> and </spacecraftParameters>), the user must place the keywords required by the specific logical block as specified in Section 4.

## 8.10 CREATING AN OEM INSTANTIATION

**8.10.1** An OEM instantiation shall be delimited with the `<oem></oem>` root element tags using the standard attributes documented in 8.3.

**8.10.2** The final attributes of the `<oem>` tag shall be 'id' and 'version'.

**8.10.3** The 'id' attribute shall be 'id="CCSDS\_OEM\_VERS"'.

**8.10.4** The 'version' attribute for the version of the OEM described in Section 5 shall be 'version="3.0"'.

**8.10.5** The standard NDM header shall follow the `<oem>` tag- (see 8.4).

**8.10.6** The OEM `<body>` shall consist of one or more `<segment>` constructs.

**8.10.7** Each `<segment>` shall consist of a `<metadata>` section and a `<data>` section.

**8.10.8** The keywords in the `<metadata>` and `<data>` sections shall be those specified in Section 5. The rules for including any of the keyword tags in the OEM/XML are the same as those specified for the OEM in Section 5.

**8.10.9** Tags for keywords specified in Section 5 shall be all uppercase.

**8.10.10** Several of the OEM/XML keywords may have the unit attribute.

**8.10.11** In all cases, the units shall match those defined in Section 5.

**8.10.108.10.12** In addition to the OEM keywords specified in Section 5, there are some special tags associated with the OEM body as described in the next Sections.

**8.10.118.10.13** The `<stateVector>` tag shall encapsulate the keywords associated with one of the ephemeris data lines in the OEM.

**8.10.128.10.14** In the XML representation of the OEM, the components of the `<stateVector>` ephemeris data line must be represented with keywords (i.e., a tag).

**8.10.138.10.15** The `<stateVector>` keywords shall be the same as those defined for the same construct in the OPM.

**8.10.148.10.16** The ~~ODMOEM~~OEM/XML tags used within the `<stateVector>` structure shall be drawn from the following table:

OEM Tag	Represents	Example
<EPOCH>	time tag of the state	<EPOCH>2007-09-20T17:41:00</EPOCH>
<X>	x component of position	<X units="km">6678.0</X>
<Y>	y component of position	<Y units="km">0.0</Y>
<Z>	z component of position	<Z units="km">0.0</Z>
<X_DOT>	x component of velocity	<X_DOT units="km/s">0</X_DOT>
<Y_DOT>	y component of velocity	<Y_DOT units="km/s">7.73</Y_DOT>
<Z_DOT>	z component of velocity	<Z_DOT units="km/s">0.0</Z_DOT>
<X_DDOT>	x component of acceleration	<X_DDOT units="km/s**2">0.0</X_DDOT>
<Y_DDOT>	y component of acceleration	<Y_DDOT units="km/s**2">0.50</Y_DDOT>
<Z_DDOT>	z component of acceleration	<Z_DDOT units="km/s**2">0.0</Z_DDOT>

**8.10.158.10.17** Between the begin tag and end tag (i.e., between <stateVector> and </stateVector>), the user shall place the values required by the ephemeris data line as specified in Section 5.

**8.10.168.10.18** Since the state vector structure is shared by the OPM schema and OEM schema, units may optionally appear in the XML version of the OEM ephemeris data line.

**8.10.178.10.19** The <covarianceMatrix> tag shall encapsulate the keywords associated with the covariance matrix lines in the OEM.

**8.10.188.10.20** In the XML representation of the OEM, the covariance data line must be represented with keywords (i.e., a tag).

**8.10.198.10.21** The OEM <covarianceMatrix> keywords shall be the same as those defined for the same construct in the OPM and OMM.

NOTE – In the KVN representations of the OEM covariance matrix data lines, keywords are not used. Rather, the components of the covariance matrix data line appear in an order defined in Section 5. Similarly, units are not used in the KVN version of the OEM covariance matrix; however, they are optional in the OPM and OMM.

**8.10.208.10.22** Since the covariance matrix structure is shared by the OPM, OMM and OEM, units may optionally appear in the XML version of the OEM covariance matrix line.

**8.10.218.10.23** The OEM/XML tags used within the <covarianceMatrix> structure shall be drawn from the following table:

Keyword	Units	Example
CX_X, CY_X, CY_Y, CZ_X, CZ_Y, CZ_Z	km**2	<CX_X units="km**2">numeric-value</CX_X>
CX_DOT_X, CX_DOT_Y, CX_DOT_Z, CY_DOT_X, CY_DOT_Y, CY_DOT_Z, CZ_DOT_X, CZ_DOT_Y, CZ_DOT_Z	km**2/s	<CX_DOT_X units="km**2/s">numeric-value</CX_DOT_X>
CX_DOT_X_DOT, CY_DOT_X_DOT, CY_DOT_Y_DOT, CZ_DOT_X_DOT, CZ_DOT_Y_DOT, CZ_DOT_Z_DOT	km**2/s**2	<CX_DOT_X_DOT units="km**2/s**2">numeric-value</CX_DOT_X_DOT>

**8.10.228.10.24** Between the begin tag and end tag (i.e., between <covarianceMatrix> and </covarianceMatrix>), the user shall place the values required by the covariance matrix line type as specified in Section 5.

## 8.11 CREATING AN OCM INSTANTIATION

**8.11.1** An OCM instantiation shall be delimited with the <ocm></ocm> root element tags using the standard attributes documented in 8.3.

**8.11.2** The final attributes of the <ocm> tag shall be 'id' and 'version'.

**8.11.3** The 'id' attribute shall be 'id="CCSDS\_OCM\_VERS"'.

**8.11.4** The 'version' attribute for the version of the OCM described in Section 6 shall be 'version="3.0"'.

**8.11.5** The standard NDM header shall follow the <ocm> tag- (see 8.4).

**8.11.6** The OCM <body> shall consist of a single <segment> construct.

**8.11.7** The <segment> shall consist of a <metadata> section and a <data> section.

**8.11.8** The keywords in the <metadata> and <data> sections shall be those specified in Section 6. The rules for including any of the keyword tags in the OCM/XML are the same as those specified for the OCM in Section 6.

**8.11.9** Tags for keywords specified in Section 6 shall be all uppercase.

**8.11.10** Several of the OCM/XML keywords may have the unit attribute.

**8.11.11** In all cases, the units shall match those defined in the tables in Section 6.

**8.11.10/8.11.12** In addition to the OCM keywords specified in Section 6, there are some special tags associated with the OCM body as described in the next Sections.

~~8.11.11 TBD~~

~~8.11.12 TBD~~

~~8.11.13 TBD~~

~~8.11.14 The OCM/XML tags used within the <tbd> structure shall be drawn from the following table:~~

<u>OCM TagSection</u>	<u>RepresentsAssociated ODM/XML OCM Tag</u>	<u>ExampleData Line Tag</u>
<del>&lt;tbd&gt;Orbit Data</del>	<del>tbd&lt;orbitState&gt;</del>	<del>&lt;tbd units="tbd"&gt;tbd&lt;/tbd&gt;&lt;orbitLines&gt;</del>
<del>Space Object Physical Description</del>	<del>&lt;physicalDescription&gt;</del>	<del>N/A</del>

<u>Covariance Data</u>	<u>&lt;covarianceMatrix&gt;</u>	<u>&lt;covarianceLines&gt;</u>
<u>State Transition Matrix Data</u>	<u>&lt;stateTransitionMatrix&gt;</u>	<u>&lt;stmLines</u>
<u>Maneuver Data</u>	<u>&lt;maneuverParameters&gt;</u>	<u>maneuverLines</u>
<u>Perturbations Parameters</u>	<u>&lt;perturbations&gt;</u>	<u>N/A</u>
<u>Orbit Determination Data</u>	<u>&lt;odParameters&gt;</u>	<u>N/A</u>
<u>User-Defined Parameters</u>	<u>&lt;userDefinedParameters&gt;</u>	<u>N/A</u>

~~8.10.23~~ Between the begin tag and end tag (e.g., between ~~<tbid>~~ and ~~</tbid>~~), the user shall place the values required by the TBD data line as specified in Section 6.

~~8.10.24~~ In the XML representation of the OCM, the ~~tbid~~ data line must be represented with keywords (i.e., a tag).

~~8.10.25~~ A sample OCM/XML follows:

**8.10.25** In the XML representation of the OCM, the tbid data line must be represented with keywords (i.e., a tag). [NOTE TO DAN: We should discuss whether we depend on the user to parse a string delimited with spaces (e.g., an "orbitLine") based on the ORB\_TYPE selected from the SANA registry, or whether we want to develop the XML tags for all of those orbit types (and the several other data lines that have complex structure). Right now in the schema I have "orbitLine", "maneuverLine", "covarianceLine", "stmLine" as a tag, after which is an unstructured string (structure supplied according to the applicable registry). It will be a huge job to break all those apart in XML. Could be done, but want to discuss before embarking on that path.]

## 8.12 CREATING A COMBINED INSTANTIATION

For instructions on creating a combined instantiation, e.g., one that incorporates multiple ODM/XML messages or an ODM/XML message combined with other navigation related messages, see reference [4].

```

<?xml version="1.0" encoding="UTF-8"?>
<oem xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:noNamespaceSchemaLocation="http://sanaregistry.org/r/ndmxml/ndmxml-1.0-master.xsd"
  id="CCSDS_OEM_VERS" version="3.0">
  <header>
    <COMMENT>THIS EXAMPLE IS TBD</COMMENT>
    <CREATION_DATE>2017-11-04T17:22:31</CREATION_DATE>
    <ORIGINATOR>NASA</ORIGINATOR>
  </header>
  <body>
    <segment>
      <metadata>
        </metadata>
      <data>
        </data>
    </segment>
  </body>
</oem>

```

## ANNEX A

**IMPLEMENTATION  
CONFORMANCE****STATEMENT PRO FORMA****(NORMATIVE)****A1 INTRODUCTION****A1.1 OVERVIEW**

This annex provides the Implementation Conformance Statement (ICS) Requirements List (RL) for an implementation of the Orbit Data Messages (CCSDS 502.0). The ICS for an implementation is generated by completing the RL in accordance with the instructions below. An implementation shall satisfy the mandatory conformance requirements referenced in the RL.

- The RL in this annex is blank. An implementation's completed RL is called the ICS. The ICS states which capabilities and options have been implemented. The following can use the ICS:
  - the implementer, as a checklist to reduce the risk of failure to conform to the standard through oversight;
  - a supplier or potential acquirer of the implementation, as a detailed indication of the capabilities of the implementation, stated relative to the common basis for understanding provided by the standard ICS proforma;
  - a user or potential user of the implementation, as a basis for initially checking the possibility of interworking with another implementation (it should be noted that, while interworking can never be guaranteed, failure to interwork can often be predicted from incompatible ICS lists);
  - a tester, as the basis for selecting appropriate tests against which to assess the claim for conformance of the implementation.

**A1.2 ABBREVIATIONS AND CONVENTIONS**

The RL consists of information in tabular form. The status of features is indicated using the abbreviations and conventions described below.

Item Column

The item column contains sequential numbers for items in the table.

Feature Column

The feature column contains a brief descriptive name for a feature. It implicitly means “Is this feature supported by the implementation?”

Status Column

The status column uses the following notations:

- M            mandatory;
- O            optional;
- C            conditional;
- X            prohibited;
- I            out of scope;
- N/A         not applicable.

Support Column Symbols

The support column is to be used by the implementer to state whether a feature is supported by entering Y, N, or N/A, indicating:

- Y        Yes, supported by the implementation.
- N        No, not supported by the implementation.
- N/A     Not applicable.

The support column should also be used, when appropriate, to enter values supported for a given capability.

**A1.3 INSTRUCTIONS FOR COMPLETING THE RL**

An implementer shows the extent of compliance to the Recommended Standard by completing the RL; that is, the state of compliance with all mandatory requirements and the options supported are shown. The resulting completed RL is called an ICS. The implementer shall complete the RL by entering appropriate responses in the support or values supported column, using the notation described in A1.2. If a conditional requirement is inapplicable, N/A should be used. If a mandatory requirement is not satisfied, exception information must be supplied by entering a reference  $X_i$ , where  $i$  is a unique identifier, to an accompanying rationale for the noncompliance.

## A2 ICS PROFORMA FOR ORBIT DATA MESSAGES

### A2.1 IDENTIFICATION OF ICS

Date of Statement (DD/MM/YYYY)	
ICS serial number	
System Conformance statement cross-reference	

### A2.2 IDENTIFICATION OF IMPLEMENTATION UNDER TEST (IUT )

Implementation name	
Implementation version	
Special Configuration	
Other Information	

### A2.3 IDENTIFICATION OF SUPPLIES

Supplier	
Contact Point for Queries	
Implementation Name(s) and Versions	
Other information necessary for full identification, e.g., name(s) and version(s) for machines and/or operating systems; System Name(s)	

### A2.4 DOCUMENT VERSIONS

CCSDS 502.0 Document Version	P2-383
<p>Have any exceptions been required?</p> <p>(Note: A YES answer means that the implementation does not conform to the Recommended Standard. Non-supported mandatory capabilities are to be identified in the ICS, with an explanation of why the implementation is non-conforming.)</p>	<p>Yes _____ No_____</p>

## A2.5 REQUIREMENTS LISTS

[See CCSDS A20.1-Y-1, *CCSDS Implementation Conformance Statements* (Yellow Book, Issue 1, April 2014).]

### A2.6 ORBIT PARAMETER MESSAGE REQUIREMENTS LIST

Note to Tom Gannett: this section should probably be A2.5.1 (Annex level three) but the line type is not defined and I'm not confident I know how to do that.

Item	Feature	Keyword	Reference ( <del>Blue</del> book)	Status (M/O/...)	Support
<u>1</u>	<u>OPM Header</u>	<u>N/A</u>	<u>Table 3-1</u>	<u>M</u>	
<u>2</u>	<u>OPM Version</u>	<u>CCSDS_OPM_VERS</u>	<u>Table 3-1</u>	<u>M</u>	
<u>3</u>	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-1</u>	<u>O</u>	
<u>4</u>	<u>Message creation date and time</u>	<u>CREATION_DATE</u>	<u>Table 3-1</u>	<u>M</u>	
<u>5</u>	<u>Message originator</u>	<u>ORIGINATOR</u>	<u>Table 3-1</u>	<u>M</u>	
<u>6</u>	<u>Unique message identifier</u>	<u>MESSAGE_ID</u>	<u>Table 3-1</u>	<u>O</u>	
<u>7</u>	<u>OPM Metadata</u>	<u>N/A</u>	<u>Table 3-2</u>	<u>M</u>	
<u>8</u>	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-2</u>	<u>O</u>	
<u>9</u>	<u>Name of space object</u>	<u>OBJECT_NAME</u>	<u>Table 3-2</u>	<u>M</u>	
<u>10</u>	<u>Identifier of space object</u>	<u>OBJECT_ID</u>	<u>Table 3-2</u>	<u>M</u>	
<u>11</u>	<u>Orbit center</u>	<u>CENTER_NAME</u>	<u>Table 3-2</u>	<u>M</u>	
<u>12</u>	<u>Reference frame</u>	<u>REF_FRAME</u>	<u>Table 3-2</u>	<u>M</u>	
<u>13</u>	<u>Epoch of reference frame</u>	<u>REF_FRAME_EPOCH</u>	<u>Table 3-2</u>	<u>O</u>	
<u>14</u>	<u>Time system applicable to data</u>	<u>TIME_SYSTEM</u>	<u>Table 3-2</u>	<u>M</u>	
<u>15</u>	<u>OPM Data</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>M</u>	
<u>16</u>	<u>State Vector logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>M</u>	
<u>17</u>	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-3</u>	<u>O</u>	
<u>18</u>	<u>Epoch of the state vector</u>	<u>EPOCH</u>	<u>Table 3-3</u>	<u>M</u>	
<u>19</u>	<u>X component of position</u>	<u>X</u>	<u>Table 3-3</u>	<u>M</u>	
<u>20</u>	<u>Y component of position</u>	<u>Y</u>	<u>Table 3-3</u>	<u>M</u>	
<u>21</u>	<u>Z component of position</u>	<u>Z</u>	<u>Table 3-3</u>	<u>M</u>	
<u>22</u>	<u>X component of velocity</u>	<u>X_DOT</u>	<u>Table 3-3</u>	<u>M</u>	
<u>23</u>	<u>Y component of velocity</u>	<u>Y_DOT</u>	<u>Table 3-3</u>	<u>M</u>	
<u>24</u>	<u>Z component of velocity</u>	<u>Z_DOT</u>	<u>Table 3-3</u>	<u>M</u>	

<u>25</u>	<u>Keplerian Elements logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>M</u>	
<u>26</u>	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-3</u>	<u>O</u>	
<u>27</u>	<u>Semi-major axis of orbit</u>	<u>SEMI_MAJOR_AXIS</u>	<u>Table 3-3</u>	<u>O</u>	
<u>28</u>	<u>Eccentricity of orbit</u>	<u>ECCENTRICITY</u>	<u>Table 3-3</u>	<u>O</u>	
<u>29</u>	<u>Inclination of orbit</u>	<u>INCLINATION</u>	<u>Table 3-3</u>	<u>O</u>	
<u>30</u>	<u>Right ascension of ascending node of orbit</u>	<u>RA OF ASC NODE</u>	<u>Table 3-3</u>	<u>O</u>	
<u>31</u>	<u>Argument of pericenter of orbit</u>	<u>ARG OF PERICENTER</u>	<u>Table 3-3</u>	<u>O</u>	
<u>32</u>	<u>True or mean anomaly of orbit</u>	<u>TRUE ANOMALY</u> or <u>MEAN ANOMALY</u>	<u>Table 3-3</u>	<u>O</u>	
<u>33</u>	<u>Gravitational coefficient of the central body</u>	<u>GM</u>	<u>Table 3-3</u>	<u>O</u>	
<u>34</u>	<u>Spacecraft Parameters logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>M</u>	
<u>35</u>	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-3</u>	<u>O</u>	
<u>36</u>	<u>Mass of the spacecraft</u>	<u>MASS</u>	<u>Table 3-3</u>	<u>O</u>	
<u>37</u>	<u>Solar radiation area of the spacecraft</u>	<u>SOLAR_RAD_AREA</u>	<u>Table 3-3</u>	<u>O</u>	
<u>38</u>	<u>Solar radiation coefficient of the spacecraft</u>	<u>SOLAR_RAD_COEFF</u>	<u>Table 3-3</u>	<u>O</u>	
<u>39</u>	<u>Drag area of the spacecraft</u>	<u>DRAG_AREA</u>	<u>Table 3-3</u>	<u>O</u>	
<u>40</u>	<u>Drag coefficient of the spacecraft</u>	<u>DRAG_COEFF</u>	<u>Table 3-3</u>	<u>O</u>	
<u>41</u>	<u>Position/velocity Covariance Matrix logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>O</u>	
<u>42</u>	<u>Covariance matrix [1,1]</u>	<u>CX_X</u>	<u>Table 3-3</u>	<u>O</u>	
<u>43</u>	<u>Covariance matrix [2,1]</u>	<u>CY_X</u>	<u>Table 3-3</u>	<u>O</u>	
<u>44</u>	<u>Covariance matrix [2,2]</u>	<u>CY_Y</u>	<u>Table 3-3</u>	<u>O</u>	
<u>45</u>	<u>Covariance matrix [3,1]</u>	<u>CZ_X</u>	<u>Table 3-3</u>	<u>O</u>	
<u>46</u>	<u>Covariance matrix [3,2]</u>	<u>CZ_Y</u>	<u>Table 3-3</u>	<u>O</u>	
<u>47</u>	<u>Covariance matrix [3,3]</u>	<u>CZ_Z</u>	<u>Table 3-3</u>	<u>O</u>	
<u>48</u>	<u>Covariance matrix [4,1]</u>	<u>CX_DOT_X</u>	<u>Table 3-3</u>	<u>O</u>	
<u>49</u>	<u>Covariance matrix [4,2]</u>	<u>CX_DOT_Y</u>	<u>Table 3-3</u>	<u>O</u>	
<u>50</u>	<u>Covariance matrix [4,3]</u>	<u>CX_DOT_Z</u>	<u>Table 3-3</u>	<u>O</u>	

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51	<u>Covariance matrix [4,4]</u>	<u>CX_DOT_X_DOT</u>	<u>Table 3-3</u>	<u>O</u>	
52	<u>Covariance matrix [5,1]</u>	<u>CY_DOT_X</u>	<u>Table 3-3</u>	<u>O</u>	
53	<u>Covariance matrix [5,2]</u>	<u>CY_DOT_Y</u>	<u>Table 3-3</u>	<u>O</u>	
54	<u>Covariance matrix [5,3]</u>	<u>CY_DOT_Z</u>	<u>Table 3-3</u>	<u>O</u>	
55	<u>Covariance matrix [5,4]</u>	<u>CY_DOT_X_DOT</u>	<u>Table 3-3</u>	<u>O</u>	
56	<u>Covariance matrix [5,5]</u>	<u>CY_DOT_Y_DOT</u>	<u>Table 3-3</u>	<u>O</u>	
57	<u>Covariance matrix [6,1]</u>	<u>CZ_DOT_X</u>	<u>Table 3-3</u>	<u>O</u>	
58	<u>Covariance matrix [6,2]</u>	<u>CZ_DOT_Y</u>	<u>Table 3-3</u>	<u>O</u>	
59	<u>Covariance matrix [6,3]</u>	<u>CZ_DOT_Z</u>	<u>Table 3-3</u>	<u>O</u>	
60	<u>Covariance matrix [6,4]</u>	<u>CZ_DOT_X_DOT</u>	<u>Table 3-3</u>	<u>O</u>	
61	<u>Covariance matrix [6,5]</u>	<u>CZ_DOT_Y_DOT</u>	<u>Table 3-3</u>	<u>O</u>	
62	<u>Covariance matrix [6,6]</u>	<u>CZ_DOT_Z_DOT</u>	<u>Table 3-3</u>	<u>O</u>	
63	<u>Maneuver Parameters logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>O</u>	
64	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-3</u>	<u>O</u>	
65	<u>Time of maneuver start</u>	<u>MAN_EPOCH_IGNITION</u>	<u>Table 3-3</u>	<u>O</u>	
66	<u>Duration of maneuver</u>	<u>MAN_DURATION</u>	<u>Table 3-3</u>	<u>O</u>	
67	<u>Change of mass due to maneuver</u>	<u>MAN_DELTA_MASS</u>	<u>Table 3-3</u>	<u>O</u>	
68	<u>Relevant reference frame for maneuver</u>	<u>MAN_REF_FRAME</u>	<u>Table 3-3</u>	<u>O</u>	
69	<u>X component of velocity change</u>	<u>MAN_DV_1</u>	<u>Table 3-3</u>	<u>O</u>	
70	<u>Y component of velocity change</u>	<u>MAN_DV_2</u>	<u>Table 3-3</u>	<u>O</u>	
71	<u>Z component of velocity change</u>	<u>MAN_DV_3</u>	<u>Table 3-3</u>	<u>O</u>	
72	<u>User Defined Parameters logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>O</u>	
73	<u>As defined by user, "essential information that cannot be conveyed in COMMENT statements"</u>	<u>USER_DEFINED_x</u>	<u>Table 3-3</u>	<u>O</u>	

**A2.7 ORBIT MEAN ELEMENTS MESSAGE REQUIREMENTS LIST**

Note to Tom Gannett: this section should probably be A2.5.2 (Annex level three) but the line type is not defined and I'm not confident I know how to do that.

<u>Item</u>	<u>Feature</u>	<u>Keyword</u>	<u>Reference</u>	<u>Status (M/O)</u>	<u>Support</u>
<u>1</u>	<u>OPM Header</u>	<u>N/A</u>	<u>Table 3-1</u>	<u>M</u>	
<u>2</u>	<u>OPM Version</u>	<u>CCSDS OPM VERS</u>	<u>Table 3-1</u>	<u>M</u>	
<u>3</u>	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-1</u>	<u>O</u>	
<u>4</u>	<u>Message creation date and time</u>	<u>CREATION_DATE</u>	<u>Table 3-1</u>	<u>M</u>	
<u>5</u>	<u>Message originator</u>	<u>ORIGINATOR</u>	<u>Table 3-1</u>	<u>M</u>	
<u>6</u>	<u>Unique message identifier</u>	<u>MESSAGE_ID</u>	<u>Table 3-1</u>	<u>O</u>	
<u>7</u>	<u>OPM Metadata</u>	<u>N/A</u>	<u>Table 3-2</u>	<u>M</u>	
<u>8</u>	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-2</u>	<u>O</u>	
<u>9</u>	<u>Name of space object</u>	<u>OBJECT_NAME</u>	<u>Table 3-2</u>	<u>M</u>	
<u>10</u>	<u>Identifier of space object</u>	<u>OBJECT_ID</u>	<u>Table 3-2</u>	<u>M</u>	
<u>11</u>	<u>Orbit center</u>	<u>CENTER_NAME</u>	<u>Table 3-2</u>	<u>M</u>	
<u>12</u>	<u>Reference frame</u>	<u>REF_FRAME</u>	<u>Table 3-2</u>	<u>M</u>	
<u>13</u>	<u>Epoch of reference frame</u>	<u>REF_FRAME_EPOCH</u>	<u>Table 3-2</u>	<u>O</u>	
<u>14</u>	<u>Time system applicable to data</u>	<u>TIME_SYSTEM</u>	<u>Table 3-2</u>	<u>M</u>	
<u>15</u>	<u>OPM Data</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>M</u>	
<u>16</u>	<u>State Vector logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>M</u>	
<u>17</u>	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-3</u>	<u>O</u>	
<u>18</u>	<u>Epoch of the state vector</u>	<u>EPOCH</u>	<u>Table 3-3</u>	<u>M</u>	
<u>19</u>	<u>X component of position</u>	<u>X</u>	<u>Table 3-3</u>	<u>M</u>	
<u>20</u>	<u>Y component of position</u>	<u>Y</u>	<u>Table 3-3</u>	<u>M</u>	
<u>21</u>	<u>Z component of position</u>	<u>Z</u>	<u>Table 3-3</u>	<u>M</u>	
<u>22</u>	<u>X component of velocity</u>	<u>X_DOT</u>	<u>Table 3-3</u>	<u>M</u>	
<u>23</u>	<u>Y component of velocity</u>	<u>Y_DOT</u>	<u>Table 3-3</u>	<u>M</u>	
<u>24</u>	<u>Z component of velocity</u>	<u>Z_DOT</u>	<u>Table 3-3</u>	<u>M</u>	
<u>25</u>	<u>Keplerian Elements logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>M</u>	
<u>26</u>	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-3</u>	<u>O</u>	
<u>27</u>	<u>Semi-major axis of orbit</u>	<u>SEMI MAJOR AXIS</u>	<u>Table 3-3</u>	<u>O</u>	
<u>28</u>	<u>Eccentricity of orbit</u>	<u>ECCENTRICITY</u>	<u>Table 3-3</u>	<u>O</u>	

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

29	<u>Inclination of orbit</u>	<u>INCLINATION</u>	<u>Table 3-3</u>	<u>O</u>	
30	<u>Right ascension of ascending node of orbit</u>	<u>RA OF ASC NODE</u>	<u>Table 3-3</u>	<u>O</u>	
31	<u>Argument of pericenter of orbit</u>	<u>ARG OF PERICENTER</u>	<u>Table 3-3</u>	<u>O</u>	
32	<u>True or mean anomaly of orbit</u>	<u>TRUE ANOMALY</u> or <u>MEAN ANOMALY</u>	<u>Table 3-3</u>	<u>O</u>	
33	<u>Gravitational coefficient of the central body</u>	<u>GM</u>	<u>Table 3-3</u>	<u>O</u>	
34	<u>Spacecraft Parameters logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>M</u>	
35	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-3</u>	<u>O</u>	
36	<u>Mass of the spacecraft</u>	<u>MASS</u>	<u>Table 3-3</u>	<u>O</u>	
37	<u>Solar radiation area of the spacecraft</u>	<u>SOLAR RAD AREA</u>	<u>Table 3-3</u>	<u>O</u>	
38	<u>Solar radiation coefficient of the spacecraft</u>	<u>SOLAR RAD COEFF</u>	<u>Table 3-3</u>	<u>O</u>	
39	<u>Drag area of the spacecraft</u>	<u>DRAG AREA</u>	<u>Table 3-3</u>	<u>O</u>	
40	<u>Drag coefficient of the spacecraft</u>	<u>DRAG COEFF</u>	<u>Table 3-3</u>	<u>O</u>	
41	<u>Position/velocity Covariance Matrix logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>O</u>	
42	<u>Covariance matrix [1,1]</u>	<u>CX_X</u>	<u>Table 3-3</u>	<u>O</u>	
43	<u>Covariance matrix [2,1]</u>	<u>CY_X</u>	<u>Table 3-3</u>	<u>O</u>	
44	<u>Covariance matrix [2,2]</u>	<u>CY_Y</u>	<u>Table 3-3</u>	<u>O</u>	
45	<u>Covariance matrix [3,1]</u>	<u>CZ_X</u>	<u>Table 3-3</u>	<u>O</u>	
46	<u>Covariance matrix [3,2]</u>	<u>CZ_Y</u>	<u>Table 3-3</u>	<u>O</u>	
47	<u>Covariance matrix [3,3]</u>	<u>CZ_Z</u>	<u>Table 3-3</u>	<u>O</u>	
48	<u>Covariance matrix [4,1]</u>	<u>CX_DOT_X</u>	<u>Table 3-3</u>	<u>O</u>	
49	<u>Covariance matrix [4,2]</u>	<u>CX_DOT_Y</u>	<u>Table 3-3</u>	<u>O</u>	
50	<u>Covariance matrix [4,3]</u>	<u>CX_DOT_Z</u>	<u>Table 3-3</u>	<u>O</u>	
51	<u>Covariance matrix [4,4]</u>	<u>CX_DOT_X_DOT</u>	<u>Table 3-3</u>	<u>O</u>	
52	<u>Covariance matrix [5,1]</u>	<u>CY_DOT_X</u>	<u>Table 3-3</u>	<u>O</u>	
53	<u>Covariance matrix [5,2]</u>	<u>CY_DOT_Y</u>	<u>Table 3-3</u>	<u>O</u>	

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

54	<u>Covariance matrix</u> [5,3]	<u>CY DOT Z</u>	<u>Table 3-3</u>	<u>O</u>	
55	<u>Covariance matrix</u> [5,4]	<u>CY DOT X DOT</u>	<u>Table 3-3</u>	<u>O</u>	
56	<u>Covariance matrix</u> [5,5]	<u>CY DOT Y DOT</u>	<u>Table 3-3</u>	<u>O</u>	
57	<u>Covariance matrix</u> [6,1]	<u>CZ DOT X</u>	<u>Table 3-3</u>	<u>O</u>	
58	<u>Covariance matrix</u> [6,2]	<u>CZ DOT Y</u>	<u>Table 3-3</u>	<u>O</u>	
59	<u>Covariance matrix</u> [6,3]	<u>CZ DOT Z</u>	<u>Table 3-3</u>	<u>O</u>	
60	<u>Covariance matrix</u> [6,4]	<u>CZ DOT X DOT</u>	<u>Table 3-3</u>	<u>O</u>	
61	<u>Covariance matrix</u> [6,5]	<u>CZ DOT Y DOT</u>	<u>Table 3-3</u>	<u>O</u>	
62	<u>Covariance matrix</u> [6,6]	<u>CZ DOT Z DOT</u>	<u>Table 3-3</u>	<u>O</u>	
63	<u>Maneuver Parameters</u> <u>logical block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>O</u>	
64	<u>Comment</u>	<u>COMMENT</u>	<u>Table 3-3</u>	<u>O</u>	
65	<u>Time of maneuver</u> <u>start</u>	<u>MAN EPOCH IGNITION</u>	<u>Table 3-3</u>	<u>O</u>	
66	<u>Duration of</u> <u>maneuver</u>	<u>MAN DURATION</u>	<u>Table 3-3</u>	<u>O</u>	
67	<u>Change of mass</u> <u>due to maneuver</u>	<u>MAN DELTA MASS</u>	<u>Table 3-3</u>	<u>O</u>	
68	<u>Relevant reference</u> <u>frame for maneuver</u>	<u>MAN_REF_FRAME</u>	<u>Table 3-3</u>	<u>O</u>	
69	<u>X component of</u> <u>velocity change</u>	<u>MAN DV 1</u>	<u>Table 3-3</u>	<u>O</u>	
70	<u>Y component of</u> <u>velocity change</u>	<u>MAN DV 2</u>	<u>Table 3-3</u>	<u>O</u>	
71	<u>Z component of</u> <u>velocity change</u>	<u>MAN DV 3</u>	<u>Table 3-3</u>	<u>O</u>	
72	<u>User Defined</u> <u>Parameters logical</u> <u>block</u>	<u>N/A</u>	<u>Table 3-3</u>	<u>O</u>	
73	<u>As defined by user,</u> <u>"essential</u> <u>information that</u> <u>cannot be conveyed</u> <u>in COMMENT</u> <u>statements"</u>	<u>USER_DEFINED_x</u>	<u>Table 3-3</u>	<u>O</u>	

## ANNEX B

**NORMATIVE VALUES AND  
REFERENCES FOR  
TIMING SYSTEM,  
REFERENCE FRAME,  
ORBITAL ELEMENT, AND  
COVARIANCE-RELATED  
KEYWORDS**

**(NORMATIVE)**

The set of accepted values for Originators, Orbit Centers, time systems, reference frames, orbit-relative reference frames, spacecraft and attitude control reference frames, orbital elements and additional covariance element sets for all Orbit Data Messages (i.e., OPM, OMM, OEM and OCM) are discussed in this annex. These acceptable values are stored on the SANA Registry, globally accessible on the CCSDS SANA registry website located at: [https://sanaregistry.org/r/navigation\\_standard\\_normative\\_annexes](https://sanaregistry.org/r/navigation_standard_normative_annexes)

Exchange partners may submit additional (new) keywords for consideration of future inclusion into the SANA registry by submitting a detailed email request (mailto:info@sanaregistry.org) per ANNEX L, Section L2. The CCSDS Area or Working Group responsible for the maintenance of the ODM at the time of the request is the approval authority. Until a suggested value is included in the SANA registry, exchange partners may define and use values that are not listed in the SANA registry only if mutually agreed and properly documented ~~by an accompanying ICD.~~

## **B1 MESSAGE ORIGINATORS**

The set of acceptable values for the **ORIGINATOR** keyword ~~are~~**is** provided in ~~ANNEX B~~ normative reference [~~B-110~~].

## **B2 REFERENCE FRAME CENTER AND THIRD-BODY PERTURBATIONS**

The set of acceptable values for the reference frame center keywords (**CENTER\_NAME** for OPM, OEM, OMM and OCM, as well as **N\_BODY\_PERTURBATIONS**, **PERTFORBIT\_CENTER\_NAME**, **MAN\_CENTER\_NAME**, **STM\_CENTER\_NAME**, ~~**EC\_CENTER\_NAME**~~) ~~are~~**is** provided in ~~ANNEX B~~ normative reference [~~B-212~~].

Note that ~~this~~**these** values may also be useful to specify another platform (satellite, airframe, ground vehicle, etc.) as the reference frame origin to permit the specification of relative positional state time history data. In this case, message authors shall clearly communicate to recipients by ICD (as noted above) that the orbit center is not a gravitational center, that

propagation of ephemeris vectors or extrapolation of ephemeris start/stop states is not advisable, and that interpolation of state time histories should not be accomplished using classical orbit propagation forces, e.g., gravitational constants, drag.

### B3 TIME SYSTEMS

The set of acceptable values for the **TIME\_SYSTEM** keyword **areis** provided in ANNEX B normative reference [B-313].

For further details and description of time systems, see references [M-1] and [M-43].

### B4 REFERENCE FRAMES

The set of acceptable non-orbit-relative reference frame values for **\*\_REF\_FRAME** keyword are provided in ~~ANNEX B~~ normative reference [B-414].

### B5 ADDITIONAL ORBIT-RELATIVE REFERENCE FRAMES

In addition to the above reference frames, maneuver and covariance data **canmay** be specified in orbit-relative reference frames using **\*\_REF\_FRAME** keyword values provided in ~~ANNEX B~~ normative reference [B-515].

**Note that two types of orbit-relative local reference frames exist: inertial and rotating. When transforming velocity terms between inertial and rotating frames, remember to properly incorporate the  $(\bar{\omega} \times \bar{r})$  contribution.**

### B6 ADDITIONAL SPACECRAFT AND ATTITUDE REFERENCE FRAMES

An additional set of spacecraft and attitude control reference frames are acceptable as provided in ~~ANNEX B~~ normative reference [B-616]. Note that for many of these frames (particularly those that are spacecraft hardware-dependent), an ICD will likely be necessary to fully define and convey understanding of these frames.

### B7 ORBITAL ELEMENTS

The set of acceptable values for the **ORB\_TYPE** keyword **areis** provided in ~~ANNEX B~~ normative reference [B-717].

Unique to the Orbit Comprehensive Message (OCM), orbit element states and/or time histories may be specified in the following multiple element sets.

Orbit elements shall be interpreted as osculating elements unless either explicitly specified via the **ORB\_AVERAGING** keyword or pre-coordinated between the message originator and

recipient to contain mean elements (e.g. singly- or doubly-averaged elements based upon Kozai, Brouwer or other theories).

~~Non-inertial~~Inertial reference frames shall ~~not~~ be specified when employing inertial element sets.

~~Conversely~~When employing non-inertial element sets, inertial reference frames shall not be specified ~~when employing non-inertial element sets~~.

## **B8 ADDITIONAL COVARIANCE REPRESENTATIONS**

In addition to the above orbit element sets, covariance data ~~can~~may be specified in certain augmented element sets provided in ~~ANNEX B~~ normative reference [~~B-8~~18].

### ~~B9—NORMATIVE REFERENCES FOR TIMING SYSTEM, REFERENCE FRAME, ORBITAL ELEMENT, AND COVARIANCE RELATED KEYWORDS~~

~~[B-1] SANA Registry of Organizations: <https://sanaregistry.org/r/organizations>~~

~~[B-2] SANA Registry of Orbit Centers: [https://sanaregistry.org/r/orbit\\_centers](https://sanaregistry.org/r/orbit_centers)~~

~~[B-3] SANA Registry of Time Systems: [https://sanaregistry.org/r/time\\_systems](https://sanaregistry.org/r/time_systems)~~

~~[B-4] SANA Registry of Reference Frames: [https://sanaregistry.org/r/absolute\\_reference\\_frames](https://sanaregistry.org/r/absolute_reference_frames)~~

~~[B-5] SANA Registry of Orbit Relative Reference Frames:  
[https://sanaregistry.org/r/orbit\\_relative\\_reference\\_frames](https://sanaregistry.org/r/orbit_relative_reference_frames)~~

~~[B-6] SANA Registry of Spacecraft and Attitude Control Reference Frames:  
[https://sanaregistry.org/r/spacecraft\\_reference\\_frames](https://sanaregistry.org/r/spacecraft_reference_frames)~~

~~[B-7] SANA Registry of Orbital Elements: [https://sanaregistry.org/r/orbital\\_elements](https://sanaregistry.org/r/orbital_elements)~~

### ~~B9 [B-8] SANA REGISTRY OF COVARIANCE REPRESENTATIONS: HTTPS://SANAREGISTRY.ORG/R/COVARIANCE -REPRESENTATIONS-FRAMESATMOSPHERE MODELS~~

~~The set of acceptable values for the ATMOSPHERIC\_MODEL keyword is provided in normative reference [19].~~

## **B10 GRAVITY MODELS**

~~The set of acceptable values for the GRAVITY\_MODEL keyword is provided in normative reference [20].~~

**B11 OBJECT TYPES**

The set of acceptable values for the OBJECT\_TYPE keyword is provided in normative reference [21].

**B12 OPERATIONAL STATUS**

The set of acceptable values for the OPS\_STATUS keyword is provided in normative reference [22].

**B13 ORBIT AVERAGING TECHNIQUES**

The set of acceptable values for the ORB\_AVERAGING keyword is provided in normative reference [23].

**B14 ORBIT TYPES**

The set of acceptable values for the ORBIT\_TYPE keyword is provided in normative reference [24].

## ANNEX C

## TECHNICAL MATERIAL

## (INFORMATIVE)

C1 SATELLITE PHYSICAL CHARACTERISTICS SPECIFICATION  
(INFORMATIVE)

This section of the informative technical annex defines satellite dimensional and orientational parameters of the OCM's satellite physical characteristics specification.

To facilitate improved modeling of the physical space occupied by a space object, the space object's attitude, orientation, the probability of a hard body collision occurring, and drag and SRP acceleration forces, the OCM allows the specification of an “**Optimally-Encompassing Shape**” (OES). ~~Allowable OES types include BOX, ELLIPTICAL\_CYLINDER and ELLIPSOIDBox~~ (OEB). Note that the OEB describes the physical space occupied by the space object, which may or may not align with the inertia tensor for that object.

For a box-shaped satellite (e.g., a CubeSat) without appendages, the satellite and a corresponding ~~box-shaped OES~~OEB would be a one-to-one mapping.

For a satellite having solar arrays that extend from the spacecraft body structure, the ~~OES~~OEB would extend from the main satellite body to encompass the deployed solar arrays as well.

The ~~BOX and ELLIPSOID shapes are~~OEB shape is shown in Fig. C- 1 below. As illustrated, the ~~OES~~OEB reference frame axes (depicted in RED) are defined by convention as follows:

- The ~~OES~~OEB x-axis is along the **longest** dimension of the ~~OES~~box ( ~~$\hat{x}_{OES\_MAX}$~~  $\hat{x}_{OEB\_MAX}$ ). This is sometimes referred to the “span” of the space object.
- The ~~OES~~OEB y-axis is along the **intermediate** orthonormal dimension ( ~~$\hat{y}_{OES\_MED}$~~  $\hat{y}_{OEB\_MED}$ )
- The ~~OES~~OEB z-axis is along the **shortest** orthonormal dimension ( ~~$\hat{z}_{OES\_MIN}$~~  $\hat{z}_{OEB\_MIN}$ ).

The BOX shape can easily represent a cube by setting all orthonormal dimensions equal. In the event that the longest two or three orthonormal dimensions are equivalent, ~~the user shall select  $\hat{x}_{OES\_MAX}$~~  $\hat{x}_{OEB\_MAX}$  is defined as the direction along one of those longest dimensions and the next as  $\hat{y}_{OES\_MED}$ .

~~For the ELLIPSOID shape, note that the longest dimension (x-axis) corresponds to the major principal axis of the ellipsoid and the z-axis corresponds to the minor principal axis. This ellipsoid shape can easily represent a sphere by setting all principal axis dimensions equal.~~

In the event that the longest two or three principal axis dimensions of the ellipsoidbox are equivalent, ~~the user shall select  $\hat{x}_{OES\_MAX}$  as  $\hat{x}_{OEB\_MAX}$  is defined as~~ the direction along one of those longest principal dimensions and the next as  ~~$\hat{y}_{OES\_MED}$~~  $\hat{y}_{OEB\_MED}$ .

The OESOEB z-axis shall always be defined as:  $\hat{z}_{OES\_MIN}\hat{z}_{OEB\_MIN} = \hat{x}_{OES\_MAX}\hat{x}_{OEB\_MAX} \times \hat{y}_{OES\_MED}\hat{y}_{OEB\_MED}$ .

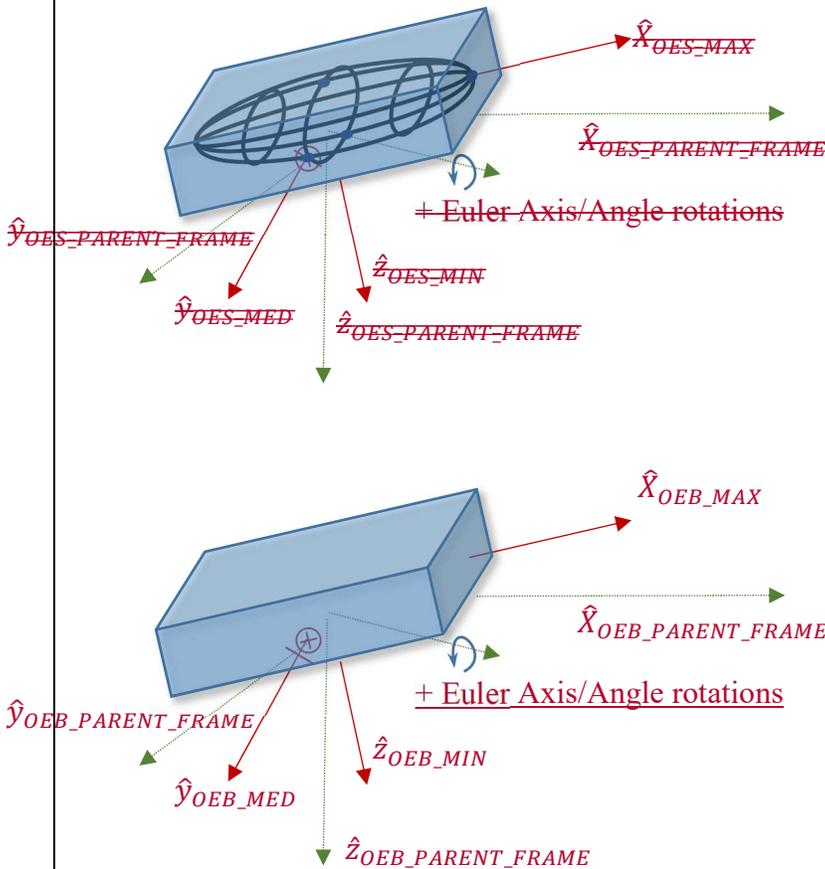


Fig. C- 1 Depiction of ~~BOX and ELLIPSOID~~ shape type Optimally-Enclosing Box and definitions of MAX, MED and MIN orientation vectors relative to OESOEB parent frame

The ELLIPTICAL\_CYLINDER shape type is shown in Fig. C- 2 below. As illustrated, the OES reference frame axes (depicted in RED) are defined by convention as follows:

- The OES x axis aligns with the cylindrical axis of rotation ( $\hat{x}_{OES\_MAX}$ ). Note that this direction may not coincide with the longest (span) direction, as was the case for the ~~BOX and ELLIPSOID~~ shapes.
- The OES y axis aligns with the longest of the two ellipse principal axes ( $\hat{y}_{OES\_MED}$ )
- The OES z axis is along the **shortest** of the two ellipse principal axes ( $\hat{z}_{OES\_MIN}$ ).

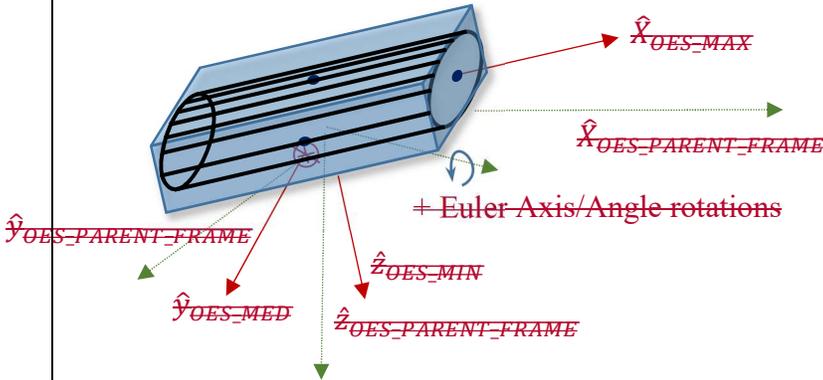


Fig. C-2 Depiction of ELLIPTICAL\_CYLINDER shape type and definitions of MAX, MED and MIN orientation vectors relative to OES parent frame

As was the case for the BOX and ELLIPSOID shapes, the ELLIPTICAL\_CYLINDER OES z-axis shall always be defined as:  $\hat{z}_{OES\_MIN} = \hat{x}_{OES\_MAX} \times \hat{y}_{OES\_MED}$ .

**NOTE: parent and body axis are shown in proximity to each other for display purposes only, but could generally be in any orientation as specified by the quaternion.**

A fixed orientation of the Optimally-Encompassing **ShapeBox** with respect to the user-specified “**OES\_OEB\_PARENT\_FRAME**” is defined using an ordered sequence of Euler rotations that map from the user-specified **OES\_OEB\_PARENT\_FRAME** to the Optimally-Encompassing **ShapeBox** vector directions. The above figure shows the proper definitions and adopted sign conventions for Yaw, Pitch and Roll angles. The resulting transformation sequence is:

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix}_{OES} = [M] \begin{bmatrix} x \\ y \\ z \end{bmatrix}_{OES\_PARENT\_FRAME}$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix}_{OEB} = [M] \begin{bmatrix} x \\ y \\ z \end{bmatrix}_{OEB\_PARENT\_FRAME}$$

Where the frame transformation matrix [M] is a function of the quaternion components

$$[M] = \begin{bmatrix} q_1^2 - q_2^2 - q_3^2 + q_c^2 & 2(q_1q_2 + q_3q_c) & 2(q_1q_3 - q_2q_c) \\ 2(q_1q_2 - q_3q_c) & -q_1^2 + q_2^2 - q_3^2 + q_c^2 & 2(q_2q_3 + q_1q_c) \\ 2(q_1q_3 + q_2q_c) & 2(q_2q_3 - q_1q_c) & -q_1^2 - q_2^2 + q_3^2 + q_c^2 \end{bmatrix}$$

The physical dimensions of the ΘESOEB (long, intermediate and short dimensions) are specified via ΘESOEB\_MAX, ΘESOEB\_MED and ΘESOEB\_MIN respectively.

The cross-sectional area as viewed along the ΘESOEB x, y and z axes (long, intermediate and short dimension directions) are specified via AREA\_ALONG\_ΘESOEB\_MAX, AREA\_ALONG\_ΘESOEB\_MED and AREA\_ALONG\_ΘESOEB\_MIN, respectively.

These projected areas can represent the actual cross-sectional area presented normal to each axis direction, which can be useful for drag and SRP force estimates. The use of a blending function allows force estimations along an arbitrary direction.

## C2 APPARENT-TO-ABSOLUTE VISUAL MAGNITUDE RELATIONSHIP (INFORMATIVE)

This section of the informative technical annex presents the relationships to be used to map apparent to absolute visual magnitude for inclusion in an OCM. These equations, based on reference [M-128], examine signal magnitude for reflected illumination by a Resident Space Object (RSO) that is exoatmospheric, meaning that its illumination by the Sun is not reduced or impeded by atmospheric transmission losses. The equations do not account for spatial distribution across multiple detectors, which involves characterizing the Point Spread Function of the system.

The equation for  $VM_{\text{absolute}}$  is not provided.

Definitions:

$E_{\text{EntranceAperture}}$	Target's specific entrance aperture radiance [ $W/m^2$ ]
$I_{\text{Sun}}$	Solar Intensity $\approx 3.088374161 \times 10^{25}$ [ $W$ ]
$d_{\text{SunToTarget}}$	Distance from the sun to the target (e.g. 1 AU = $1.4959787066 \times 10^{11}$ m)
$E_{\text{Sun}}$	Exoatmospheric solar irradiance, nominally 1380 [ $W/m^2$ ] at 1 AU
$\varphi$	Phase or Critical Angle to the Sun (CATS) from sun to the sensor, as shown in Fig. C- 2 and measured at the observed target [rad]
$Phase(\varphi)$	Geometric reflectance function [ <del>between</del> unitless, 0 and $\leq Phase(\varphi) \leq 1$ ]
$F$	General shadowing term accounting for the penumbra region's influence [ <del>unitless ratio between, 0 &lt; F &lt;= 1</del> ] <sup>[OD6]</sup> 0 = umbra and 1 = full Sun illumination]
$A_{\text{Target}}$	Effective area of the target [ $m^2$ ]
$\pi$	Pi constant
$\rho$	Reflectance of the target [between 0 (none) and 1 (perfect reflectance)]
$I_{\text{Target}}$	Intensity of reflected energy from target treated as a point source [ $W$ ]
$E_{\text{Target}}$	Target Irradiance at Sensor without atmospheric loss [ $W/m^2$ ] <sup>[DLO7]</sup>
$r_{\text{Target}}$	Effective radius of the target [ $m^2$ ] <sup>[DLO8]</sup>
$d_{\text{TargetToSensor}}$	Distance from target to sensor [ $m$ ]
$\tau_{\text{Atmosphere}}$	Atmospheric transmission [unitless <del>between, 0 and</del> $\tau \leq 1$ ]
$E_0$	Ref. Visual Magnitude (Vega) Irradiance [ $2.77894 \times 10^{-8}$ $W/m^2$ ]

Given an optical sensor's measured target entrance aperture radiance:

$$VM_{\text{apparent}} = -2.5 \log_{10} \frac{E_{\text{target}}}{E_0}, \text{ measured on the visual magnitude scale}$$

$$E_{\text{target}} = \frac{E_{\text{EntranceAperture}}}{\tau_{\text{Atmosphere}}(\theta)} \text{ [W/m}^2\text{]}$$

or if  $VM_{\text{apparent}}$  known:  $E_{\text{target}} = E_0 10^{\left[-\frac{VM_{\text{apparent}}}{2.5}\right]}$

$$I_{target} = E_{target} d_{TargetToSensor}^2 \text{ [W]}$$

$$E_{Sun} = \frac{I_{Sun}}{d_{SunToTarget}^2} \text{ [W/m}^2\text{]}$$

$$Phase(\varphi) = \frac{\sin \varphi + (\pi - \varphi) \cos \varphi}{\pi}$$

$$\rho A_{Target} = \frac{\pi I_{Target}}{E_{Sun} F Phase(\varphi)} \text{ [m}^2\text{]}$$

From the above equations,  $VM_{absolute}$  “normalized” to a 1 AU Sun-to-target distance, a phase angle of  $0^\circ$  and a 40,000 km target-to-sensor distance (equivalent to a GEO satellite tracked at  $15.6^\circ$  elevation above the optical site’s local horizon), is obtained as:

$$VM_{absolute} = -2.5 \log_{10} \left\{ \frac{[E_{Sun1AU=1380 W/m^2}] [Phase(0 rad)=1.0] [\rho A_{Target} \text{ from above, in } m^2]}{\pi [E_0=2.77894 \times 10^{-8} W/m^2] [1.6 \times 10^{15} m^2]} \right\}$$

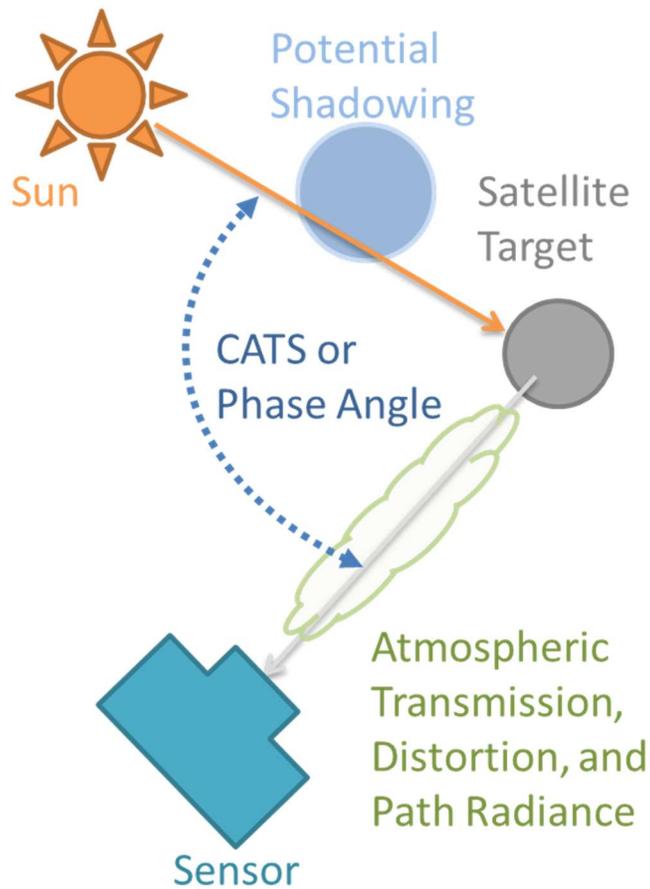


Fig. C-2 Depiction of optical viewing Critical Angle To the Sun (CATS) phase angle-geometry

### C3 MANEUVER AND DUTY CYCLE DIAGRAMS (INFORMATIVE)

This section of the informative technical annex defines ~~the relationships between~~ time-based, phase-angle-based and cone-based duty cycle parameters.

A “duty cycle” is a cycle of thruster operation which operates intermittently rather than continuously, having an “on” interval followed by an “off” interval.

Time-based duty cycle parameters define a window of duty cycle operations, the actual execution interval and “ON” and “OFF” intervals, as shown in Fig. C- 3.

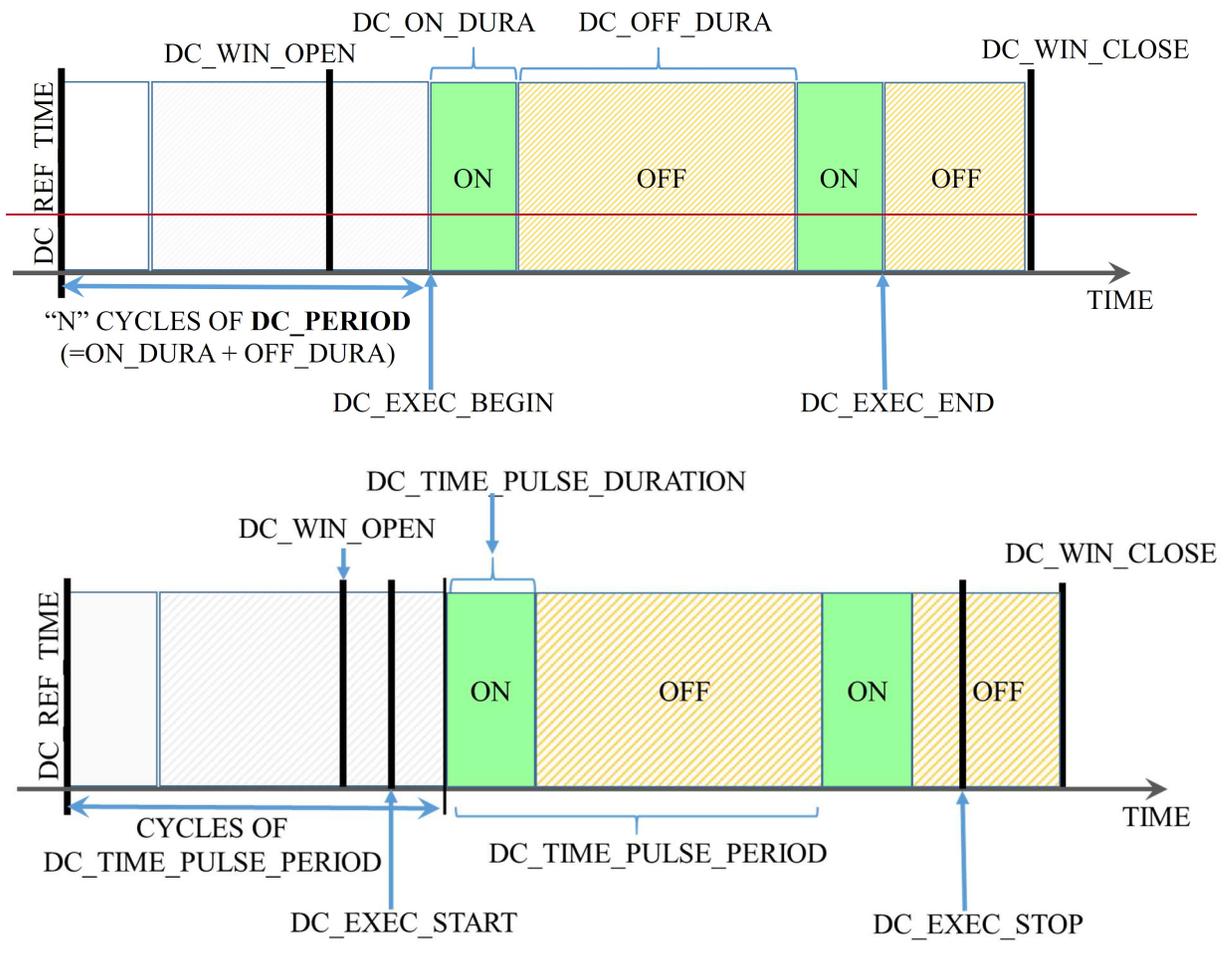
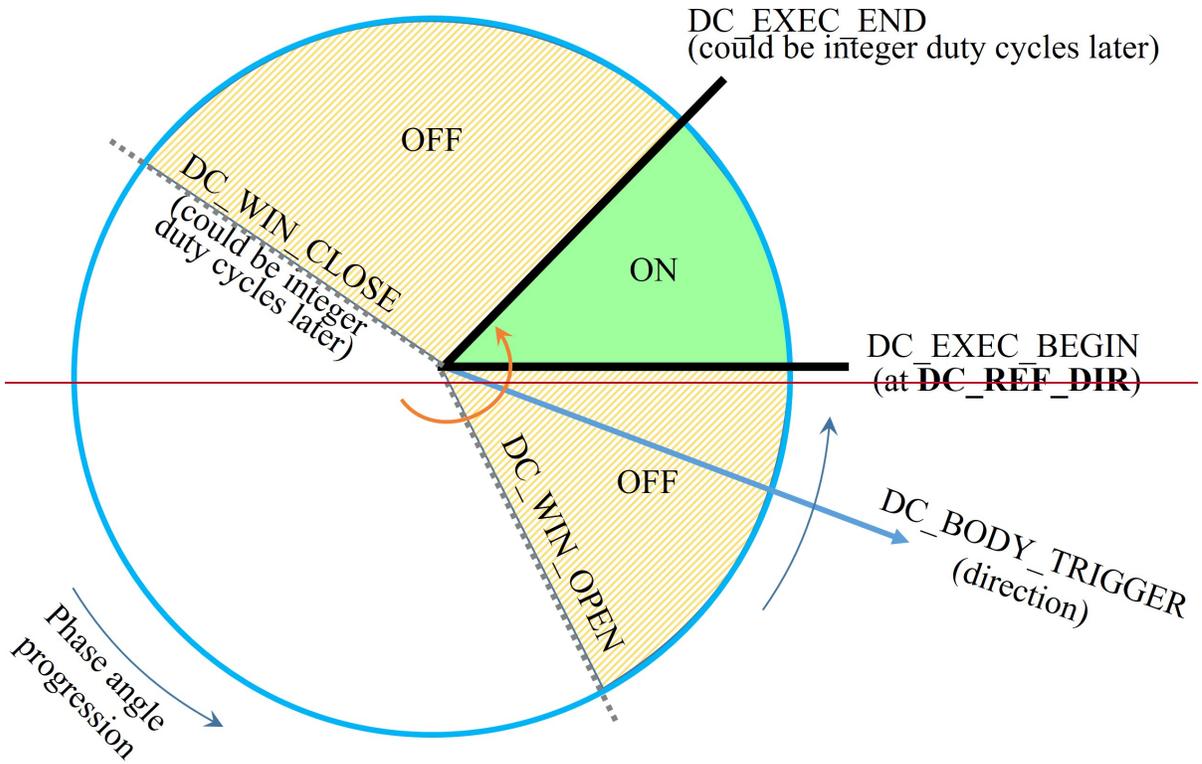


Fig. C- 3 Diagram of time-based duty cycle (~~MAN\_DUTY\_CYCLE\_TYPE~~ = “TIME”)



Angle-based duty cycle parameters also define a window of duty cycle operations and actual execution interval and “ON” and “OFF” intervals, but in this timecase the “ON” and “OFF” intervals are triggered by angular limits as shown in Fig. C- 4.

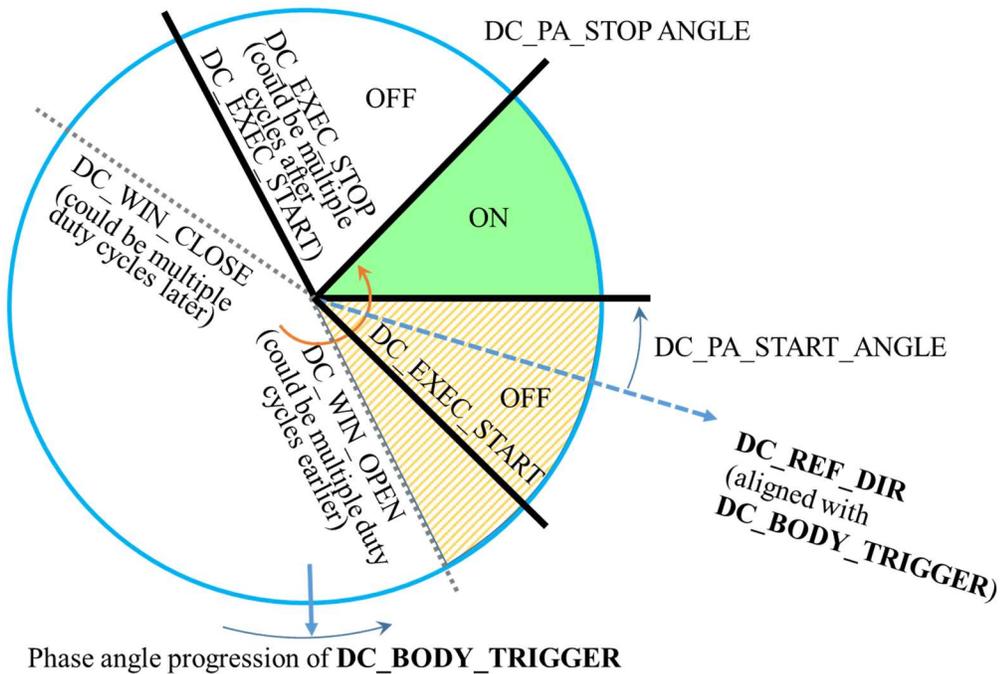


Fig. C- 4 Diagram of angle-based duty cycle (~~MAN\_DUTY\_CYCLE\_TYPE~~ = "PHASE\_ANGLE")

#### **C4 ORBIT DETERMINATION GENERALIZED DILUTION OF PRECISION (GDoP) FORMULATION (INFORMATIVE)**

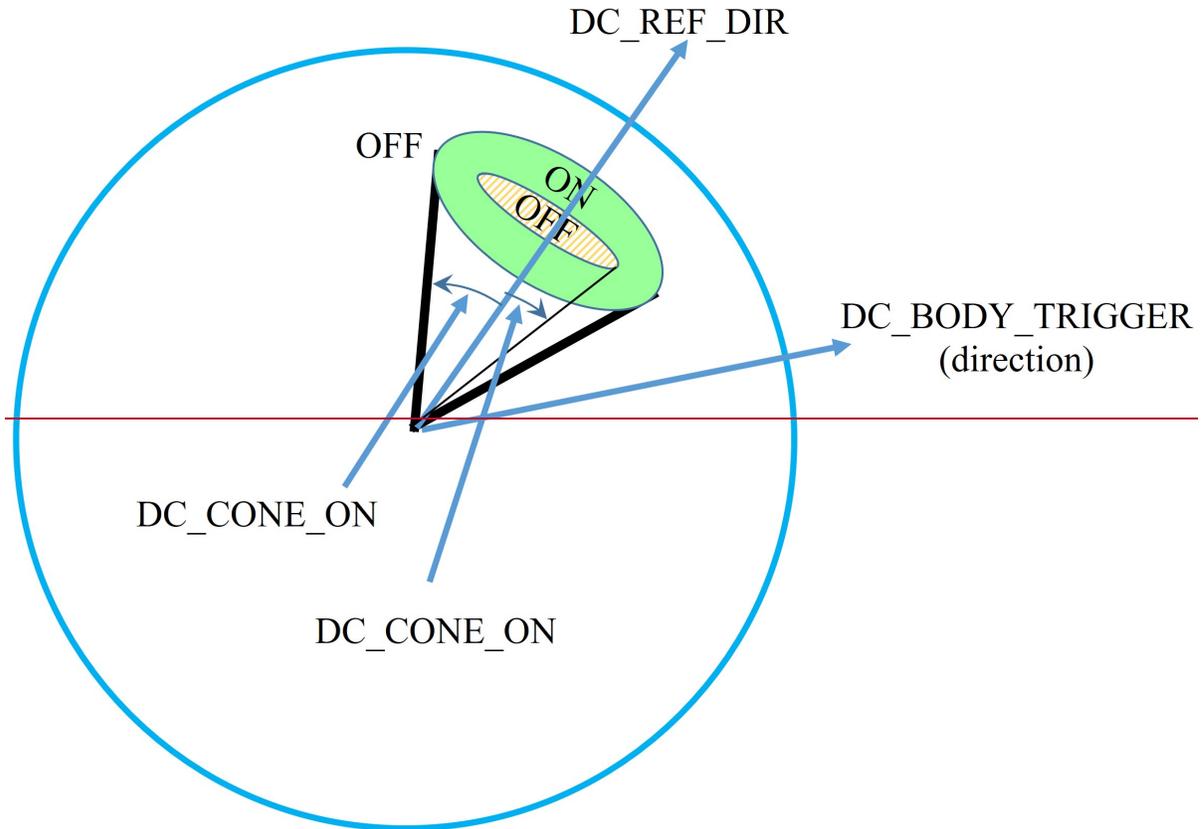
This section of the informative technical annex defines the generalized dilution of precision (GDoP) formulation used in the orbit determination section of the OCM.

As described in reference [M-11], Generalized Dilution of Precision (DoP) (GDoP) provides a method to assess the navigation performance over a time-integrated orbit solution. Generalized DoP broadens the DoP concept from the more common instantaneous geometric or kinematic solution of multiple transmit sources at one time, to a scenario associated with a receiver that is able to integrate metric range and/or Doppler (or range-rate) measurements over time, potentially from different transmit sources, to estimate the user's orbital position and velocity state. It is defined as a function of the sum of information matrices to obtain an observability gramian associated with a set of metric tracking measurements collected over a period of time.

The following equation for GDoP represents the uncertainty of an orbit state estimate as observed over time.

$$\sqrt{\max \left[ \text{eig} \left( \left( \sum_{t_0}^{t_n} \tilde{H}_0^T W \tilde{H}_0 \right)^{-1} \right) \right]}$$

~~Where Conical angle based duty cycle parameters also define a conical window of duty cycle operations and actual execution interval and "ON" and "OFF" intervals triggered by conical angle limits as shown in Fig. C-5.~~



*Fig. C-6 Diagram of Cone angle-based duty cycle (MAN\_DUTY\_CYCLE\_TYPE = CONE)*

H represents the measurement matrix modeled in the state estimate, and W is a diagonal matrix of relative weights that represents the accuracy of the measurements.  $\tilde{H}_0^T W \tilde{H}_0$  represents the information matrix, the inverse of which is the covariance matrix. By summing over time, one obtains an estimate of the state uncertainty from the time-derived measurement set.

## ANNEX D

## OPM EXAMPLES

## (INFORMATIVE)

The following are examples of Orbit Parameter Messages (OPMs).

## OPM examples in KVN:

The following figures are examples of OPMs in Keyword Value Notation (KVN) format. The first has only a state; the second has state, Keplerian elements, and maneuvers; the third and fourth include the position/velocity covariance matrix.

Fig. D-3 and Fig. D-4 include unique features of ODM version 2.0, and thus 'CCSDS\_OPM\_VERS = 2.0' (at a minimum) must be specified.

```

CCSDS_OPM_VERS = 3.0
CREATION_DATE  = 1998-11-06T09:23:57
ORIGINATOR     = JAXA

COMMENT        GEOCENTRIC, CARTESIAN, EARTH FIXED
OBJECT_NAME    = GODZILLAOSPREY 5
OBJECT_ID      = 1998-999A
CENTER_NAME    = EARTH
REF_FRAME      = ITRF2000
TIME_SYSTEM    = UTC

EPOCH =        1998-12-18T14:28:15.1172
X =           6503.514000
Y =           1239.647000
Z =           -717.490000
X_DOT =        -0.873160
Y_DOT =         8.740420
Z_DOT =        -4.191076
MASS =         3000.000000
SOLAR_RAD_AREA = 18.770000
SOLAR_RAD_COEFF = 1.000000
DRAG_AREA =    18.770000
DRAG_COEFF =   2.500000

```

~~Annex~~ Fig. D-1: Simple OPM file example

```

CCSDS_OPM_VERS      = 3.0

COMMENT  Generated by GSOC, R. Kiehling
COMMENT  Current intermediate orbit IO2 and maneuver planning data

CREATION_DATE       = 2000-06-03T05:33:00.000
ORIGINATOR          = GSOC

OBJECT_NAME         = EUTELSAT W4
OBJECT_ID           = 2000-028A
CENTER_NAME         = EARTH
REF_FRAME           = TOD
TIME_SYSTEM         = UTC

COMMENT  State Vector
EPOCH               = 2006-06-03T00:00:00.000
X                   = 6655.9942           [km]
Y                   = -40218.5751        [km]
Z                   = -82.9177           [km]
X_DOT               = 3.11548208         [km/s]
Y_DOT               = 0.47042605         [km/s]
Z_DOT               = -0.00101495        [km/s]

COMMENT  Keplerian elements
SEMI_MAJOR_AXIS     = 41399.5123         [km]
ECCENTRICITY        = 0.020842611
INCLINATION         = 0.117746           [deg]
RA_OF_ASC_NODE      = 17.604721         [deg]
ARG_OF_PERICENTER   = 218.242943        [deg]
TRUE_ANOMALY        = 41.922339         [deg]
GM                  = 398600.4415        [km**3/s**2]

COMMENT  Spacecraft parameters
MASS                = 1913.000           [kg]
SOLAR_RAD_AREA      = 10.000            [m**2]
SOLAR_RAD_COEFF     = 1.300
DRAG_AREA           = 10.000            [m**2]
DRAG_COEFF          = 2.300

COMMENT  2 planned maneuvers

COMMENT  First maneuver: AMF-3
COMMENT  Non-impulsive, thrust direction fixed in inertial frame
MAN_EPOCH_IGNITION = 2000-06-03T09:00:34.1
MAN_DURATION        = 132.60            [s]
MAN_DELTA_MASS      = -18.418           [kg]
MAN_REF_FRAME       = J2000
MAN_DV_1            = -0.02325700       [km/s]
MAN_DV_2            = 0.01683160        [km/s]
MAN_DV_3            = -0.00893444       [km/s]

COMMENT  Second maneuver: first station acquisition maneuver
COMMENT  impulsive, thrust direction fixed in RTN frame
MAN_EPOCH_IGNITION = 2000-06-05T18:59:21.0
MAN_DURATION        = 0.00              [s]
MAN_DELTA_MASS      = -1.469            [kg]
MAN_REF_FRAME       = RTN
MAN_DV_1            = 0.00101500        [km/s]
MAN_DV_2            = -0.00187300       [km/s]
MAN_DV_3            = 0.00000000        [km/s]

```

**Annex-~~Fig.~~ D-2: OPM file example with optional Keplerian elements and two maneuvers**

```

CCSDS_OPM_VERS = 3.0

CREATION_DATE = 1998-11-06T09:23:57
ORIGINATOR    = JAXA

COMMENT       GEOCENTRIC, CARTESIAN, EARTH FIXED
OBJECT_NAME   = GODZILLAOSPREY 5
OBJECT_ID     = 1998-999A
CENTER_NAME   = EARTH
REF_FRAME     = ITRF1997
TIME_SYSTEM   = UTC

EPOCH =      1998-12-18T14:28:15.1172
X =          6503.514000
Y =          1239.647000
Z =          -717.490000
X_DOT =      -0.873160
Y_DOT =       8.740420
Z_DOT =      -4.191076

MASS =        3000.000000
SOLAR_RAD_AREA = 18.770000
SOLAR_RAD_COEFF = 1.000000
DRAG_AREA =   18.770000
DRAG_COEFF =  2.500000

CX_X = 3.331349476038534e-04
CY_X = 4.618927349220216e-04
CY_Y = 6.782421679971363e-04
CZ_X = -3.070007847730449e-04
CZ_Y = -4.221234189514228e-04
CZ_Z = 3.231931992380369e-04
CX_DOT_X = -3.349365033922630e-07
CX_DOT_Y = -4.686084221046758e-07
CX_DOT_Z = 2.484949578400095e-07
CX_DOT_X_DOT = 4.296022805587290e-10
CY_DOT_X = -2.211832501084875e-07
CY_DOT_Y = -2.864186892102733e-07
CY_DOT_Z = 1.798098699846038e-07
CY_DOT_X_DOT = 2.608899201686016e-10
CY_DOT_Y_DOT = 1.767514756338532e-10
CZ_DOT_X = -3.041346050686871e-07
CZ_DOT_Y = -4.989496988610662e-07
CZ_DOT_Z = 3.540310904497689e-07
CZ_DOT_X_DOT = 1.869263192954590e-10
CZ_DOT_Y_DOT = 1.008862586240695e-10
CZ_DOT_Z_DOT = 6.224444338635500e-10
    
```

**Annex** Fig. D-3: OPM file example with covariance matrix

```

CCSDS_OPM_VERS = 3.0
COMMENT Generated by GSOC, R. Kiehling
COMMENT Current intermediate orbit IO2 and maneuver planning data
CREATION_DATE = 2000-06-03T05:33:00.000
ORIGINATOR = GSOC
OBJECT_NAME = EUTELSAT W4
OBJECT_ID = 2000-028A
CENTER_NAME = EARTH
REF_FRAME = TOD
TIME_SYSTEM = UTC
COMMENT State Vector
EPOCH = 2006-06-03T00:00:00.000
X = 6655.9942 [km]
Y = -40218.5751 [km]
Z = -82.9177 [km]
X_DOT = 3.11548208 [km/s]
Y_DOT = 0.47042605 [km/s]
Z_DOT = -0.00101495 [km/s]
COMMENT Keplerian elements
SEMI_MAJOR_AXIS = 41399.5123 [km]
ECCENTRICITY = 0.020842611
INCLINATION = 0.117746 [deg]
RA_OF_ASC_NODE = 17.604721 [deg]
ARG_OF_PERICENTER = 218.242943 [deg]
TRUE_ANOMALY = 41.922339 [deg]
GM = 398600.4415 [km**3/s**2]
COMMENT Spacecraft parameters
MASS = 1913.000 [kg]
SOLAR_RAD_AREA = 10.000 [m**2]
SOLAR_RAD_COEFF = 1.300
DRAG_AREA = 10.000 [m**2]
DRAG_COEFF = 2.300
COV_REF_FRAME = RTN
CX_X = 3.331349476038534e-04 [km**2]
CY_X = 4.618927349220216e-04 [km**2]
CY_Y = 6.782421679971363e-04 [km**2]
CZ_X = -3.070007847730449e-04 [km**2]
CZ_Y = -4.221234189514228e-04 [km**2]
CZ_Z = 3.231931992380369e-04 [km**2]
CX_DOT_X = -3.349365033922630e-07 [km**2/s]
CX_DOT_Y = -4.686084221046758e-07 [km**2/s]
CX_DOT_Z = 2.484949578400095e-07 [km**2/s]
CX_DOT_X_DOT = 4.296022805587290e-10 [km**2/s**2]
CY_DOT_X = -2.211832501084875e-07 [km**2/s]
CY_DOT_Y = -2.864186892102733e-07 [km**2/s]
CY_DOT_Z = 1.798098699846038e-07 [km**2/s]
CY_DOT_X_DOT = 2.608899201686016e-10 [km**2/s**2]
CY_DOT_Y_DOT = 1.767514756338532e-10 [km**2/s**2]
CZ_DOT_X = -3.041346050686871e-07 [km**2/s]
CZ_DOT_Y = -4.989496988610662e-07 [km**2/s]
CZ_DOT_Z = 3.540310904497689e-07 [km**2/s]
CZ_DOT_X_DOT = 1.869263192954590e-10 [km**2/s**2]
CZ_DOT_Y_DOT = 1.008862586240695e-10 [km**2/s**2]
CZ_DOT_Z_DOT = 6.224444338635500e-10 [km**2/s**2]
USER_DEFINED_EARTH_MODEL = WGS-84
    
```

**Annex-Fig. D-4: OPM file example with optional Keplerian elements, covariance matrix, and a user defined parameter**

OPM example in XML:

Fig. D-5 contains an example of an OPM in Extensible Markup Language (XML) format.

```

<?xml version="1.0" encoding="UTF-8"?>
<opm xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:noNamespaceSchemaLocation="http://sanaregistry.org/r/ndmxml/ndmxml-1.0-master.xsd"
  id="CCSDS_OPM_VERS" version="3.0">

  <header>
    <COMMENT>THIS EXAMPLE CONFORMS TO FIGURE 3-1 IN 502.0-B-2 IS AN XML VERSION OF THE
    OPM</COMMENT>
    <CREATION_DATE>2001-11-06T09:23:57</CREATION_DATE>
    <ORIGINATOR>JAXA</ORIGINATOR>
  </header>
  <body>
    <segment>
      <metadata>
        <COMMENT>GEOCENTRIC, CARTESIAN, EARTH FIXED</COMMENT>
        <OBJECT_NAME>GODZILLA<del>AOSPREY</del> 5</OBJECT_NAME>
        <OBJECT_ID>1998-999A</OBJECT_ID>
        <CENTER_NAME>EARTH</CENTER_NAME>
        <REF_FRAME>ITRF1997</REF_FRAME>
        <TIME_SYSTEM>UTC</TIME_SYSTEM>
      </metadata>
      <data>
        <COMMENT>OBJECT_ID: 1998-057A</COMMENT>
        <stateVector>
          <EPOCH>1996-12-18T14:28:15.1172</EPOCH>
          <X>6503.514000</X>
          <Y>1239.647000</Y>
          <Z>-717.490000</Z>
          <X_DOT>-0.873160</X_DOT>
          <Y_DOT>8.740420</Y_DOT>
          <Z_DOT>-4.191076</Z_DOT>
        </stateVector>
        <spacecraftParameters>
          <MASS>3000.000000</MASS>
          <SOLAR_RAD_AREA>18.770000</SOLAR_RAD_AREA>
          <SOLAR_RAD_COEFF>1.000000</SOLAR_RAD_COEFF>
          <DRAG_AREA>18.770000</DRAG_AREA>
          <DRAG_COEFF>2.500000</DRAG_COEFF>
        </spacecraftParameters>
        <covarianceMatrix>
          <COV_REF_FRAME>ITRF1997</COV_REF_FRAME>
          <CX_X>0.316</CX_X>
          <CY_X>0.722</CY_X>
          <CY_Y>0.518</CY_Y>
          <CZ_X>0.202</CZ_X>
          <CZ_Y>0.715</CZ_Y>
          <CZ_Z>0.002</CZ_Z>
          <CX_DOT_X>0.912</CX_DOT_X>
          <CX_DOT_Y>0.306</CX_DOT_Y>
          <CX_DOT_Z>0.276</CX_DOT_Z>
          <CX_DOT_X_DOT>0.797</CX_DOT_X_DOT>
          <CY_DOT_X>0.562</CY_DOT_X>
          <CY_DOT_Y>0.899</CY_DOT_Y>
          <CY_DOT_Z>0.022</CY_DOT_Z>
          <CY_DOT_X_DOT>0.079</CY_DOT_X_DOT>
          <CY_DOT_Y_DOT>0.415</CY_DOT_Y_DOT>
          <CZ_DOT_X>0.245</CZ_DOT_X>
          <CZ_DOT_Y>0.965</CZ_DOT_Y>
          <CZ_DOT_Z>0.950</CZ_DOT_Z>
          <CZ_DOT_X_DOT>0.435</CZ_DOT_X_DOT>
          <CZ_DOT_Y_DOT>0.621</CZ_DOT_Y_DOT>
          <CZ_DOT_Z_DOT>0.991</CZ_DOT_Z_DOT>
        </covarianceMatrix>
      </data>
    </segment>
  </body>
</opm>

```

Annex Fig. D-5: OPM file example in XML format

## ANNEX E

## OMM EXAMPLES

## (INFORMATIVE)

The following are examples of Orbit Mean-Element Messages (OMMs). All of these examples are based on the TLE shown in Fig. E-1.

```
GOES 9 [P]
1 23581U 95025A 07064.44075725 -.00000113 00000-0 10000-3 0 9250
2 23581 3.0539 81.7939 0005013 249.2363 150.1602 1.00273272 43169
```

**Annex Fig. E-1: Example Two Line Element Set (TLE)**

## OMM examples in KVN:

The following figures are examples of OMMs in Keyword Value Notation (KVN) format .

```
CCSDS_OMM_VERS = 3.0
CREATION_DATE = 2007-065T16:00:00
ORIGINATOR = NOAA/USA

OBJECT_NAME = GOES 9
OBJECT_ID = 1995-025A
CENTER_NAME = EARTH
REF_FRAME = TEME
TIME_SYSTEM = UTC
MEAN_ELEMENT_THEORY = SGP/SGP4

EPOCH = 2007-064T10:34:41.4264
MEAN_MOTION = 1.00273272
ECCENTRICITY = 0.0005013
INCLINATION = 3.0539
RA_OF_ASC_NODE = 81.7939
ARG_OF_PERICENTER = 249.2363
MEAN_ANOMALY = 150.1602
GM = 398600.8
EPHEMERIS_TYPE = 0
CLASSIFICATION_TYPE = U
NORAD_CAT_ID = 23581
ELEMENT_SET_NO = 0925
REV_AT_EPOCH = 4316
BSTAR = 0.0001
MEAN_MOTION_DOT = -0.00000113
MEAN_MOTION_DDOT = 0.0
```

**Annex Fig. E-2: OMM file example without covariance matrix**

```

CCSDS_OMM_VERS = 3.0
CREATION_DATE = 2007-065T16:00:00
ORIGINATOR = NOAA/USA

OBJECT_NAME = GOES 9
OBJECT_ID = 1995-025A
CENTER_NAME = EARTH
REF_FRAME = TEME
TIME_SYSTEM = UTC
MEAN_ELEMENT_THEORY = SGP/SGP4

EPOCH = 2007-064T10:34:41.4264
MEAN_MOTION = 1.00273272
ECCENTRICITY = 0.0005013
INCLINATION = 3.0539
RA_OF_ASC_NODE = 81.7939
ARG_OF_PERICENTER = 249.2363
MEAN_ANOMALY = 150.1602
GM = 398600.8

EPHEMERIS_TYPE = 0
CLASSIFICATION_TYPE = U
NORAD_CAT_ID = 23581
ELEMENT_SET_NO = 0925
REV_AT_EPOCH = 4316
BSTAR = 0.0001
MEAN_MOTION_DOT = -0.00000113
MEAN_MOTION_DDOT = 0.0

COV_REF_FRAME = TEME
CX_X = 3.331349476038534e-04
CY_X = 4.618927349220216e-04
CY_Y = 6.782421679971363e-04
CZ_X = -3.070007847730449e-04
CZ_Y = -4.221234189514228e-04
CZ_Z = 3.231931992380369e-04
CX_DOT_X = -3.349365033922630e-07
CX_DOT_Y = -4.686084221046758e-07
CX_DOT_Z = 2.484949578400095e-07
CX_DOT_X_DOT = 4.296022805587290e-10
CY_DOT_X = -2.211832501084875e-07
CY_DOT_Y = -2.864186892102733e-07
CY_DOT_Z = 1.798098699846038e-07
CY_DOT_X_DOT = 2.608899201686016e-10
CY_DOT_Y_DOT = 1.767514756338532e-10
CZ_DOT_X = -3.041346050686871e-07
CZ_DOT_Y = -4.989496988610662e-07
CZ_DOT_Z = 3.540310904497689e-07
CZ_DOT_X_DOT = 1.869263192954590e-10
CZ_DOT_Y_DOT = 1.008862586240695e-10
CZ_DOT_Z_DOT = 6.224444338635500e-10
    
```

**Annex-~~Fig.~~ E-3: OMM file example with covariance matrix**

```

CCSDS_OMM_VERS = 3.0
CREATION_DATE  = 2007-065T16:00:00
ORIGINATOR     = NOAA/USA

OBJECT_NAME    = GOES 9
OBJECT_ID      = 1995-025A
CENTER_NAME    = EARTH
REF_FRAME      = TEME
TIME_SYSTEM    = UTC
MEAN_ELEMENT_THEORY = SGP/SGP4

EPOCH          = 2007-064T10:34:41.4264
MEAN_MOTION    = 1.00273272      [rev/day]
ECCENTRICITY   = 0.0005013
INCLINATION    = 3.0539          [deg]
RA_OF_ASC_NODE = 81.7939        [deg]
ARG_OF_PERICENTER = 249.2363    [deg]
MEAN_ANOMALY   = 150.1602      [deg]
GM             = 398600.8        [km**3/s**2]
EPHEMERIS_TYPE = 0
CLASSIFICATION_TYPE = U
NORAD_CAT_ID   = 23581
ELEMENT_SET_NO = 0925
REV_AT_EPOCH   = 4316
BSTAR          = 0.0001          [1/ER]
MEAN_MOTION_DOT = -0.00000113   [rev/day**2]
MEAN_MOTION_DDOT = 0.0           [rev/day**3]

USER_DEFINED_EARTH_MODEL = WGS-84

```

**Annex-~~Fig.~~ E-4: OMM with units and a user defined parameter**

## OMM example in XML:

Fig. E-5 contains an example of an OMM in Extensible Markup Language (XML) format.

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

```

<?xml version="1.0" encoding="UTF-8"?>
<omm xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:noNamespaceSchemaLocation="http://sanaregistry.org/r/ndmxml/ndmxml-1.0-master.xsd"
  id="CCSDS_OMM_VERS" version="3.0">
  <header>
    <COMMENT> THIS EXAMPLE CONFORMS TO FIGURE 4-3 IN 502.0-B-2 IS AN XML VERSION OF THE OMM
  </COMMENT>
    <CREATION_DATE>2007-065T16:00:00</CREATION_DATE>
    <ORIGINATOR>NOAA/USA</ORIGINATOR>
  </header>

  <body>
    <segment>
      <metadata>
        <OBJECT_NAME>GOES-9</OBJECT_NAME>
        <OBJECT_ID>1995-025A</OBJECT_ID>
        <CENTER_NAME>EARTH</CENTER_NAME>
        <REF_FRAME>TEME</REF_FRAME>
        <TIME_SYSTEM>UTC</TIME_SYSTEM>
        <MEAN_ELEMENT_THEORY>TLE</MEAN_ELEMENT_THEORY>
      </metadata>

      <data>
        <meanElements>
          <EPOCH>2007-064T10:34:41.4264</EPOCH>
          <MEAN_MOTION>1.00273272</MEAN_MOTION>
          <ECCENTRICITY>0.0005013</ECCENTRICITY>
          <INCLINATION>3.0539</INCLINATION>
          <RA OF ASC NODE>81.7939</RA OF ASC NODE>
          <ARG OF PERICENTER>249.2363</ARG OF PERICENTER>
          <MEAN_ANOMALY>150.1602</MEAN_ANOMALY>
          <GM>398600.8</GM>
        </meanElements>
        <tleParameters>
          <NORAD_CAT_ID>23581</NORAD_CAT_ID>
          <ELEMENT_SET_NO>0925</ELEMENT_SET_NO>
          <REV_AT_EPOCH>4316</REV_AT_EPOCH>
          <BSTAR>0.0001</BSTAR>
          <MEAN_MOTION_DOT>-0.00000113</MEAN_MOTION_DOT>
          <MEAN_MOTION_DDOT>0.0</MEAN_MOTION_DDOT>
        </tleParameters>
        <covarianceMatrix>
          <COV_REF_FRAME>TEME</COV_REF_FRAME>
          <CX_X>0.3163.331349476038534e-04</CX_X>
          <CY_X>0.7224.618927349220216e-04</CY_X>
          <CY_Y>0.5186.782421679971363e-04</CY_Y>
          <CZ_X>0.202>-3.070007847730449e-04</CZ_X>
          <CZ_Y>0.715>-4.221234189514228e-04</CZ_Y>
          <CZ_Z>0.0023.231931992380369e-04</CZ_Z>
          <CX_DOT_X>0.912>-3.349365033922630e-07</CX_DOT_X>
          <CX_DOT_Y>0.306>-4.686084221046758e-07</CX_DOT_Y>
          <CX_DOT_Z>0.2762.484949578400095e-07</CX_DOT_Z>
          <CX_DOT_X_DOT>0.7974.296022805587290e-10</CX_DOT_X_DOT>
          <CY_DOT_X>0.562>-2.211832501084875e-07</CY_DOT_X>
          <CY_DOT_Y>0.899>-2.864186892102733e-07</CY_DOT_Y>
          <CY_DOT_Z>1.798098699846038e-070.022</CY_DOT_Z>
          <CY_DOT_X_DOT>0.0792.608899201686016e-10</CY_DOT_X_DOT>
          <CY_DOT_Y_DOT>0.4151.767514756338532e-10</CY_DOT_Y_DOT>
          <CZ_DOT_X>0.245>-3.041346050686871e-07</CZ_DOT_X>
          <CZ_DOT_Y>0.965>-4.989496988610662e-07</CZ_DOT_Y>
          <CZ_DOT_Z>0.9503.540310904497689e-07</CZ_DOT_Z>
          <CZ_DOT_X_DOT>0.4351.869263192954590e-10</CZ_DOT_X_DOT>
          <CZ_DOT_Y_DOT>0.6211.008862586240695e-10</CZ_DOT_Y_DOT>
          <CZ_DOT_Z_DOT>0.9916.224444338635500e-10</CZ_DOT_Z_DOT>
        </covarianceMatrix>
      </data>
    </segment>
  </body>
</omm>

```

~~Annex~~ **Fig. E-5: OMM file example in XML format**

ANNEX F

**OEM EXAMPLES**

**(INFORMATIVE)**

The following are examples of Orbit Ephemeris Messages (OEMs).

**OEM examples in KVN:**

The following figures are examples of OEMs in Keyword Value Notation (KVN) format. ~~Annex Fig. F-2 and Annex Fig. F-3 contain features unique to the ODM version 2, and thus 'CCSDS\_OEM\_VERS=2.0' must be specified.~~ Some ephemeris data lines have been omitted to save space.

```

CCSDS_OEM_VERS = 3.0
CREATION_DATE = 1996-11-04T17:22:31
ORIGINATOR = NASA/JPL

META_START
OBJECT_NAME      = MARS GLOBAL SURVEYOR
OBJECT_ID        = 1996-062A
CENTER_NAME      = MARS BARYCENTER
REF_FRAME        = J2000
TIME_SYSTEM      = UTC
START_TIME       = 1996-12-18T12:00:00.331
USEABLE_START_TIME = 1996-12-18T12:10:00.331
USEABLE_STOP_TIME  = 1996-12-28T21:23:00.331
STOP_TIME        = 1996-12-28T21:28:00.331
INTERPOLATION    = HERMITE
INTERPOLATION_DEGREE = 7
META_STOP

COMMENT This file was produced by M.R. Somebody, MSOO NAV/JPL, 1996NOV 04. It is
COMMENT to be used for DSN scheduling purposes only.

1996-12-18T12:00:00.331  2789.619 -280.045 -1746.755  4.73372 -2.49586 -1.04195
1996-12-18T12:01:00.331  2783.419 -308.143 -1877.071  5.18604 -2.42124 -1.99608
1996-12-18T12:02:00.331  2776.033 -336.859 -2008.682  5.63678 -2.33951 -1.94687

    < intervening data records omitted here >

1996-12-28T21:28:00.331 -3881.024  563.959 -682.773  -3.28827 -3.66735  1.63861

META_START
OBJECT_NAME      = MARS GLOBAL SURVEYOR
OBJECT_ID        = 1996-062A
CENTER_NAME      = MARS BARYCENTER
REF_FRAME        = J2000
TIME_SYSTEM      = UTC
START_TIME       = 1996-12-28T21:29:07.267
USEABLE_START_TIME = 1996-12-28T22:08:02.5
USEABLE_STOP_TIME  = 1996-12-30T01:18:02.5
STOP_TIME        = 1996-12-30T01:28:02.267
INTERPOLATION    = HERMITE
INTERPOLATION_DEGREE = 7
META_STOP

COMMENT This block begins after trajectory correction maneuver TCM-3.

1996-12-28T21:29:07.267 -2432.166 -063.042 1742.754  7.33702 -3.495867 -1.041945
1996-12-28T21:59:02.267 -2445.234 -878.141 1873.073  1.86043 -3.421256 -0.996366
1996-12-28T22:00:02.267 -2458.079 -683.858 2007.684  6.36786 -3.339563 -0.946654

    < intervening data records omitted here >

1996-12-30T01:28:02.267 2164.375 1115.811 -688.131  -3.53328 -2.88452  0.88535

```

**Annex-Fig. F-1: OEM Example With No Acceleration, No Covariance**

```

CCSDS_OEM_VERS = 3.0

COMMENT  OEM WITH OPTIONAL ACCELERATIONS

CREATION_DATE = 1996-11-04T17:22:31
ORIGINATOR = NASA/JPL

META_START
OBJECT_NAME      = MARS GLOBAL SURVEYOR
OBJECT_ID        = 2000-028A
CENTER_NAME      = MARS BARYCENTER
REF_FRAME        = J2000
TIME_SYSTEM      = UTC
START_TIME       = 1996-12-18T12:00:00.331
USEABLE_START_TIME = 1996-12-18T12:10:00.331
USEABLE_STOP_TIME  = 1996-12-28T21:23:00.331
STOP_TIME        = 1996-12-28T21:28:00.331
INTERPOLATION    = HERMITE
INTERPOLATION_DEGREE = 7
META_STOP

COMMENT  This file was produced by M.R. Somebody, MSOO NAV/JPL, 2000 NOV 04. It is
COMMENT  to be used for DSN scheduling purposes only.

1996-12-18T12:00:00.331  2789.6 -280.0 -1746.8  4.73 -2.50 -1.04  0.008 0.001 -0.159
1996-12-18T12:01:00.331  2783.4 -308.1 -1877.1  5.19 -2.42 -2.00  0.008 0.001  0.001
1996-12-18T12:02:00.331  2776.0 -336.9 -2008.7  5.64 -2.34 -1.95  0.008 0.001  0.159

    < intervening data records omitted here >

1996-12-28T21:28:00.331 -3881.0  564.0 -682.8 -3.29 -3.67  1.64  -0.003 0.000  0.000
    
```

**Annex Fig. F-2: OEM Example with Optional Accelerations**

```

CCSDS_OEM_VERS = 3.0
CREATION_DATE = 1996-11-04T17:22:31
ORIGINATOR = NASA/JPL

META_START
OBJECT_NAME      = MARS GLOBAL SURVEYOR
OBJECT_ID        = 1996-062A
CENTER_NAME      = MARS BARYCENTER
REF_FRAME        = J2000
TIME_SYSTEM      = UTC
START_TIME       = 1996-12-28T21:29:07.267
USEABLE_START_TIME = 1996-12-28T22:08:02.5
USEABLE_STOP_TIME  = 1996-12-30T01:18:02.5
STOP_TIME        = 1996-12-30T01:28:02.267
INTERPOLATION    = HERMITE
INTERPOLATION_DEGREE = 7
META_STOP

COMMENT This block begins after trajectory correction maneuver TCM-3.

1996-12-28T21:29:07.267 -2432.166 -063.042 1742.754 7.33702 -3.495867 -1.041945
1996-12-28T21:59:02.267 -2445.234 -878.141 1873.073 1.86043 -3.421256 -0.996366
1996-12-28T22:00:02.267 -2458.079 -683.858 2007.684 6.36786 -3.339563 -0.946654

  < intervening data records omitted here >

1996-12-30T01:28:02.267 2164.375 1115.811 -688.131 -3.53328 -2.88452 0.88535

COV_START
EPOCH = 1996-12-28T21:29:07.267
COV_REF_FRAME = J2000
  3.3313494e-04
  4.6189273e-04 6.7824216e-04
-3.0700078e-04 -4.2212341e-04 3.2319319e-04
-3.3493650e-07 -4.6860842e-07 2.4849495e-07 4.2960228e-10
-2.2118325e-07 -2.8641868e-07 1.7980986e-07 2.6088992e-10 1.7675147e-10
-3.0413460e-07 -4.9894969e-07 3.5403109e-07 1.8692631e-10 1.0088625e-10 6.2244443e-10

EPOCH = 1996-12-29T21:00:00
COV_REF_FRAME = J2000
  3.4424505e-04
  4.5078162e-04 6.8935327e-04
-3.0600067e-04 -4.1101230e-04 3.3420420e-04
-3.2382549e-07 -4.5750731e-07 2.3738384e-07 4.3071339e-10
-2.1007214e-07 -2.7530757e-07 1.6870875e-07 2.5077881e-10 1.8786258e-10
-3.0302350e-07 -4.8783858e-07 3.4302008e-07 1.7581520e-10 1.0077514e-10 6.2244443e-10
COVARIANCE_STOP
    
```

**Annex Fig. F-3: OEM Example with Optional Covariance Matrices**

## OEM example in XML:

Fig. F-4 contains an example of an Orbit Ephemeris Message in Extensible Markup Language (XML) format.

```

<?xml version="1.0" encoding="UTF-8"?>
<oem xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:noNamespaceSchemaLocation="http://sanaregistry.org/r/ndmxml/ndmxml-1.0-master.xsd"
  id="CCSDS_OEM_VERS" version="3.0">

  <header>
    <COMMENT>OEM WITH OPTIONAL ACCELERATIONS</COMMENT>
    <CREATION_DATE>1996-11-04T17:22:31</CREATION_DATE>
    <ORIGINATOR>NASA/JPL</ORIGINATOR>
  </header>
  <body>
    
```

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

```

<segment>
  <metadata>
    <OBJECT_NAME>MARS GLOBAL SURVEYOR</OBJECT_NAME>
    <OBJECT_ID>2000-028A</OBJECT_ID>
    <CENTER_NAME>MARS BARYCENTER</CENTER_NAME>
    <REF_FRAME>J2000</REF_FRAME>
    <TIME_SYSTEM>UTC</TIME_SYSTEM>
    <START_TIME>1996-12-18T12:00:00.331</START_TIME>
    <USEABLE_START_TIME>1996-12-18T12:10:00.331</USEABLE_START_TIME>
    <USEABLE_STOP_TIME>1996-12-28T21:23:00.331</USEABLE_STOP_TIME>
    <STOP_TIME>1996-12-28T21:28:00.331</STOP_TIME>
    <INTERPOLATION>HERMITE</INTERPOLATION>
    <INTERPOLATION_DEGREE>7</INTERPOLATION_DEGREE>
  </metadata>
  <data>
    <COMMENT>Produced by M.R. Somboddy, MSOO NAV/JPL, 1996 OCT 11. It is</COMMENT>
    <COMMENT>to be used for DSN scheduling purposes only.</COMMENT>
    <stateVector>
      <EPOCH>1996-12-18T12:00:00.331</EPOCH>
      <X>2789.6</X>
      <Y>-280.0</Y>
      <Z>-1746.8</Z>
      <X_DOT>4.73</X_DOT>
      <Y_DOT>-2.50</Y_DOT>
      <Z_DOT>-1.04</Z_DOT>
      <X_DDOT>0.008</X_DDOT>
      <Y_DDOT>0.001</Y_DDOT>
      <Z_DDOT>-0.159</Z_DDOT>
    </stateVector>
    <stateVector>
      <EPOCH>1996-12-18T12:01:00.331</EPOCH>
      <X>2783.4</X>
      <Y>-308.1</Y>
      <Z>-1877.1</Z>
      <X_DOT>5.19</X_DOT>
      <Y_DOT>-2.42</Y_DOT>
      <Z_DOT>-2.00</Z_DOT>
      <X_DDOT>0.008</X_DDOT>
      <Y_DDOT>0.001</Y_DDOT>
      <Z_DDOT>0.001</Z_DDOT>
    </stateVector>
    <stateVector>
      <EPOCH>1996-12-18T12:02:00.331</EPOCH>
      <X>2776.0</X>
      <Y>-336.9</Y>
      <Z>-2008.7</Z>
      <X_DOT>5.64</X_DOT>
      <Y_DOT>-2.34</Y_DOT>
      <Z_DOT>-1.95</Z_DOT>
      <X_DDOT>0.008</X_DDOT>
      <Y_DDOT>0.001</Y_DDOT>
      <Z_DDOT>0.159</Z_DDOT>
    </stateVector>
    <stateVector>
      <EPOCH>1996-12-28T21:28:00.331</EPOCH>
      <X>-3881.0</X>
      <Y>564.0</Y>
      <Z>-682.8</Z>
      <X_DOT>-3.29</X_DOT>
      <Y_DOT>-3.67</Y_DOT>
      <Z_DOT>1.64</Z_DOT>
      <X_DDOT>-0.003</X_DDOT>
      <Y_DDOT>0.000</Y_DDOT>
      <Z_DDOT>0.000</Z_DDOT>
    </stateVector>
    <covarianceMatrix>
      <EPOCH></EPOCH>
      <COV_REF_FRAME>ITRF1997</COV_REF_FRAME>
      <CX_X>0.316</CX_X>
      <CY_X>0.722</CY_X>
      <CY_Y>0.518</CY_Y>
  </data>

```

```

<CZ_X>0.202</CZ_X>
<CZ_Y>0.715</CZ_Y>
<CZ_Z>0.002</CZ_Z>
<CX_DOT_X>0.912</CX_DOT_X>
<CX_DOT_Y>0.306</CX_DOT_Y>
<CX_DOT_Z>0.276</CX_DOT_Z>
<CX_DOT_X_DOT>0.797</CX_DOT_X_DOT>
<CY_DOT_X>0.562</CY_DOT_X>
<CY_DOT_Y>0.899</CY_DOT_Y>
<CY_DOT_Z>0.022</CY_DOT_Z>
<CY_DOT_X_DOT>0.079</CY_DOT_X_DOT>
<CY_DOT_Y_DOT>0.415</CY_DOT_Y_DOT>
<CZ_DOT_X>0.245</CZ_DOT_X>
<CZ_DOT_Y>0.965</CZ_DOT_Y>
<CZ_DOT_Z>0.950</CZ_DOT_Z>
<CZ_DOT_X_DOT>0.435</CZ_DOT_X_DOT>
<CZ_DOT_Y_DOT>0.621</CZ_DOT_Y_DOT>
<CZ_DOT_Z_DOT>0.991</CZ_DOT_Z_DOT>
</covarianceMatrix>
</data>
</segment>
</body>
</oem>

```

**Annex Fig. F-4: OEM file example in XML format**

## ANNEX G

**OCM EXAMPLES AND  
ASSOCIATED  
SUPPLEMENTARY  
INFORMATION  
  
(INFORMATIVE)**

The following are examples of Orbit Comprehensive Messages (OCMs).

### OCM examples in KVN:

The following figures are examples of OCMs in Keyword Value Notation (KVN) format. The first has only a time history of orbital states and constitutes a minimal content OCM. The second includes space object characteristics and perturbations specifications; the third includes a time series of maneuvers, a time history of Cartesian position and velocity orbit states, followed by a time history of Keplerian elements; the fourth includes a time series of covariance matrices, and the fifth contains a State Transition Matrix ~~and an Ephemeris Compression~~ section.

```

CCSDS_OCM_VERS = 3.0
CREATION_DATE = 1998-11-06T09:23:57
ORIGINATOR = JAXA
META_START
META_START
DEF_TIME_SYSTEM = UTC
EPOCH_TZERO = 1998-12-18T14:28:15.1172
DEF_TIME_SYSTEM = UTC
META_STOP
ORB_START
DT=0.0 2789.6 -280.0 -1746.8 4.73 -2.50 -1.04
T=1998-12-18T14:28:25.117210.0 2783.4 -308.1 -1877.1 5.19 -2.42 -2.00
DT=20.0 2776.0 -336.9 -2008.7 5.64 -2.34 -1.95
< intervening data records omitted here >
DT=500.0 2164.375 1115.811 -688.131 -3.53328 -2.88452 0.88535
ORB_STOP

```

**Annex Fig. G-1: Simple/Succinct OCM File example with only Cartesian ephemeris.**  
**Reference** In this example, the reference frame (ORB\_REF\_FRAME) defaults to ITRF2000, CENTER\_NAME defaults to EARTH and orbit type (ORB\_TYPE) to CARTPV. In this example, at the expense of readability, KVN values are unaligned to minimize message storage and transmission size.

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

CCSDS\_OCM\_VERS = 3.0  
 COMMENT This OCM reflects the latest conditions post-maneuver A67Z  
 COMMENT This example shows the specification of multiple comment lines  
 CREATION\_DATE = 1998-11-06T09:23:57

META\_START

ORIGINATOR = JAXA  
 ORIGINATOR\_POC = R. Rabbit  
 ORIGINATOR\_POSITION = Flight Dynamics Mission Design Lead  
 ORIGINATOR\_PHONE = (719)555-1234

META\_START

TECH\_POC = Mr. Rodgers  
 TECH\_PHONE = (719)555-1234  
 TECH\_ADDRESS = email@email.XXX

OBJECT\_NAME = GODZILLAOSPREY 5  
 INTERNATIONAL\_DESIGNATOR = 1998-999A

~~DEF\_EPOCH\_TZERO~~ = 1998-12-18T00:00:00.0000  
~~DEF\_TIME\_SYSTEM~~ = UT1

TAIMUTC AT TZERO = 36 [s]  
~~UT2MUTC~~UT1MUTC AT TZERO = .357 [s]  
~~UT1MUTC\_RATE\_TZERO~~ = 0.0001 [ms/day]  
 META\_STOP

ORB\_START

COMMENT GEOCENTRIC, CARTESIAN, EARTH FIXED  
 COMMENT THIS IS MY SECOND COMMENT LINE  
~~ORB\_EPOCH\_TZERO~~ = ~~1998-12-18T14:28:35.1172~~  
 ORB\_REF\_FRAME = EFG  
 ORB\_TYPE = CARTPVA  
~~DT=0.000000~~1998-12-18T14:28:25.1172 2789.6 -280.0 -1746.8 4.73 -2.50 -1.04 0.008 0.001  
 -0.159  
 ORB\_STOP

PHYS\_START

COMMENT S/CSpacecraft Physical Characteristics:  
 MASS = 100.0 [kg]  
~~ESOE~~Q1 = 0.03123  
~~ESOE~~Q2 = 0.78543  
~~ESOE~~Q3 = 0.39158  
~~ESOE~~QC = 0.47832  
~~ESOE~~MAX = 2.0 [m]  
~~ESOE~~MED = 1.0 [m]  
~~ESOE~~MIN = 0.5 [m]  
 AREA\_ALONG ~~ESOE~~MAX = 0.15 [m\*\*2]  
 AREA\_ALONG ~~ESOE~~MED = 0.3 [m\*\*2]  
 AREA\_ALONG ~~ESOE~~MIN = 0.5 [m\*\*2]  
 PHYS\_STOP

PERT\_START

COMMENT Perturbations Specification:  
 ATMOSPHERIC\_MODEL = NRLMSIS00  
 GRAVITY\_MODEL = EGM-96: 36D 360  
 GM = 398600.4415 [km\*\*3/s\*\*2]  
 N\_BODY\_PERTURBATIONS = MOON, SUN  
 FIXED\_GEOMAG\_KP = 12.0  
 FIXED\_F10P7 = 105.0  
 FIXED\_F10P7\_MEAN = 120.0  
 PERT\_STOP

USER\_START

EARTH\_MODEL = WGS-84  
 USER\_STOP

**Annex Fig. G-2: OCM example with space object characteristics and perturbations**

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

```

CCSDS_OCM_VERS = 3.0
CREATION_DATE = 1998-11-06T09:23:57

META_START
DEF_ORIGINATOR = JAXA
META_START
EPOCH_TZERO = 1998-12-18T14:28:15.1172
META_STOP

ORB_START
COMMENT ORBIT EPHEMERIS INCORPORATING DEPLOYMENTS AND MANEUVERS (BELOW)
ORB_REF_FRAME = TOD
ORB_FRAME_EPOCH = 1998-12-18T14:28:15.1172
ORB_TYPE = CARTPVA
DT=0.000000 2789.6 -280.0 -1746.8 4.73 -2.50 -1.04 0.008 0.001 -0.159
DT=10.000000 2783.4 -308.1 -1877.1 5.19 -2.42 -2.00 0.008 0.001 0.001
DT=20.000000 2776.0 -336.9 -2008.7 5.64 -2.34 -1.95 0.008 0.001 0.159
< intervening data records omitted here >
T=1998-12-18T14:36:35.1172 2164.3753 1115.8118 -688.1311 -3.53328533 -2.88452884
0.88535885 0.008 0.001 0.159
ORB_STOP

PHYS_START
COMMENT S/CSpacecraft Physical Characteristics:
DRAG_AREA = 10.00 [m**2]
DRAG_COEFF = 2.300
MASS = 100.0 [kg]
SOLAR_RAD_AREA = 4.00
SOLAR_RAD_COEFF = 1.300
PHYS_STOP

MAN_START
COMMENT = Ten 1kg objects deployed from 200kg host over 100 s timespan
COMMENT = 20 deg off of back-track direction
MAN_BASIS = PREDICTED
MAN_IS_ADDITIVE = YES
MAN_PURPOSE = DEPLOY
MAN_EOI= DV_X, DV_Y, DV_Z, DV_SIGMA, DV_DMSS, DEPLOY_ID, DEPLOY_DV_X, DEPLOY_DV_Y, DEPLOY_DV_Z, DEPLOY_MASS
MAN_REF_FRAME = RTN
DT=500.0 -0.00144 0.00470 -0.00092 0.0 -1.0 CUBESAT_10 0.28773 -0.93969 0.18491 -
1.0
DT=510.0 -0.00071 0.00470 -0.00156 0.0 -1.0 CUBESAT_1011 0.14208 -0.93969 0.31111 -
1.0
DT=520.0 0.00024 0.00470 -0.00169 0.0 -1.0 CUBESAT_1012 -0.04867 -0.93969 0.33854 -
1.0
DT=530.0 0.00112 0.00470 -0.00129 0.0 -1.0 CUBESAT_1013 -0.22398 -0.93969 0.25848 -
1.0
DT=540.0 0.00164 0.00470 -0.00048 0.0 -1.0 CUBESAT_1014 -0.32817 -0.93969 0.09636 -
1.0
DT=550.0 0.00164 0.00470 0.00048 0.0 -1.0 CUBESAT_1015 -0.32817 -0.93969 -0.09636 -
1.0
DT=560.0 0.00112 0.00470 0.00129 0.0 -1.0 CUBESAT_1016 -0.22398 -0.93969 -0.25848 -
1.0
DT=570.0 0.00024 0.00470 0.00169 0.0 -1.0 CUBESAT_1017 -0.04867 -0.93969 -0.33854 -
1.0
DT=580.0 -0.00071 0.00470 0.00156 0.0 -1.0 CUBESAT_1018 0.14208 -0.93969 -0.31111 -
1.0
DT=590.0 -0.00144 0.00470 0.00092 0.0 -1.0 CUBESAT_1019 0.28773 -0.93969 -0.18491 -
1.0
MAN_STOP

MAN_START
COMMENT = 100 s of 0.5N +in-track thrust w/effic η=0.95, Isp=300s, 5% 1-sigma
error
MAN_BASIS = PREDICTED
MAN_IS_ADDITIVE = YES
MAN_PURPOSE = ORBIT_ADJUST
MAN_EOI = MAN_DURA, THR_X, THR_Y, THR_Z, THR_SIGMA, THR_INTERP, THR_ISP, THR_EFFIC
MAN_REF_FRAME = RTN
DT=500.01998-12-18T14:36:35.1172 100.0 0.0 0.5 0.0 5.0 NO 300.0 0.95
MAN_STOP
    
```

```

PERT_START
COMMENT Perturbations specification
GM          = 398600.4415      [km**3/s**2]
PERT_STOP

OD_START
COMMENT -----Orbit Determination information
OD_ID       = OD #10059
OD_PREV_ID  = OD #10058
OD_EPOCH    = 2001-11-06T11:17:33
OBS_USED    = 273
TRACKS_USED  = 91
OD_STOP
    
```

**Annex Fig. G-3: OCM example with deployed objects and low-level thrusting maneuver during deployment to make “string-of-pearls” deployment**

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

```

CCSDS_OCM_VERS = 3.0
CREATION_DATE = 1998-11-06T09:23:57

META_START
ORIGINATOR = JAXA

META_START
OBJECT_NAME = GODZILLAOSPREY 5
INTERNATIONAL_DESIGNATOR = 1998-999A

DEF_CATALOG_NAME = CSPOC
OBJECT_DESIGNATOR = 98765

EPOCH_TZERO = 1998-12-18T14:28:15.1172
DEF_TIME_SYSTEM = UTC
META_STOP

ORB_START
ORB_BASIS = PREDICTED
ORB_REF_FRAME = TOD
ORB_FRAME_EPOCH = 1998-12-18T14:28:15.1172
ORB_TYPE = CARTPVA
DT=0.000000 2789.6 -280.0 -1746.8 4.73 -2.50 -1.04 0.008 0.001 -0.159
DT=10.000000 2783.4 -308.1 -1877.1 5.19 -2.42 -2.00 0.008 0.001 0.001
DT=20.000000 2776.0 -336.9 -2008.7 5.64 -2.34 -1.95 0.008 0.001 0.159
< intervening data records omitted here >
T=1998-12-18T14:36:35.1172 2164.375 1115.811 -688.131 -3.53328 -2.88452 0.88535
ORB_STOP

ORB_START
ORB_BASIS = DETERMINED_OD
ORB_REF_FRAME = J2000
ORB_TYPE = KPLR
DT=0.000000 6600.0 .03 28.5 50.0 30.0 10.0
DT=10.000000 6600.0 .03 28.5 50.0 30.0 10.1
DT=20.000000 6600.0 .03 28.5 50.0 30.0 10.2
< intervening data records omitted here >
DT=500.000000 6600.0 .03 28.5 50.0 30.0 35.0
ORB_STOP

PHYS_START
COMMENT S/Spacecraft Physical Characteristics:
DRAG_AREA = 10.00 [m**2]
DRAG_COEFF = 2.300
MASS = 100.0 [kg]
SOLAR_RAD_AREA = 4.00
SOLAR_RAD_COEFF = 1.300
PHYS_STOP

MAN_START
COMMENT = 200 s of 10N thrust (in-track transitioning to radial)
COMMENT = w/effic η=0.95, Isp=300s, 5% 1-sigma error
MAN_BASIS = PREDICTED
MAN_IS_ADDITIVE = YES
MAN_PURPOSE = ORBIT_ADJUST
MAN_EOI = MAN_DURA, THR_X, THR_Y, THR_Z, THR_SIGMA, THR_INTERP, THR_ISP, THR_EFFIC
MAN_REF_FRAME = RTN
DT=500.0 100.0 0.0 10.0 0.0 5.0 ON 300.0 0.95
DT=600.0 100.0 10.0 0.0 0.0 5.0 OFF 300.0 0.95
MAN_STOP

PERT_START
COMMENT Perturbations specification
GM = 398600.4415 [km**3/s**2]
PERT_STOP

OD_START
COMMENT Orbit Determination information
OD_ID = OD #10059
OD_PREV_ID = OD #10058
OD_EPOCH = 2001-11-06T11:17:33

```

OBS_USED	273
TRACKS_USED	91
OD_STOP	

**Annex Fig. G-4: OCM example with multiple orbit time histories, a maneuver, OD, Cartesian & Keplerian ephemeris**

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

```

CCSDS_OCM_VERS      = 3.0

CREATION_DATE       = 1998-11-06T09:23:57
ORIGINATOR          = JAXA

META_START
OBJECT_NAME         = GODZILLAOSPREY 5
INTERNATIONAL_DESIGNATOR = 1998-999A
DEFEPOCH_TZERO = 1998-12-18T14:28:15.1172
DEFTIME_SYSTEM = UTC
META_STOP

ORB_START
COMMENT             GEOCENTRIC, CARTESIAN, EARTH FIXED
CENTER_NAME        = EARTH
ORB_REF_FRAME       = TOD_EARTH
ORB_FRAME_EPOCH    = 1998-12-18T14:28:15.1172
ORB_TYPE            = CARTPVA

DT= 0.000000 2789.6 -280.0 -1746.8 4.73 -2.50 -1.04 0.008 0.001 -0.159
DT=-10.000000 2783.4 -308.1 -1877.1 5.19 -2.42 -2.00 0.008 0.001 0.001
DT=-20.000000 2776.0 -336.9 -2008.7 5.64 -2.34 -1.95 0.008 0.001 0.159
  < intervening data records omitted here >
DT=500.000000 2164.375 1115.811 -688.131 -3.53328 -2.88452 0.88535
ORB_STOP

PHYS_START
COMMENT S/CSpacecraft Physical Characteristics:
DRAG_AREA           = 10.000 [m**2]
DRAG_COEFF          = 2.300
MASS                 = 1913.000 [kg]
SOLAR_RAD_AREA      = 10.000 [m**2]
SOLAR_RAD_COEFF     = 1.300
PHYS_STOP

COV_START
COV_EPOCH_TZERO = 1998-12-18T14:28:15.1172
COV_REF_FRAME       = J2000
COV_TYPE            = ADBARV

DT =-10.00
  3.331349e-04
  4.618927e-04 6.782421e-04
-3.070007e-04 -4.221234e-04 3.231931e-04
-3.349365e-07 -4.686084e-07 2.484949e-07 4.296022e-10
-2.211832e-07 -2.864186e-07 1.798098e-07 2.608899e-10 1.767514e-10
-3.041346e-07 -4.989496e-07 3.540310e-07 1.869263e-10 1.008862e-10 6.224444e-10
  < intervening data records omitted here >
T =-20.0
1998-12-18T14:31:35.1172
  3.442450e-04
  4.507816e-04 6.893532e-04
-3.060006e-04 -4.110123e-04 3.342042e-04
-3.238254e-07 -4.575073e-07 2.373838e-07 4.307133e-10
-2.100721e-07 -2.753075e-07 1.687087e-07 2.507788e-10 1.878625e-10
-3.030235e-07 -4.878385e-07 3.430200e-07 1.758152e-10 1.007751e-10 6.224444e-10
COV_STOP

COV_START
COV_EPOCH_TZERO = 1998-12-18T14:31:35.1172
COV_TYPE            = EFG
1998-12-18T14:31:35.1172
DT =-30.00
  3.331349e-04
  4.618927e-04 6.782421e-04
-3.070007e-04 -4.221234e-04 3.231931e-04
COV_STOP

PERT_START
COMMENT Perturbations specification
GM              = 398600.4415 [km**3/s**2]

```

PERT\_STOP

**Annex Fig. G-5: OCM example with Covariance Matrix**

```

CCSDS_OCM_VERS      = 3.0
CREATION_DATE       = 1998-11-06T09:23:57

META_START
ORIGINATOR          = JAXA

META_START
OBJECT_NAME         = GODZILLAOSPREY 5
INTERNATIONAL_DESIGNATOR = 1998-999A
DEF_EPOCH_TZERO    = 1998-12-18T14:28:15.1172
META_STOP

STM_START
COMMENT HERE IS A STATE TRANSITION MATRIX DATA BLOCK:
STM_MAP_MODE        = STATE
STM_EPOCH_TZEROORB TIME = 0.0
STM_ORB_STATE       = 2789.6 -280.0 -1746.8 4.73 -2.50 -1.04
STM_REF_FRAME       = ICRF3
STM_TYPE            = CARTPV

DT = 0.00
1.0 0.0 0.0 0.0 0.0 0.0
0.0 1.0 0.0 0.0 0.0 0.0
0.0 0.0 1.0 0.0 0.0 0.0
0.0 0.0 0.0 1.0 0.0 0.0
0.0 0.0 0.0 0.0 1.0 0.0
0.0 0.0 0.0 0.0 0.0 1.0

< intervening data records omitted here >

DT = 500.00
1.23456 7.89012 3.45678 9.01234 5.67890 1.23456
7.89012 3.45678 9.01234 5.67890 1.23456 7.89012
3.45678 9.01234 5.67890 1.23456 7.89012 3.45678
9.01234 5.67890 1.23456 7.89012 3.45678 9.01234
5.67890 1.23456 7.89012 3.45678 9.01234 5.67890
1.23456 7.89012 3.45678 9.01234 5.67890 1.23456
STM_STOP
    
```

**Annex Fig. G-6: OCM example with STM (Cartesian position and velocity elements)**

### OCM example in XML:

Fig. G-7 contains an example of an Orbit Comprehensive Message in Extensible Markup Language (XML) format.

CCSDS PROPOSED STANDARD FOR ORBIT DATA MESSAGES

```

<?xml version="1.0" encoding="UTF-8"?>
<ocm xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:noNamespaceSchemaLocation="file:///Y:/Desktop/ccsds-ndmxml/ndmxml-1.0.x-schemas-
unqualified/ndmxml-1.0-master.xsd"
  id="CCSDS_OCM_VERS" version="P2.39">
  <header>
    <COMMENT>ODM V.3 Example G-2</COMMENT>
    <COMMENT>OCM example with space object characteristics and perturbations.</COMMENT>
    <COMMENT>This OCM reflects the latest conditions post-maneuver A67Z</COMMENT>
    <COMMENT>This example shows the specification of multiple comment lines</COMMENT>
    <CREATION DATE>1998-11-06T09:23:57</CREATION DATE>
    <ORIGINATOR>JAXA</ORIGINATOR>
  </header>
  <body>
    <segment>
      <metadata>
        <ORIGINATOR POC>R. Rabbit</ORIGINATOR POC>
        <ORIGINATOR POSITION>Flight Dynamics Mission Design Lead</ORIGINATOR POSITION>
        <ORIGINATOR PHONE>(719)555-1234</ORIGINATOR PHONE>
        <TECH POC>Mr. Rodgers</TECH POC>
        <TECH PHONE>(719)555-1234</TECH PHONE>
        <TECH ADDRESS>email@email.XXX</TECH ADDRESS>
        <OBJECT NAME>OSPREY 5</OBJECT NAME>
        <INTERNATIONAL DESIGNATOR>1998-999A</INTERNATIONAL DESIGNATOR>
        <TIME SYSTEM>UT1</TIME SYSTEM>
        <EPOCH TZERO>1998-12-18T00:00:00.0000</EPOCH TZERO>
        <TAIMUTC AT TZERO units="s">36</TAIMUTC AT TZERO>
        <UT1MUTC AT TZERO units="s">.357</UT1MUTC AT TZERO>
      </metadata>
      <data>
        <orbitState>
          <COMMENT>GEOCENTRIC, CARTESIAN, EARTH FIXED</COMMENT>
          <COMMENT>THIS IS MY SECOND COMMENT LINE</COMMENT>
          <ORB REF FRAME>EFG</ORB REF FRAME>
          <ORB TYPE>CARTPVA</ORB TYPE>
          <orbitLine>0.000000 2789.6 -280.0 -1746.8 4.73 -2.50 -1.04 0.008 0.001 -
0.159</orbitLine>
        </orbitState>
        <physicalDescription>
          <COMMENT>Spacecraft Physical Characteristics</COMMENT>
          <MASS units="kg">100.0</MASS>
          <OEB Q1>0.03123</OEB Q1>
          <OEB Q2>0.78543</OEB Q2>
          <OEB Q3>0.39158</OEB Q3>
          <OEB QC>0.47832</OEB QC>
          <OEB MAX units="m">2.0</OEB MAX>
          <OEB MED units="m">1.0</OEB MED>
          <OEB MIN units="m">0.5</OEB MIN>
          <AREA ALONG OEB MAX units="m**2">0.15</AREA ALONG OEB MAX>
          <AREA ALONG OEB MED units="m**2">0.3</AREA ALONG OEB MED>
          <AREA ALONG OEB MIN units="m**2">0.5</AREA ALONG OEB MIN>
        </physicalDescription>
        <perturbations>
          <COMMENT>Perturbations Specification</COMMENT>
          <ATMOSPHERIC MODEL>NRLMSIS00</ATMOSPHERIC MODEL>
          <GRAVITY MODEL>EGM-96: 36D 360</GRAVITY MODEL>
          <GM units="km**3/s**2">398600.4415</GM>
          <N BODY PERTURBATIONS>MOON, SUN</N BODY PERTURBATIONS>
          <FIXED GEOMAG KP>12.0</FIXED GEOMAG KP>
          <FIXED F10P7>105.0</FIXED F10P7>
          <FIXED F10P7 MEAN>120.0</FIXED F10P7 MEAN>
        </perturbations>
        <userDefinedParameters>
          <USER DEFINED parameter="EARTH MODEL">WGS-84</USER DEFINED>
        </userDefinedParameters>
      </data>
    </segment>
  </body>
</ocm>

```

OCM XML EXAMPLES HERE

| **Annex**

**Fig. G-7: OCM file example in XML format**

## ANNEX H

**ABBREVIATIONS AND  
ACRONYMS****(INFORMATIVE)**

ASCII	American Standard Code for Information Interchange
CCSDS	Consultative Committee for Space Data Systems
CIO	Celestial Intermediate Origin
CIP	Celestial Intermediate Pole
DSST	Draper Semi-Analytic Satellite Theory
<del>ECI</del>	<del>Earth Centered Inertial</del>
EGM	Earth Gravitational Model, Earth Geopotential Model
EOP	Earth Orientation Parameters
<del>GCRF</del>	<del>Geocentric Celestial Reference Frame</del>
GPS	Global Positioning System
IAU	International Astronomical Union
ICD	Interface Control Document
ICRF	International Celestial Reference Frame
IEC	International Electro-technical Commission
IERS	International Earth Rotation and Reference Systems Service
IIRV	Improved Inter-Range Vector
ISO	International Standards Organization
ITRF	International Terrestrial Reference Frame
<del>ITRS</del>	<del>International Terrestrial Reference System</del>
GRC	Greenwich Rotating Coordinate Frame
J2000	Earth Mean Equator and Equinox of J2000 (Julian Date 2000)
KVN	Keyword = Value Notation

NORAD	North American Aerospace Defense Command
OD	Orbit Determination
ODM	Orbit Data Message
<del>OES</del> <u>OE</u> <del>SOEB</del>	Optimally-Encompassing <u>ShapeBox</u>
OEM	Orbit Ephemeris Message
OCM	Orbit Comprehensive Message
OMM	Orbit Mean-Elements Message
OPM	Orbit Parameter Message
RTN	Radial, Transverse (along-track) and Normal
S/C	Spacecraft
SGP4	US Air Force Simplified General Perturbations No. 4
SPK	Satellite, Planetary Kernel
TAI	International Atomic Time
TCB	Barycentric <del>Coordinate Time</del>
<del>TCG</del>	<del>Geocentric</del> Coordinate Time
TDB	Barycentric Dynamical Time
TDR	True of Date Rotating
TDT	Terrestrial Dynamical Time (see also 'TT')
TEME	True Equator Mean Equinox
TLE	Two Line Element
TOD	True Equator and Equinox of Date
TT	Terrestrial Dynamical Time (see also 'TDT')
USM	Universal Semi-analytical Method
UTC	Coordinated Universal Time
W3C	World Wide Web Consortium
WGS	World Geodetic System

XML      Extensible Markup Language

## ANNEX I

**RATIONALE FOR ORBIT  
DATA MESSAGES****(INFORMATIVE)****II OVERVIEW**

This annex presents the rationale behind the design of each message. It may help the application engineer to select a suitable message.

A specification of requirements agreed to by all parties is essential to focus design and to ensure the product meets the needs of the Member Agencies and satellite operators. There are many ways of organizing requirements, but the categorization of requirements is not as important as the agreement to a sufficiently comprehensive set. In this section the requirements are organized into three categories:

- a) **Primary Requirements:** These are the most elementary and necessary requirements. They would exist no matter the context in which the CCSDS is operating, i.e., regardless of pre-existing conditions within the CCSDS, its Member Agencies, or other independent users.
- b) **Heritage Requirements:** These are additional requirements that derive from pre-existing Member Agency or other independent user requirements, conditions or needs. Ultimately these carry the same weight as the Primary Requirements. This Recommended Standard reflects heritage requirements pertaining to some of the CCSDS Areas' home institutions collected during the preparation of the document; it does not speculate on heritage requirements that could arise from other sources. Corrections and/or additions to these requirements are expected during future updates.
- c) **Desirable Characteristics:** These are not requirements, but they are felt to be important or useful features of the Recommended Standard.

## 12 PRIMARY REQUIREMENTS ACCEPTED BY THE ORBIT DATA MESSAGES

### 12.1 PRIMARY REQUIREMENTS

#	Requirement	OPM?	OMM?	OEM?	OCM?
P1	Data must be provided in digital form (computer file).	Y	Y	Y	Y
P2	The file specification must not require of the receiving exchange partner the separate application of, or modeling of, spacecraft dynamics or gravitational force models, or integration or propagation.	N	N	Y	Y
P3	The interface must facilitate the receiver of the message to generate a six-component Cartesian state vector (position and velocity) at any required epoch.	Y	Y	Y	Y
P4	State vector information must be provided in a reference frame that is clearly identified and unambiguous.	Y	Y	Y	Y
P5	Identification of the object and the center(s) of motion must be clearly identified and unambiguous.	Y	Y	Y	Y
P6	Time measurements (time stamps, or epochs) must be provided in a commonly used, clearly specified system.	Y	Y	Y	Y
P7	The time bounds of the ephemeris must be unambiguously specified.	N/A	N/A	Y	Y
P8	The Recommended Standard must provide for clear specification of units of measure.	Y	Y	Y	Y
P9	Files must be readily ported between, and useable within, 'all' computational environments in use by Member Agencies.	Y	Y	Y	Y
P10	Files must have means of being uniquely identified and clearly annotated. The file name alone is considered insufficient for this purpose.	Y	Y	Y	Y
P11	File name syntax and length must not violate computer constraints for those computing environments in use by Member Agencies.	Y	Y	Y	Y
P12	A means to convey information about the uncertainty of the state shall be provided.	Y	Y	Y	Y

### 12.2 HERITAGE REQUIREMENTS

#	Requirement	OPM?	OMM?	OEM?	OCM?
H1	Ephemeris data is reliably convertible into the SPICE SPK (NASA) format (reference [M-64]) and IIRV (NASA) format (reference [M-75]) using a standard, multi-mission, unsupervised pipeline process. A complete ephemeris, not subject to integration or propagation by the customer, must be provided.	N	N	Y	Y
H2	Ephemeris data provided for scheduling or operations (metric predicts) is to be certified by the providing Agency as correct and complete for the intended purpose. The receiving Agency cannot provide evaluation, trajectory propagation or other usability services.	N	N	Y	Y

#	Requirement	OPM?	OMM?	OEM?	OCM?
H3	The ODM shall provide a mechanism by which messages may be uniquely identified and clearly annotated. Facilitates discussion between the recipient and the message originator, should that be necessary.	<del>NY</del>	<del>NY</del>	<del>NY</del>	Y
H4	The ODM shall provide a mechanism by which maneuvers may be uniquely identified and clearly annotated. Facilitates discussion between the recipient and the message originator, should that be necessary.	N	N	N	Y
H5	The Recommended Standard is, or includes, an ASCII format.	Y	Y	Y	Y
H6	The Recommended Standard does not require software supplied by other Agencies.	Y	N	Y	Y

### 12.3 DESIRABLE CHARACTERISTICS

#	Requirement	OPM?	OMM?	OEM?	OCM?
DC1	The Recommended Standard applies to non-traditional objects, such as landers, rovers, balloons, and natural bodies (asteroids, comets).	Y	N	Y	Y
DC2	The Recommended Standard allows state vectors to be provided in other than the traditional J2000 inertial reference frame; one example is the International Astronomical Union (IAU) Mars body-fixed frame. (In such a case, provision or ready availability of supplemental information needed to transform data into a standard frame must be arranged.)	Y	Y	Y	Y
DC3	The Recommended Standard is extensible with no disruption to existing users/uses.	Y	Y	Y	Y
DC4	The Recommended Standard is consistent with, and ideally a part of, ephemeris products and processes used for other space science purposes.	Y	Y	Y	Y
DC5	The Recommended Standard is as consistent as reasonable with any related CCSDS ephemeris Recommended Standards used for earth-to-spacecraft or spacecraft-to-spacecraft applications.	Y	Y	Y	Y

### 12.4 APPLICABILITY OF CRITERIA TO MESSAGE OPTIONS

The selection of one particular message will depend on the optimization criteria in the given application. Section I2.5 compares the four recommended messages in terms of the relevant selection criteria identified by the CCSDS:

**12.5 APPLICABILITY OF THE CRITERIA TO ORBIT DATA MESSAGES**

<b>Criteria</b>	<b>Definition</b>	<b>Applicable to OPM?</b>	<b>Applicable to OMM?</b>	<b>Applicable to OEM?</b>	<b>Applicable to OCM?</b>
Modeling Fidelity	Permits modeling of any dynamic perturbation to the trajectory.	N	N	Y	Y
Human Readability	Provides easily readable message corresponding to widely used orbit representation.	Y	Y	Y	Y
Remote Body Extensibility	Permits use for assets on remote solar system bodies.	Y	N	Y	Y
Lander/Rover Compatibility	Permits exchange of non-orbit trajectories.	N	N	Y	Y

**13 INCREASING ORBIT PROPAGATION FIDELITY OF AN OPM OR OMM**

Some OPM or OMM users may desire/require a higher fidelity propagation of the state vector or Keplerian elements. A higher fidelity technique may be desired/required to minimize inconsistencies in predictions generated by diverse, often operator-unique propagation schemes. Nominally the OPM and OMM are engineered only for low- to medium-fidelity orbit propagation. However, with the inclusion of additional context information, it is possible for users to provide data that could be used to provide a relatively higher fidelity orbit propagation. For this relatively higher fidelity orbit propagation, a much greater amount of ancillary information regarding spacecraft properties and dynamical models should be provided. Higher fidelity orbit propagations may be useful in special studies such as orbit conjunction studies.

Spacecraft orbit determination is a stochastic estimation problem; observations are inherently uncertain, and not all of the phenomena that influence satellite motion are clearly discernible. State vectors and Keplerian elements with their respective covariances are best propagated with models that include the same forces and phenomena that were used for determining the orbit. Including this information in an OPM or OMM allows exchange partners to compare the results of their respective orbit propagations.

With additional context information, the OPM and OMM may be used for assessing mutual physical or electromagnetic interference among Earth-orbiting spacecraft, developing collaborative maneuvers, and propagating the orbits of active satellites, inactive man-made objects, and near-Earth debris fragments. The additional information facilitates dynamic modeling of any user's approach to conservative and non-conservative phenomena.

The primary vehicle for the provision of additional optional ancillary information to be used when propagating an OPM or OMM is the COMMENT mechanism. Alternatively, the 'USER\_DEFINED\_' keyword prefix may be used, though this usage is not encouraged.

## I4 SERVICES RELATED TO THE DIFFERENT ORBIT DATA MESSAGE FORMATS

The different orbit data messages have been distinguished by the self-interpretability of the messages. The different services that can be achieved without special arrangements between users of the CCSDS orbit data messages are listed in table I4.1

### I4.1 SERVICES AVAILABLE WITH ORBIT DATA MESSAGES

Service	Definition	Applicable to OPM?	Applicable to OMM?	Applicable to OEM?	Applicable to OCM?
Absolute Orbit Interpretation	State availability at specific times for use in additional computations (geometry, event detection, etc.).	Y	Y	Y	Y
Relative Orbit Interpretation	Trajectory comparison and differencing for events based on the same time source.	Only at time specified at Epoch	Only at time specified at Epoch	Y	Y

## ANNEX J

**ITEMS FOR AN  
INTERFACE CONTROL  
DOCUMENT (ICD)**

**(INFORMATIVE)**

**J1 STANDARD ICD ITEMS**

In several places in this document there are references to items which should be specified in an ~~Interface Control Document (ICD)~~ICD between participants that supplements an exchange of ephemeris data. The ICD should be jointly produced by both participants in a cross-support involving the transfer of ephemeris data. This annex compiles those recommendations into a single section. Although the Orbit Data Messages described in this document may at times be used in situations in which participants have not negotiated ~~interface control documents (ICD)~~, ICDs, they should be developed and negotiated whenever possible based on the content specified in this Recommended Standard ~~should be developed and negotiated whenever possible.~~<sup>1,2</sup>

Item	Section
1) Definition of orbit accuracy requirements pertaining to any particular ODM.	1.2
2) Method of physically exchanging ODMs (transmission).	1.2, 3.1, 4.1, 5.1, 6.1
3) Whether the ASCII format of the ODM will be KVN or XML.	1.1
4) OPM, OMM, OEM <sub>1</sub> and/or OCM file-naming conventions.	3.1, 4.1, 5.1, 6.1
5) Situations where the <u>OBJECT_ID (or in the OCM, the OBJECT DESIGNATOR)</u> is not published in the UN OOSA index (reference [2]).	3.2.3, 4.2.3, 5.2.3, 6.2.3
6) Detailed description of any user defined parameters used.	3.2.4, 4.2.4, 6.2. <del>4</del> <u>11</u>
7) <del>If floating point numbers in extended single or extended double precision are to be used, then discussion of implementation specific attributes is required in an ICD between exchange partners.</del> <u>ORB_AVERAGING</u>	<del>7.5.5</del> <u>6.2.4 Table 6-4</u>

<sup>1</sup> EDITOR'S COMMENT: ~~The greater the amount of material which must be specified via ICD, the lesser the utility/benefit of the ODM (custom programming may be required to tailor software for each ICD).~~

<sup>2</sup> EDITOR'S COMMENT: The greater the amount of material which must be specified via ICD, the lesser the utility/benefit of the ODM (custom programming may be required to tailor software for each ICD).

Item	Section
<u>8) OD_CONFIDENCE</u>	<u>6.2.10</u>
<u>9) OCM Max line length</u>	<u>7.3.3</u>
<u>8)10) Specific OPM, OMM OEM, and/or OCM version numbers that will be exchanged.</u>	7.8.1
<u>9)11) Specific information security interoperability provisions that apply between agencies.</u>	Annex <u>NL</u>
<u>10)12) Exceptions for Timing System, Reference Frame, Orbital Element, and Covariance-Related keywords that are not drawn from ANNEX B (and the SANA registry, [<del>Annex B, reference B-4</del>]reference [10 – 18]) and when ORB_TYPE (6.2.4), COV_TYPE (6.2.6) and STM_TYPE (6.2.7) are = ICD</u>	Annex B
<u>11)13) Interpretation of TIME_SYSTEM specified as SCLK, if to be exchanged, and how to transform them to a standardized time system. <del>The ICD should specify that in using the timing format rules specified in 7.5.10, elapsed days are to be used relative time, with year starting at zero.</del></u>	<del>Annex B</del> <u>7.5.10 (provided that SCLK will be transformed to a standardized time system)</u>
<u>14) <del>The ICD should specify that in using the timing format rules, elapsed days are to be used as relative time, with year starting at zero.</del></u>	<u>7.5.4</u>

## ANNEX K

**CHANGES IN ODM  
VERSION 3****(INFORMATIVE)**

This annex lists the differences between ODM 2.0 and ODM 3.0. The differences are divided into those which affect the content of one or more of the orbit data messages, and those which only affect the document.

Note that changes to previous versions of the ODM can be found in CCSDS Silver Book CCSDS 502.0-B-2-S, published November 2009.

**K1 CHANGES IN THE MESSAGES**

1. The Orbit Comprehensive Message (OCM) was added to provide better support for ISO Technical Committee 20, Subcommittee 14 objectives (see section 4).

~~2.~~

2. MESSAGE\_ID was added to the OPM, OMM, and OEM to provide better satisfaction of requirement P10 (identification and annotation of messages).

**K2 CHANGES IN THE DOCUMENT**

1. A new CCSDS repository for normative keyword values for navigation messages has been created at the SANA Registry ~~of Organizations~~, accessible on the Internet at: [https://sanaregistry.org/r/organizationshttps://.../r/navigation\\_standard\\_normative\\_annexes](https://sanaregistry.org/r/organizationshttps://.../r/navigation_standard_normative_annexes). See Annex B for details on the affected keywords and links to the content. This content replaces non-normative references to the Navigation Green Book (reference [M-1]). The CCSDS documents are not allowed to make normative references to non-normative documents.
2. Several annexes were added. Some are required by CCSDS rule changes, and some are for the provision of supplementary material.
3. Examples for OPM, OMM, and OEM that formerly appeared in Sections 3, 4, and 5 respectively have been moved to Informative Annexes.
4. The "Checklist ICD" that was added in ODM Version 2 has been removed. It is replaced by the material that can be specified in the Orbit Comprehensive Message.

## ANNEX L

**SECURITY, SANA, AND PATENT CONSIDERATIONS****5.L1 SECURITY CONSIDERATIONS****L1.1 ANALYSIS OF SECURITY CONSIDERATIONS**

This Section presents the results of an analysis of security considerations applied to the technologies specified in this Recommended Standard.

**L1.2 CONSEQUENCES OF NOT APPLYING SECURITY TO THE TECHNOLOGY**

The consequences of not applying security to the systems and networks on which this Recommended Standard is implemented could include potential loss, corruption, and theft of data. Because these messages are used in preparing pointing and frequency predicts used during spacecraft commanding, and may also be used in collision avoidance analyses, the consequences of not applying security to the systems and networks on which this Recommended Standard is implemented could include compromise or loss of the mission if malicious tampering of a particularly severe nature occurs.

**L1.3 POTENTIAL THREATS AND ATTACK SCENARIOS**

Potential threats or attack scenarios include, but are not limited to, (a) unauthorized access to the programs/processes that generate and interpret the messages, (b) unauthorized access to the messages during transmission between exchange partners and (c) modification of the messages between partners. Protection from unauthorized access during transmission is especially important if the mission utilizes open ground networks, such as the Internet, to provide ground-station connectivity for the exchange of data formatted in compliance with this Recommended Standard. It is strongly recommended that potential threats or attack scenarios applicable to the systems and networks on which this Recommended Standard is implemented be addressed by the management of those systems and networks.

**L1.4 DATA PRIVACY**

Privacy of data formatted in compliance with the specifications of this Recommended Standard should be assured by the systems and networks on which this Recommended Standard is implemented.

**L1.5 DATA INTEGRITY**

Integrity of data formatted in compliance with the specifications of this Recommended Standard should be assured by the systems and networks on which this Recommended Standard is implemented.

**L1.6 AUTHENTICATION OF COMMUNICATING ENTITIES**

Authentication of communicating entities involved in the transport of data which complies with the specifications of this Recommended Standard should be provided by the systems and networks on which this Recommended Standard is implemented.

**L1.7 DATA TRANSFER BETWEEN COMMUNICATING ENTITIES**

The transfer of data formatted in compliance with this Recommended Standard between communicating entities should be accomplished via secure mechanisms approved by the Information Technology Security functionaries of exchange participants.

**L1.8 CONTROL OF ACCESS TO RESOURCES**

Control of access to resources should be managed by the systems upon which originator formatting and recipient processing are performed.

**L1.9 AUDITING OF RESOURCE USAGE**

Auditing of resource usage should be handled by the management of systems and networks on which this Recommended Standard is implemented.

**L1.10 UNAUTHORIZED ACCESS**

Unauthorized access to the programs/processes that generate and interpret the messages should be prohibited in order to minimize potential threats and attack scenarios.

**L1.11 DATA SECURITY IMPLEMENTATION SPECIFICS**

Specific information-security interoperability provisions that may apply between agencies and other independent users involved in an exchange of data formatted in compliance with this Recommended Standard could be specified in an ICD.

**L2 SANA CONSIDERATIONS**

The following ODM-related items ~~items~~ have been registered with the SANA Operator.

- The ODM XML schema (see Section 8).

The following normative ODM elements shall be selected from the SANA registry: [\(see Annex B\)](#):

- ODM Message ORIGINATORS;

- Spacecraft identifiers;
- Reference Frame Center and Third-Body Perturbations;
- Time Systems;
- Reference Frames (inertial, quasi-inertial, orbit-relative, spacecraft & attitude frames);
- Orbital element set and covariance column definitions;

The registration rule for new entries in the SANA registry is the approval of new requests by the CCSDS Area or Working Group responsible for the maintenance of the ODM at the time of the request. New requests for this registry should be sent to SANA (<mailto:info@sanaregistry.org>).

### **L3 PATENT CONSIDERATIONS**

The recommendations of this document have no patent issues.

## ANNEX M

**INFORMATIVE  
REFERENCES****(INFORMATIVE)**

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- [M-12] Oltrogge, D.L., North, P. and Nicholls, M., “Multi-Phenomenology Observation Network Evaluation Tool (MONET),” AMOS 2015 Space Situational Awareness Conference, Maui, HI, September 2015.
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- [M-14] Hoots, F.R. and France, R.G., “Hybrid Ephemeris Compression Model,” *Astrodynamics Specialist Conference*, AAS-97-690, [http://www.space-flight.org/AAS\\_meetings/1997\\_astro/abstracts/97-690.html](http://www.space-flight.org/AAS_meetings/1997_astro/abstracts/97-690.html).
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